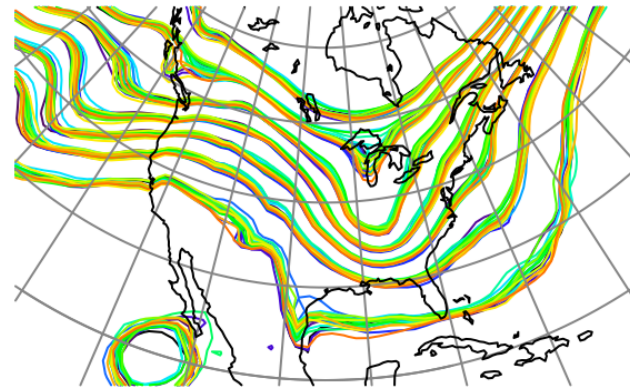


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DART Tutorial Section 16: Diagnostic Output



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UCAR | Atmospheric Research

DART Diagnostic Output Categories:

- State-Space:
Values of models state vector.
Output using netCDF format.
- Observation-Space:
Values of the observations.
DART-specific *obs_sequence* format for now.
- Regression confidence factor:
Values for state vector / observation pairs.
Output as flat ASCII (soon to be netCDF).
- Program diagnostic output:
Identification for source code version and namelist values.
Error, warning, message output from modules.

State-Space Diagnostic Files:

Available in netCDF (a common data format)

<http://www.unidata.ucar.edu/software/netcdf>

1. Prior state (Prior_Diag.nc) : state before assimilation.
2. Posterior state (Posterior_Diag.nc) : state after assimilation.
3. Truth (True_State.nc) : truth for OSSEs.

Contents of prior and posterior controlled by *filter_nml*:

1. `output_state_ens_mean = .true.` (include ensemble mean);
2. `output_state_ens_spread = .true.` (include ensemble spread);
3. `num_output_state_members = ##` (include this many of the individual ensemble members)
4. `output_interval = N` (only output every N^{th} assimilation time)

Note: `output_interval` for `True_State.nc` is in the *perfect_model_obs_nml* namelist.

DART State-Space Diagnostic functions

See the DART website section titled: “Configuring Matlab to work with DART”
www.image.ucar.edu/DAReS/DART/DART_Documentation.php#configure_matlab

ALL the DART Matlab state-space diagnostic functions are in `<dart>/matlab`
This **must** be in your *matlabpath*.

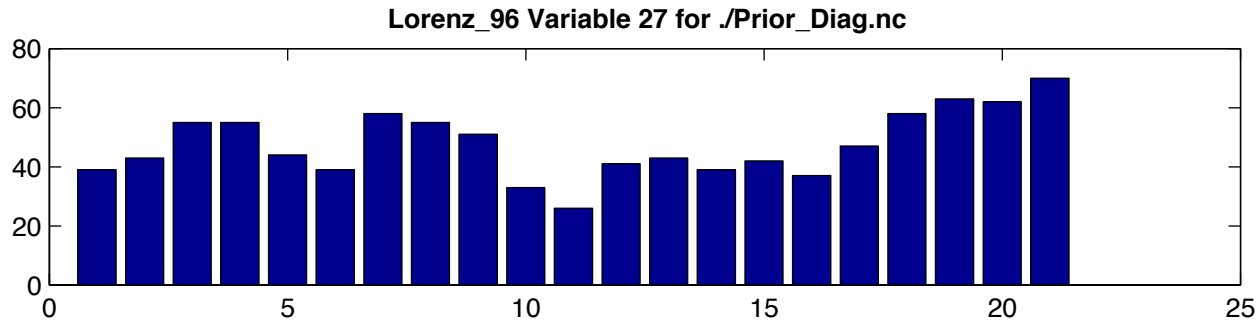
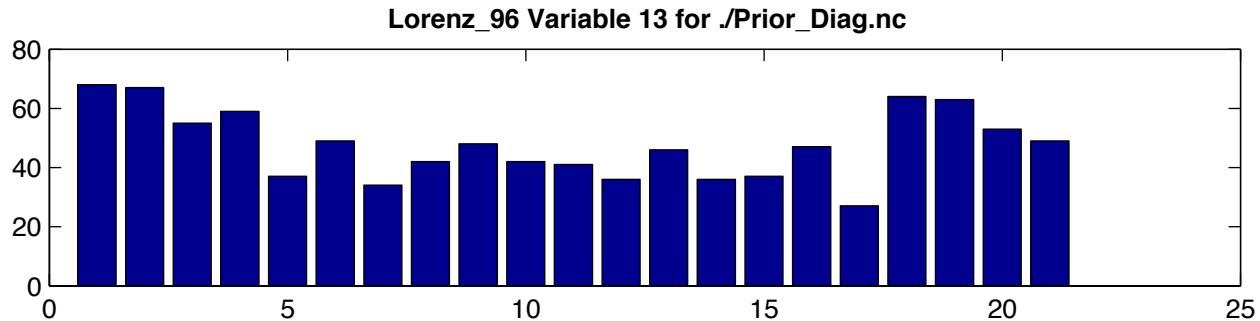
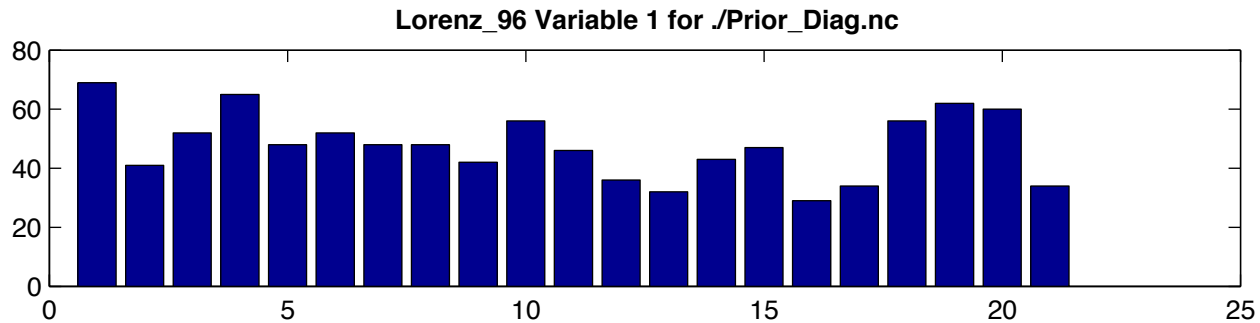
Only focus on the functions/scripts that start with *plot_*

- `plot_bins.m`
- `plot_correl.m`
- `plot_ens_err_spread.m`
- `plot_ens_mean_time_series.m`
- `plot_ens_time_series.m`
- `plot_phase_space.m`
- `plot_reg_factor.m`
- `plot_sawtooth.m`
- `plot_smoother_err.m`
- `plot_total_err.m`
- `plot_var_var_correl.m`
- ...

Some, but not all, described here.
All functions have a ‘help’ section
available in the standard Matlab way.

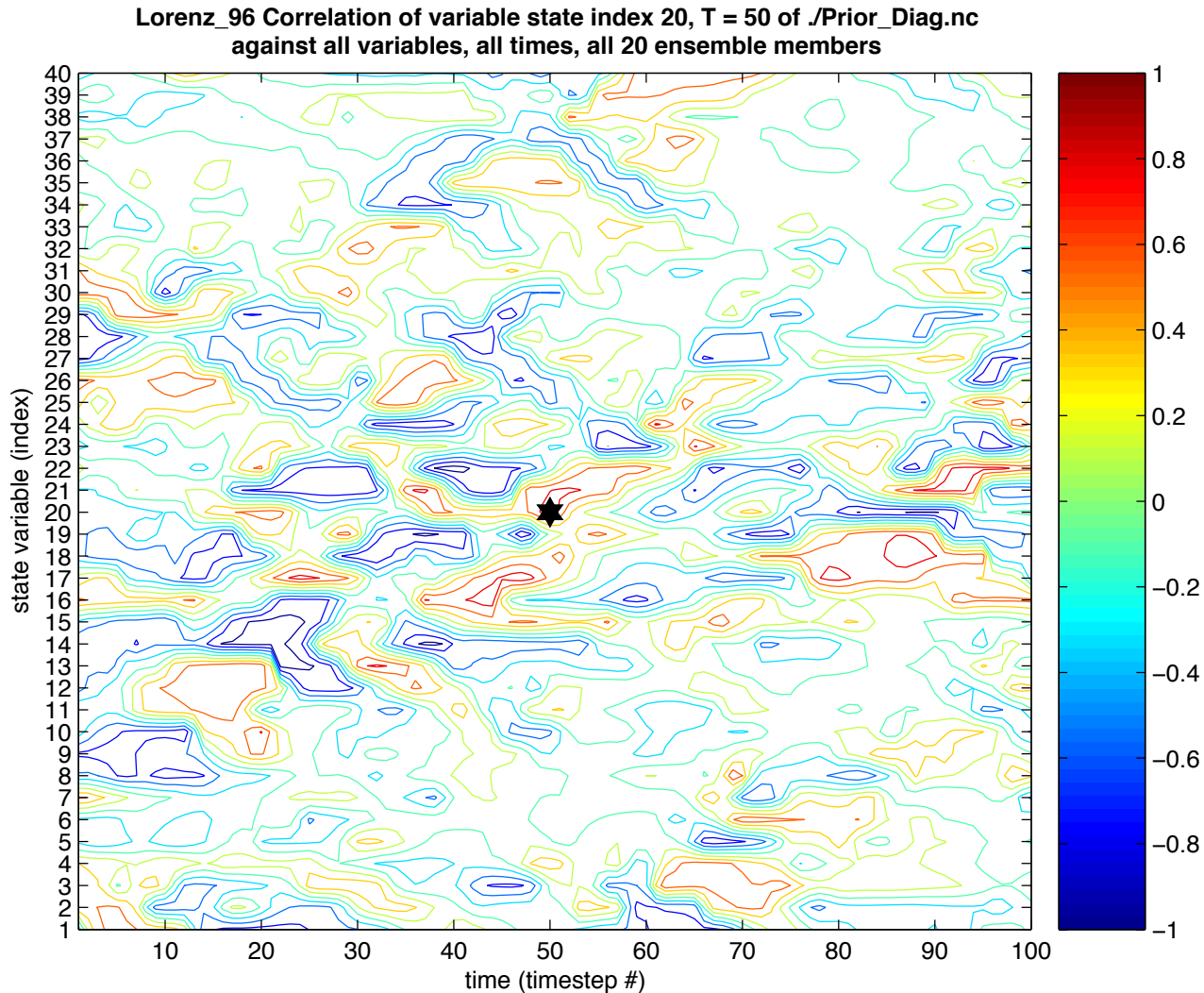
Viewing the State-Space netCDF files:

1. Standard DART matlab diagnostics:
 - a. `plot_bins`: rank histograms,



Viewing the State-Space netCDF files:

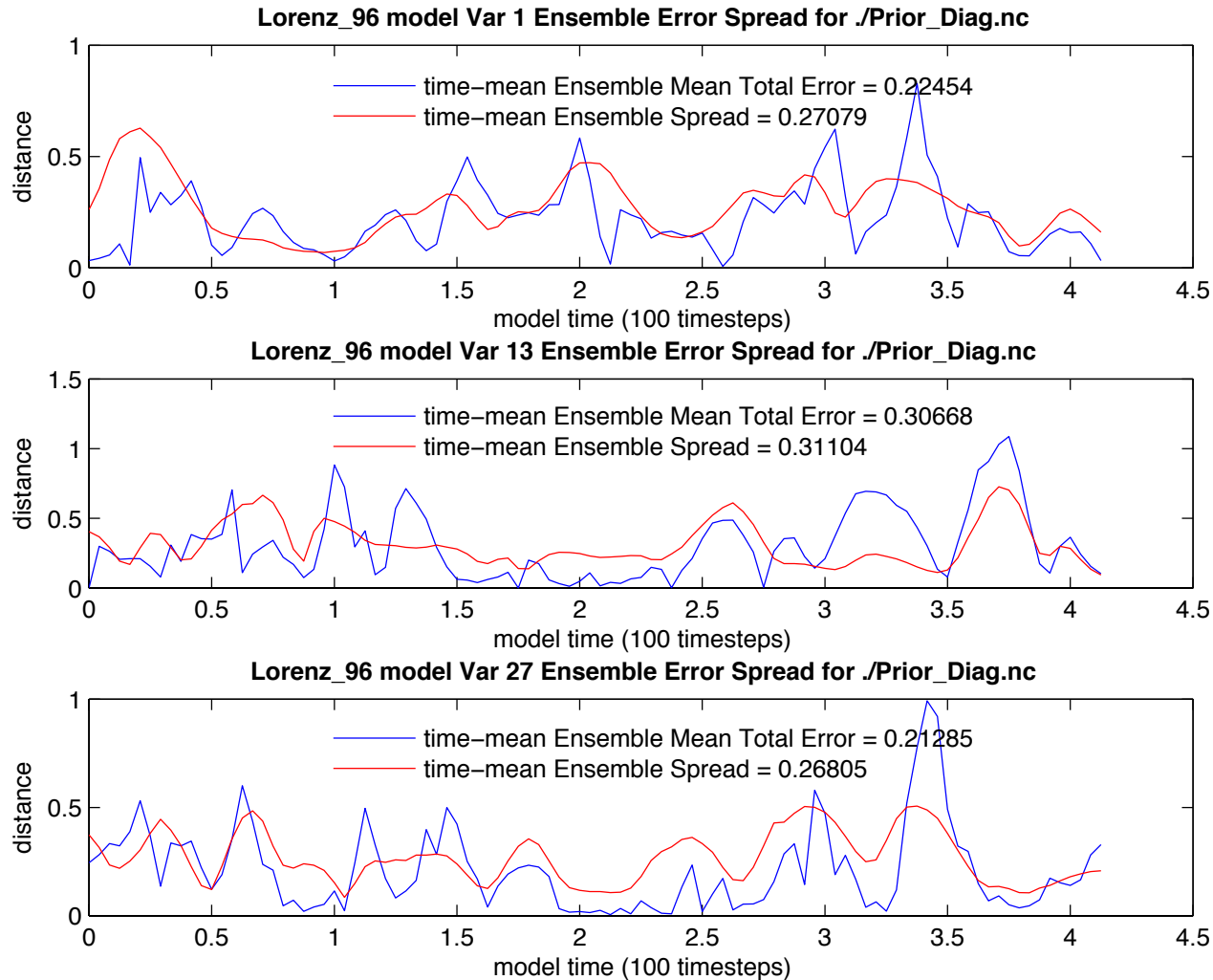
1. Standard DART matlab diagnostics:
 - b. `plot_correl`: correlation $x(t)$ with all other state vars at all times,



Viewing the State-Space netCDF files:

1. Standard DART matlab diagnostics:

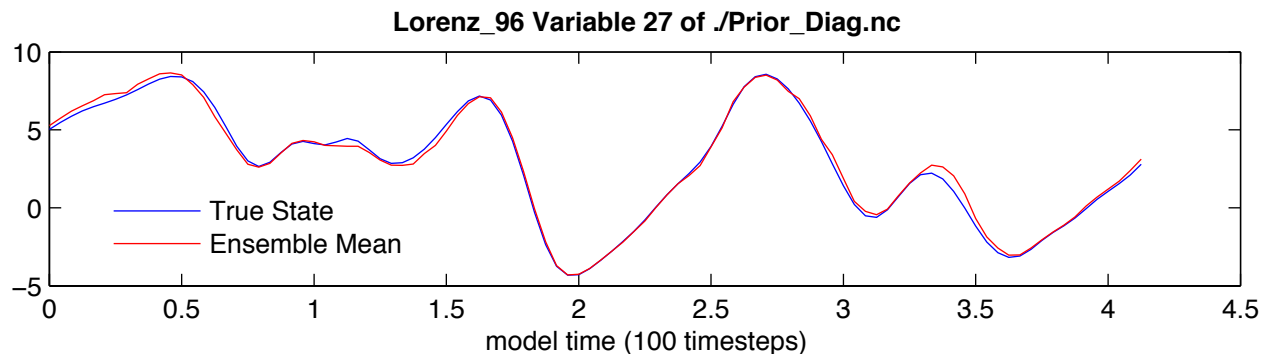
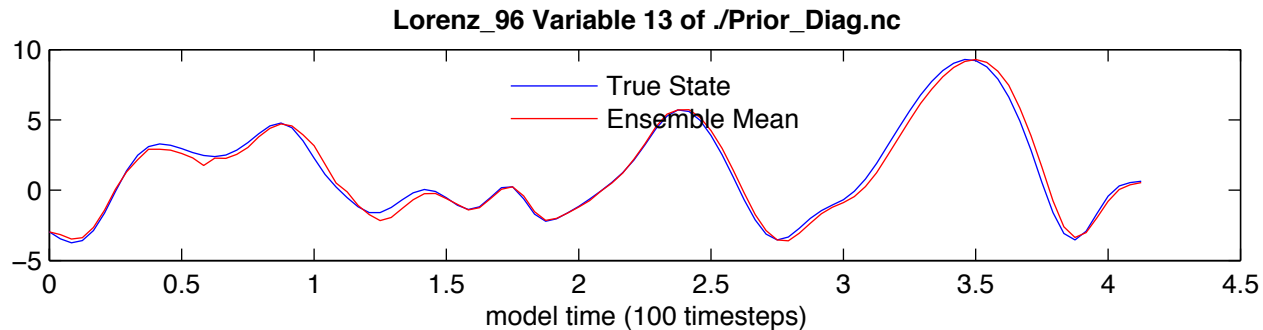
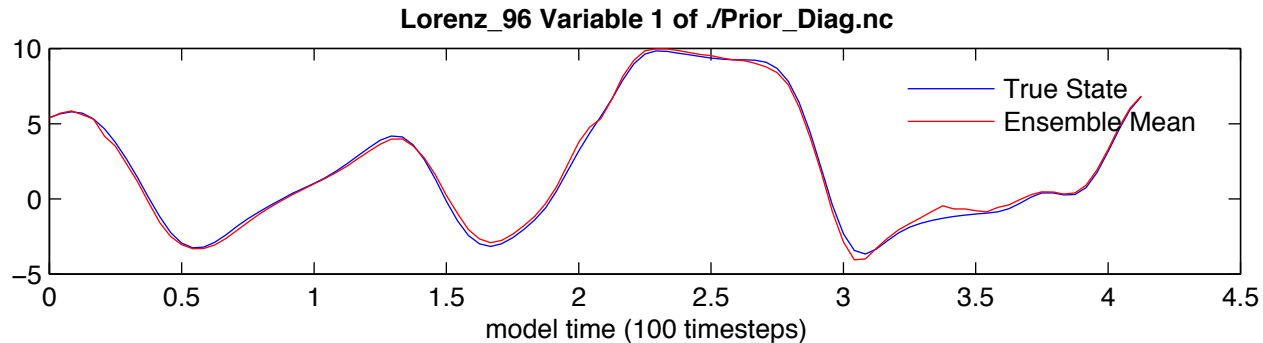
c. `plot_ens_err_spread`: rms error and spread,



Viewing the State-Space netCDF files:

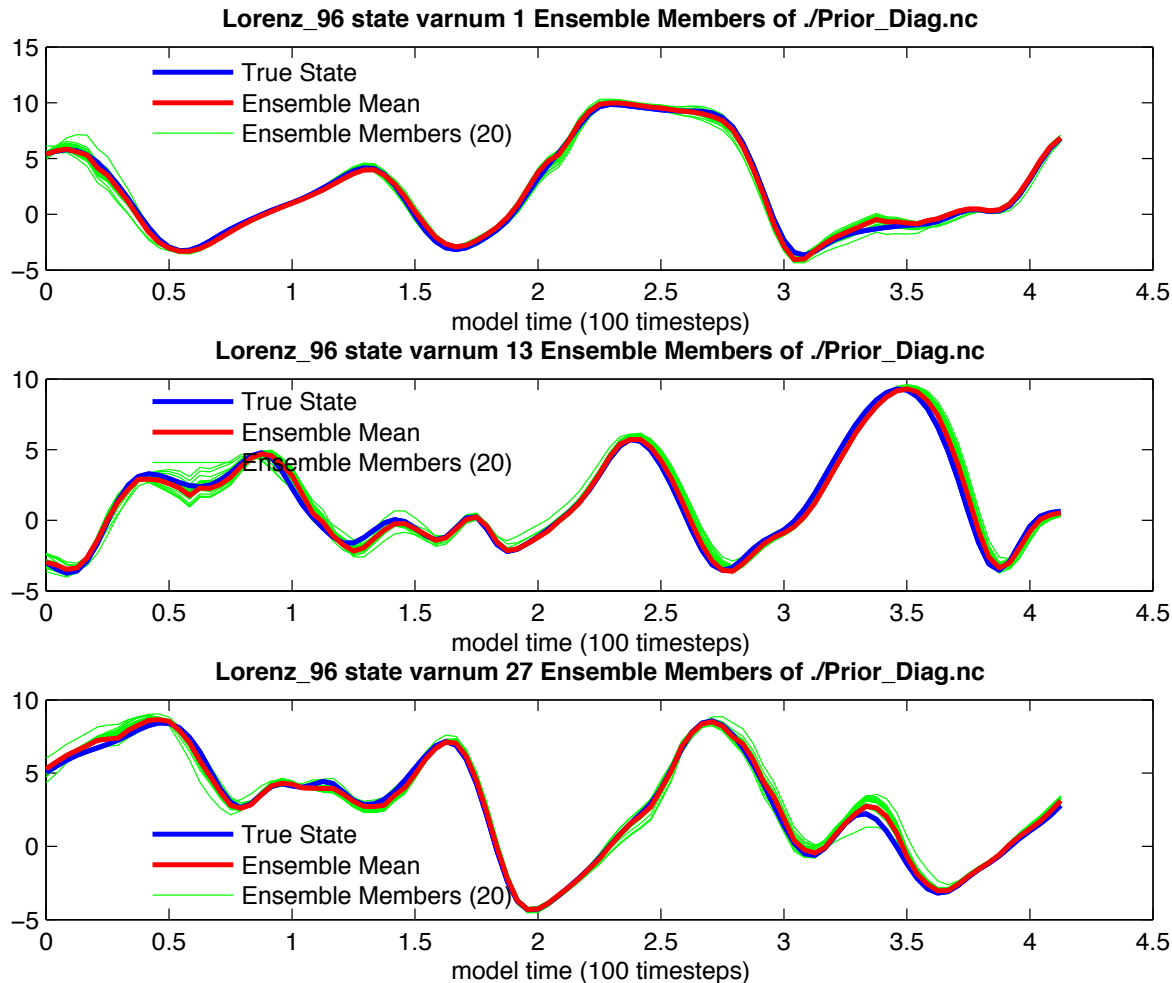
1. Standard DART matlab diagnostics:

d. `plot_ens_mean_time_series`: just like the name says,



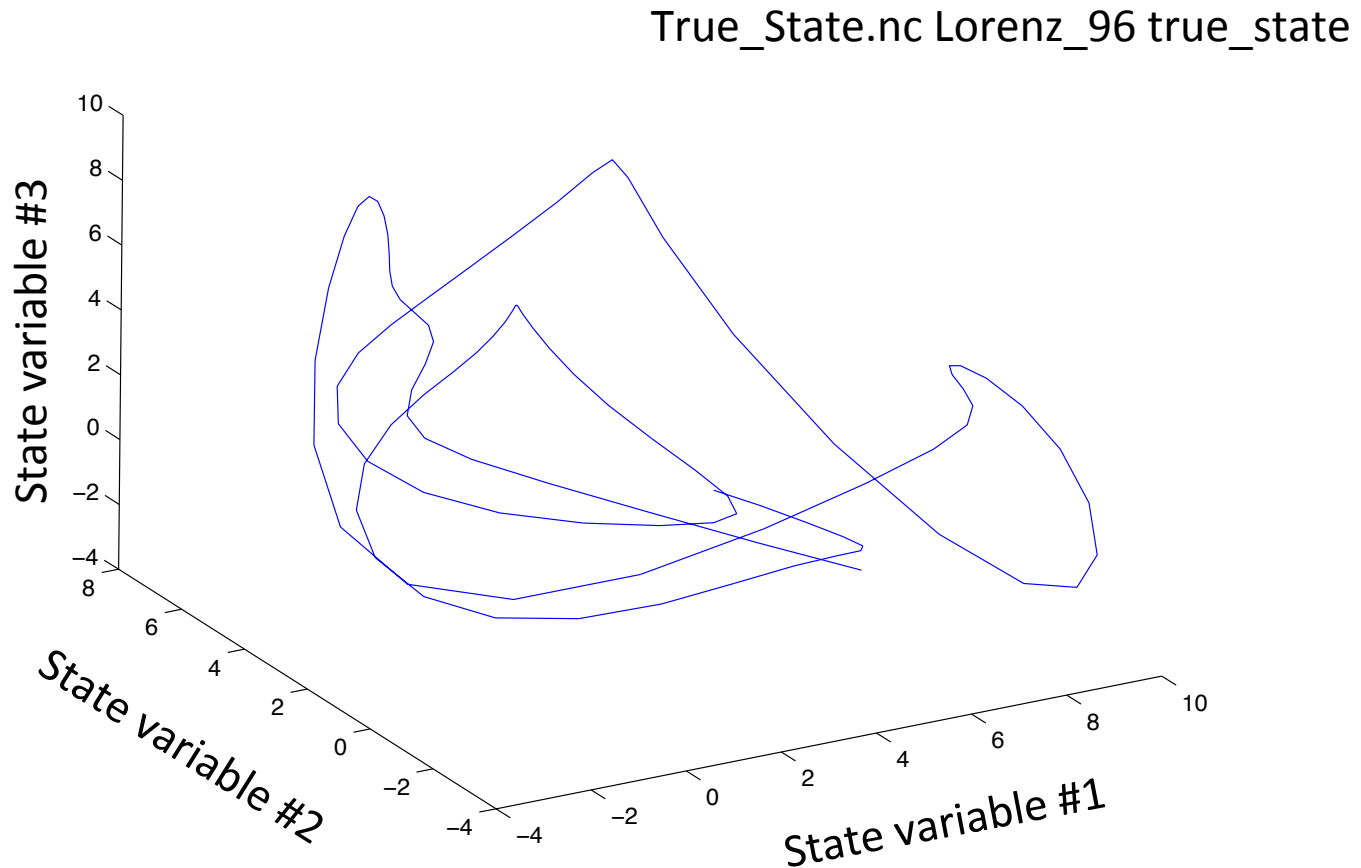
Viewing the State-Space netCDF files:

1. Standard DART matlab diagnostics:
 - e. `plot_ens_time_series`: plots the ensemble (as available from `num_output_state_members`),



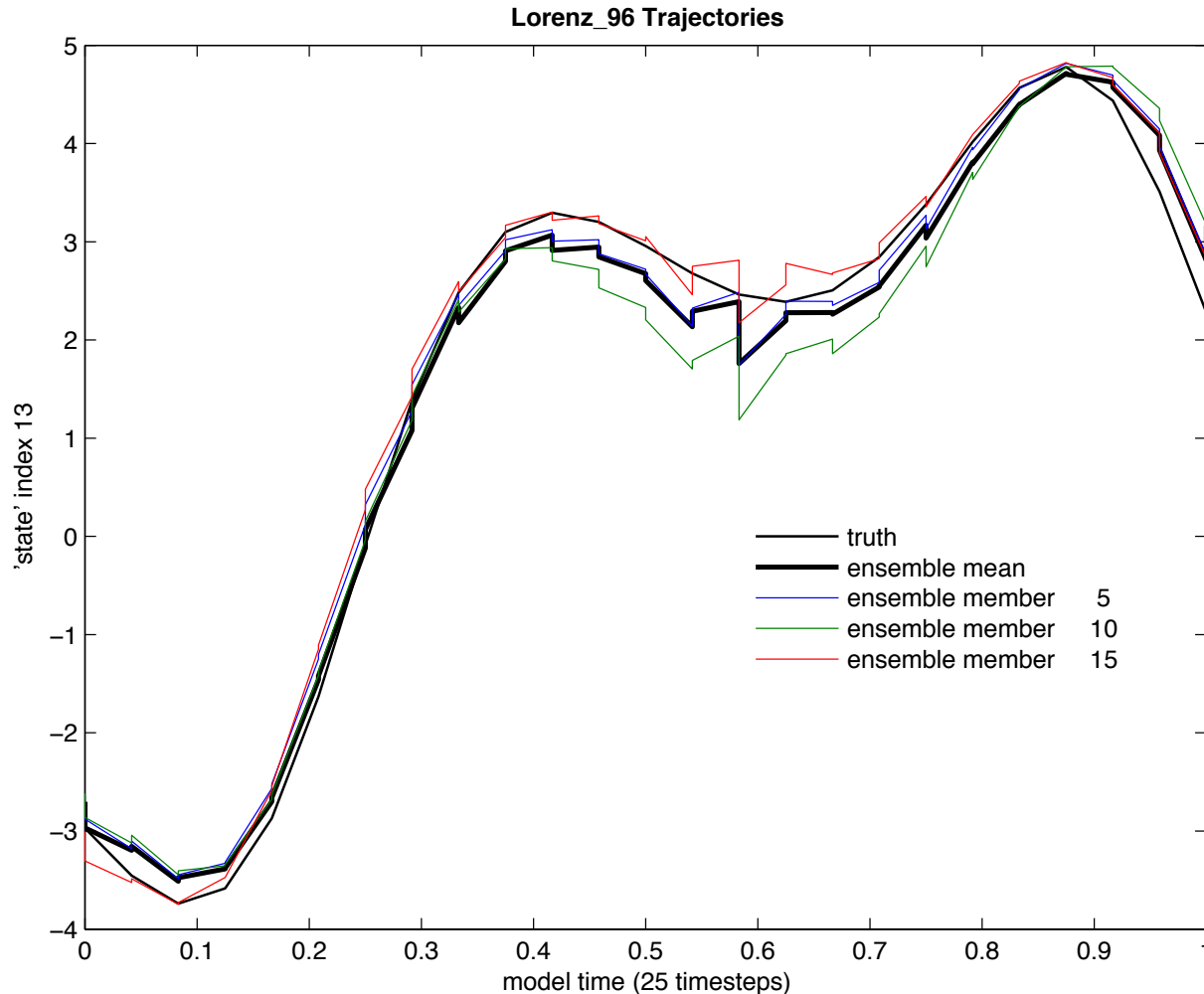
Viewing the State-Space netCDF files:

1. Standard DART matlab diagnostics:
 - f. `plot_phase_space`: 3D phase space time evolution.



Viewing the State-Space netCDF files:

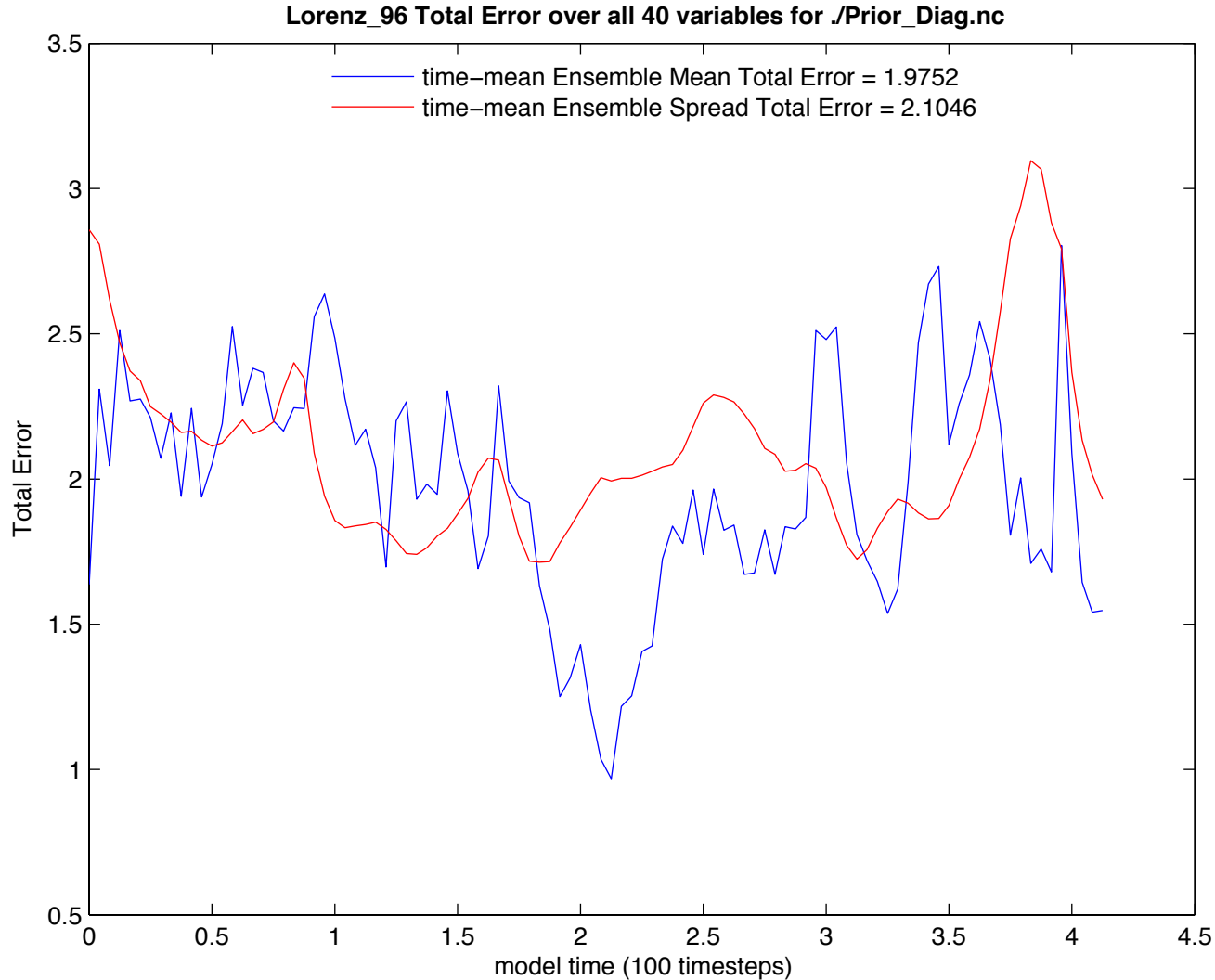
1. Standard DART matlab diagnostics:
 - g. `plot_sawtooth`: truth, prior and posterior time series.



Viewing the State-Space netCDF files:

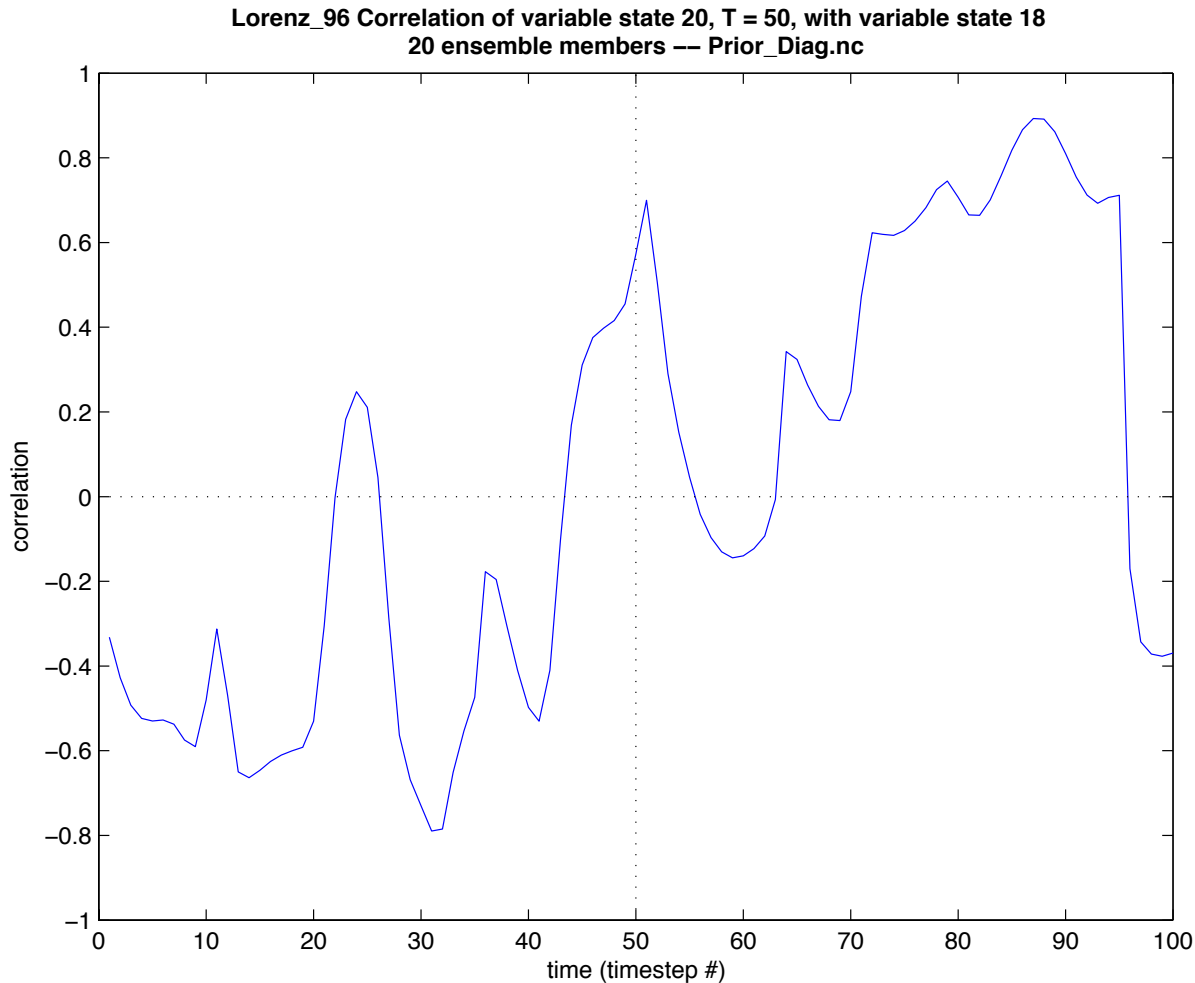
1. Standard DART matlab diagnostics:

h. `plot_total_err`: total error for different fields,



Viewing the State-Space netCDF files:

1. Standard DART matlab diagnostics:
 - i. `plot_var_var_correl`: $x(t)$ correlation to single variable, all times.

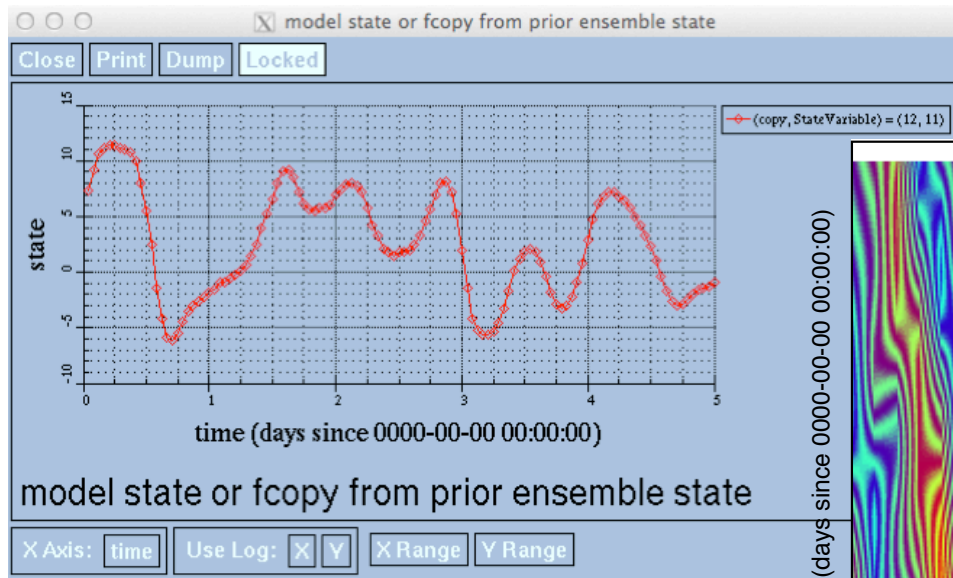


Viewing the State-Space netCDF files:

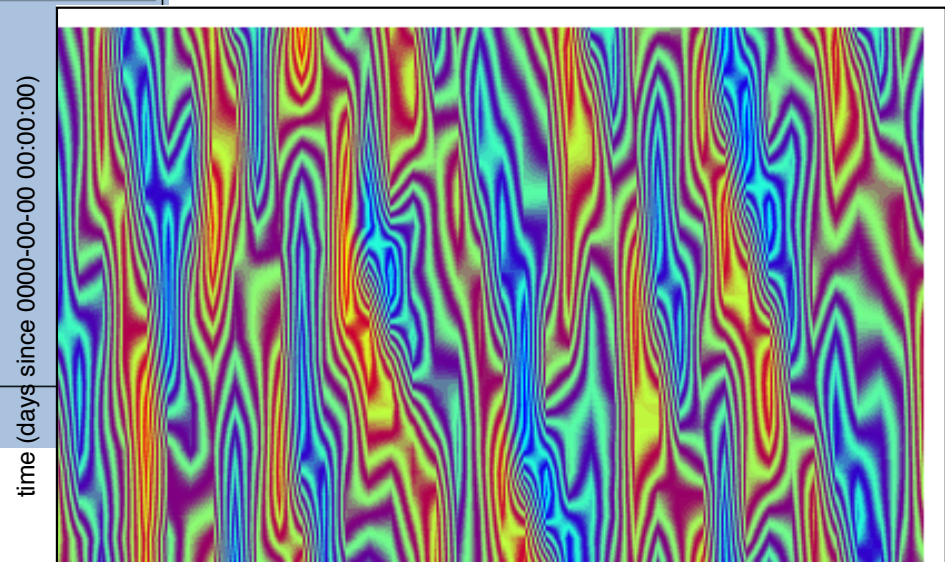
2. Ncview: a quick and surprisingly useful netCDF viewer.

http://meteora.ucsd.edu/~pierce/ncview_home_page.html

Displays spatial slices, animations, time series ...



model state or fcopy



State Variable ID (indexical)

prior ensemble state

Range of model state or fcopy: -6.18328 to 11.6954 (null)

Range of State Variable ID: 1 to 40 indexical

Range of time: 0 to 1 days since 0000-00-00 00:00:00

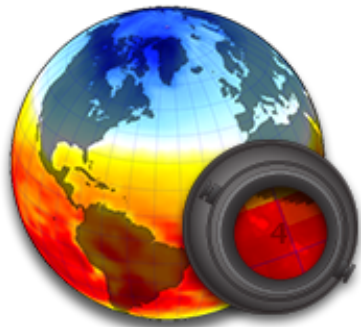
Current ensemble member or copy: 1 nondimensional

Frame 1 in File Prior_Diag.nc

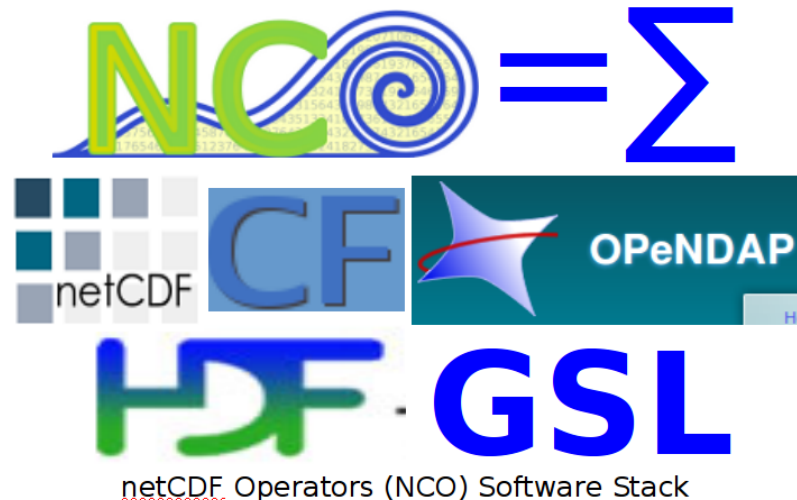
jla Sun Jun 5 13:41:44 2005

Viewing the State-Space netCDF files:

3. Many other graphical/analysis programs can read netCDF.
(Note that we use *udunits* metadata convention.)
4. netCDF Operator (NCO) tools allow operations on netCDF files:
(<http://nco.sourceforge.net>)
Selecting hyperslices of fields,
Differencing netCDF file,
Averaging, etc.



NASA GISS: Panoply



Observation-space files:

Quick recap of 'standard' observation sequence file names
(all names are actually specified in namelists):

- `obs_seq.in` input to *perfect_model_obs*
- `obs_seq.out` **output** from *perfect_model_obs*, also **input** to *filter*
- `obs_seq.final` output from *filter*

Observation sequence file output by *filter* has prior, posterior, observed value
(and truth for OSSEs). For an overview, check out the DART webpage section:
www.image.ucar.edu/DAReS/DART/DART_Observations.php#obs_seq_overview

Contents of *obs_seq.final* controlled by `filter_nml`:

1. `obs_sequence_in_name = 'obs_seq.out'`
Name of input observation sequence file.
2. `obs_sequence_out_name = 'obs_seq.final'`
Name of output observation sequence file.
3. `num_output_obs_members = ##`
Output this many individual ensemble estimates.

Observation-space diagnostics:

The observation sequence file is not in a particularly user-friendly format. To aid in the evaluation and interpretation, a program named ***obs_diag*** must be run to produce a netCDF file with results that can be plotted in a manner of your choosing. DART has Matlab functions/scripts that create high-quality graphics.

See tutorial section 18 for full coverage of viewing / diagnosing obs sequences.

Also covered in:

http://www.image.ucar.edu/DAReS/DART/DART_Documentation.php#obs_diagnostics

Here are a few of the Matlab functions available in `<dart>/diagnostics/matlab`

- `plot_rank_histogram.m`
- `plot_evolution.m`
- `plot_rmse_xxx_evolution.m`
- `two_experiments_evolution.m` (works with more than two, actually)
- `plot_profile.m`
- `plot_bias_xxx_profile.m`
- `plot_rmse_xxx_profile.m`
- `two_experiments_profile.m` (works with more than two, actually)

Regression confidence factor output:

Reminder: `reg_factor` α introduced in Tutorial Section 13 – when running the group filter (with more than 1 group!).

Controlled by `reg_factor_nml`:

1. `save_reg_diagnostics = .true.` Should file be output?
2. `reg_diagnostics_file = 'reg_diagnostics'` Name of output file.

File size could be (model size) X (number of obs.) X (number of assim times).
Very big, even for small models (only first 4 obs output default).

Normally, modify code in `reg_factor_mod.f90` to control:

Output is at end of `select_regression = 1` code block.

Format is ASCII:

time in days, time in seconds, `obs_index`, `state_index`, α

Plot with Matlab `plot_reg_factor`.

Program Diagnostic Output:

File *dart_log.out*

All DART executables **append** to this file!

Contains:

- registration information
- Program start time,
- version of code for each module used*
- Namelist values for each module**
- Names of output files,
- Diagnostic output for modules (through `error_handler()`),
- Warnings and fatal errors from DART code.

Fair Warning: This file is **not** cleared by DART. Can get very longggggggg ...
You should feel free to delete/rename it before starting the next experiment.

*Hopefully

**may be in a separate file, depending on *utilities_nml* setting

DART Tutorial Index to Sections

1. Filtering For a One Variable System
2. The DART Directory Tree
3. DART Runtime Control and Documentation
4. How should observations of a state variable impact an unobserved state variable?
Multivariate assimilation.
5. Comprehensive Filtering Theory: Non-Identity Observations and the Joint Phase Space
6. Other Updates for An Observed Variable
7. Some Additional Low-Order Models
8. Dealing with Sampling Error
9. More on Dealing with Error; Inflation
10. Regression and Nonlinear Effects
11. Creating DART Executables
12. Adaptive Inflation
13. Hierarchical Group Filters and Localization
14. Quality control
15. DART Experiments: Control and Design
16. Diagnostic Output
17. **Creating Observation Sequences**
18. **Lost in Phase Space: The Challenge of Not Knowing the Truth**
19. **DART-Compliant Models and Making Models Compliant**
20. **Model Parameter Estimation**
21. **Observation Types and Observing System Design**
22. **Parallel Algorithm Implementation**
23. Location module design (not available)
24. Fixed lag smoother (not available)