Initializing carbon cycle predictions from CLM by assimilating biomass and LAI observations

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Office of This work is funded by DOE Regional and Science Global Climate Modeling DE-SC0016011

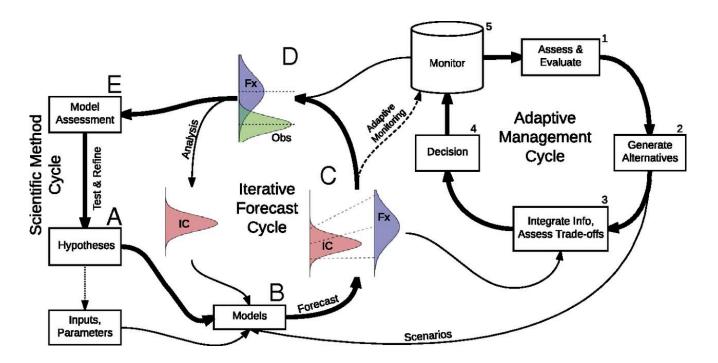


Why forecast the Carbon Cycle?

Iterative near-term ecological forecasting: Needs, opportunities, and challenges

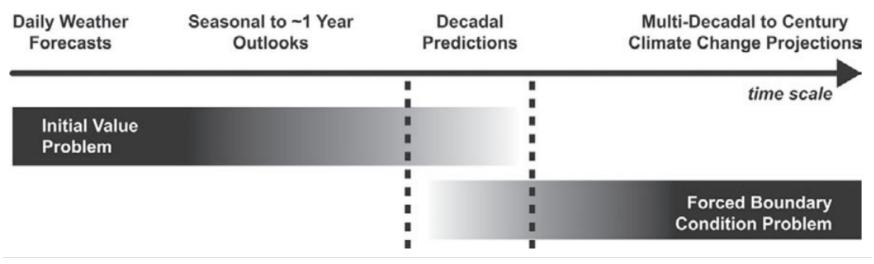
Michael C. Dietze^{a,1}, Andrew Fox^b, Lindsay M. Beck-Johnson^c, Julio L. Betancourt^d, Mevin B. Hooten^{e,f,g}, Catherine S. Jarnevich^h, Timothy H. Keittⁱ, Melissa A. Kenney^j, Christine M. Laney^k, Laurel G. Larsen^l, Henry W. Loescher^{k,m}, Claire K. Lunch^k, Bryan C. Pijanowskiⁿ, James T. Randerson^o, Emily K. Read^p, Andrew T. Tredennick^{q,r}, Rodrigo Vargas^s, Kathleen C. Weathers^t, and Ethan P. White^{u,v,w}

PNAS 2018; published ahead of print January 30, 2018, https://doi.org/10.1073/pnas.1710231115





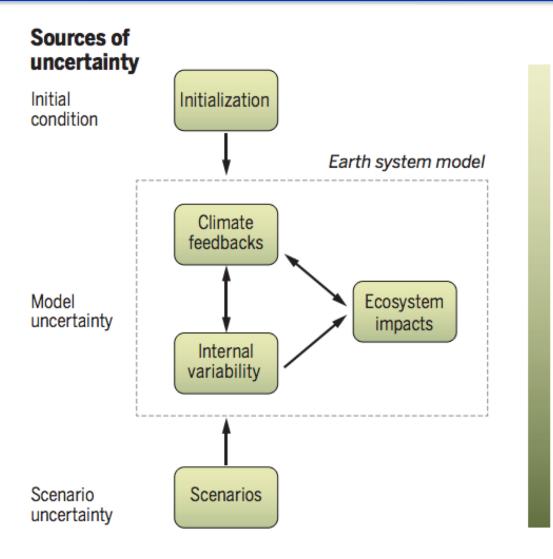
Dominant sources of uncertainty change



(Meehl et al., 2009)



Dominant sources of uncertainty change



Initial value problem

Subseasonal to seasonal forecast (2 weeks – 12 months)

Decadal prediction (1 – 30 years)

Earth system projection (30 – 100+ years) **Boundary value problem**

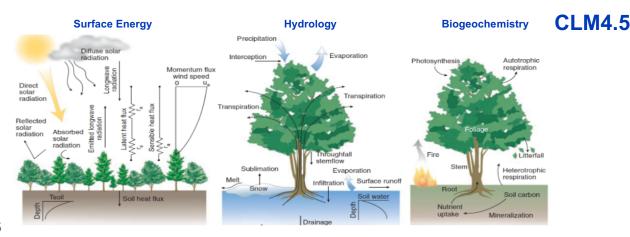
Bonan et al., Science **359**, eaam8328 (2018)

2 February 2018



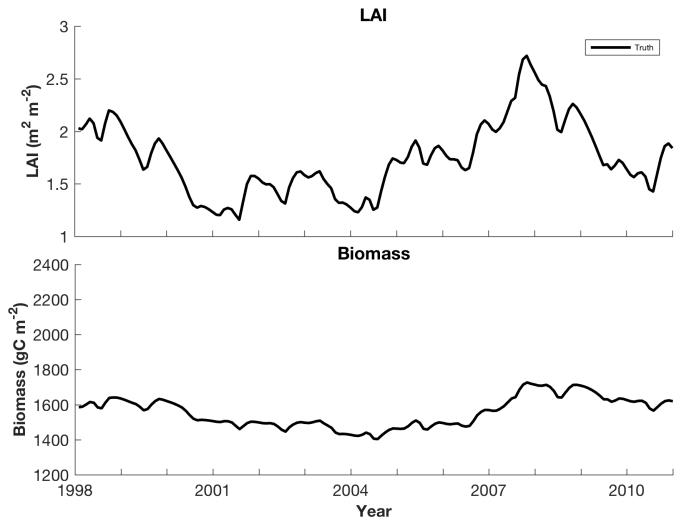
Community Land Model set up

- Multi-instance CLM4.5 BGC set up for a location in central New Mexico, USA
- PFT fractions of Bare, C4 grass, and Needleleaf Evergreen – Temperate
- Spun up by cycling 13 years of ensemble atmospheric reanalysis data



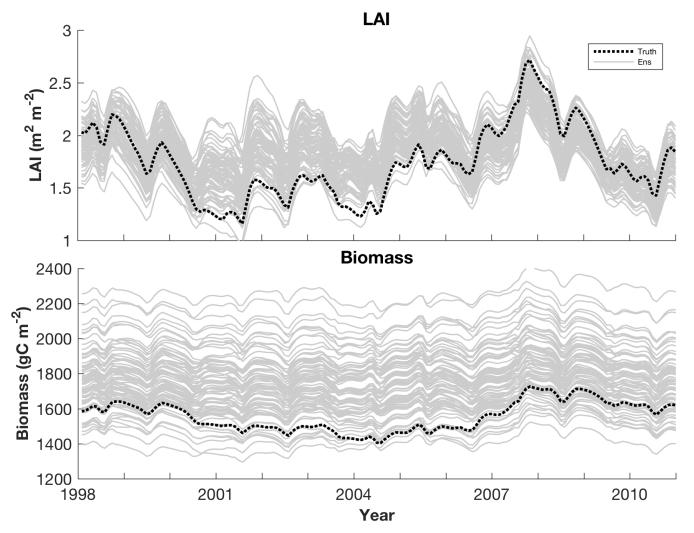


LAI and Biomass – single instance



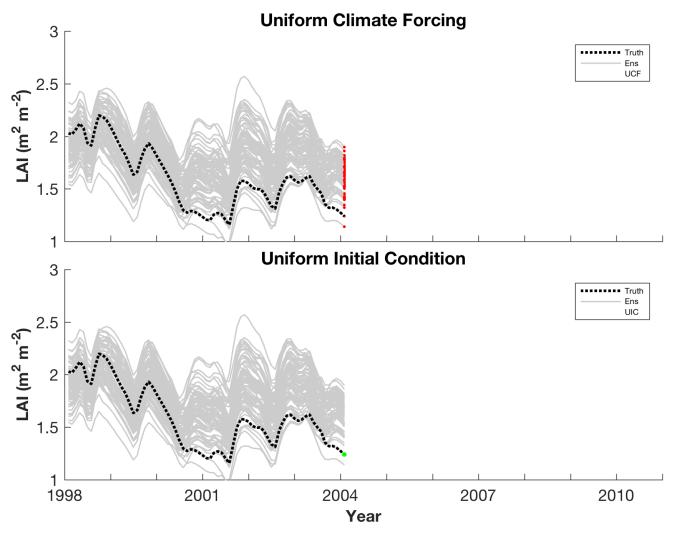


LAI and Biomass – multi-instance



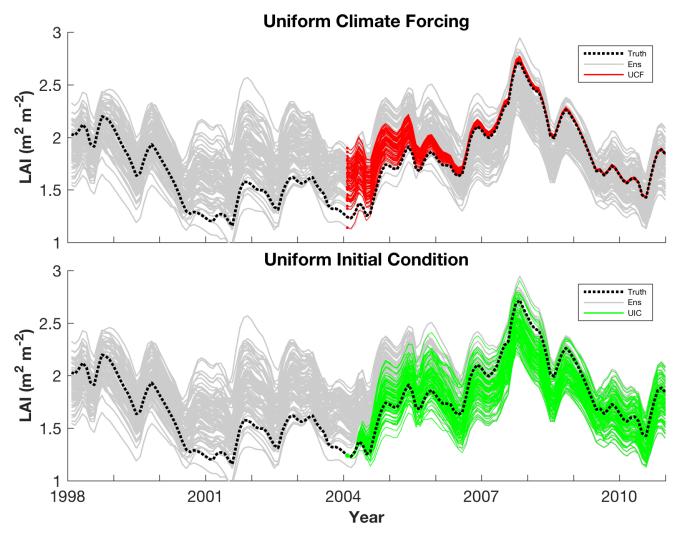


Uniform Climate Forcing v. Initial Conditions



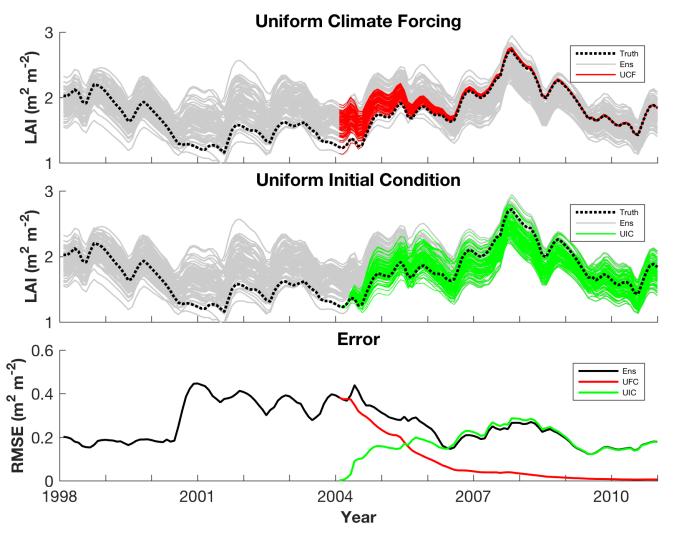


Uniform Climate Forcing v. Initial Conditions



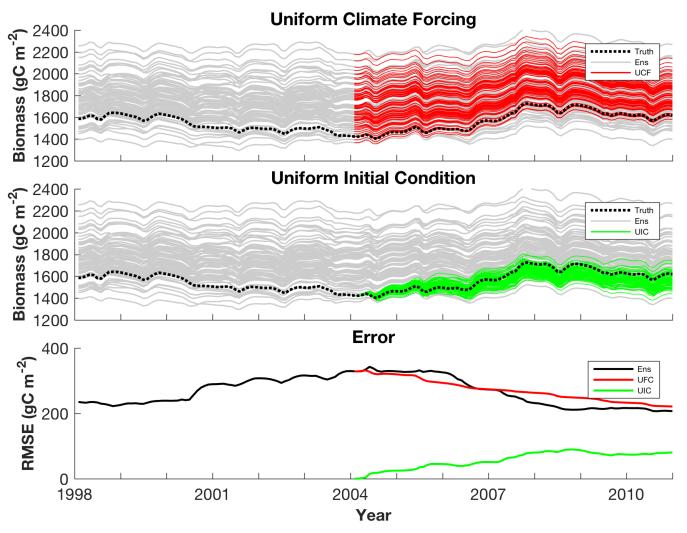


LAI – Error is reduced for 2.5 years





Biomass – Error is reduced for 7+ years





LAI and Biomass – observations

Monthly, 0.5° Aggregated MODIS LAI Observations

JOURNAL OF GEOPHYSICAL RESEARCH, VOL. 112, G01023, doi:10.1029/2006JG000168, 2007

Representing a new MODIS consistent land surface in the Community Land Model (CLM 3.0)

Peter J. Lawrence¹ and Thomas N. Chase¹

Received 27 January 2006; revised 3 October 2006; accepted 14 November 2006; published 17 March 2007.

Annual, 0.25° Vegetation Optical Depth Biomass Observations

nature climate change

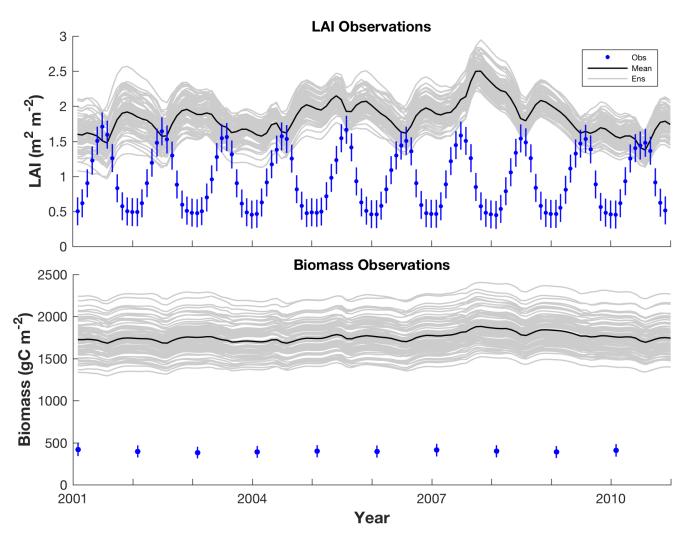
PUBLISHED ONLINE: 30 MARCH 2015 | DOI: 10.1038/NCLIMATE2581

Recent reversal in loss of global terrestrial biomass

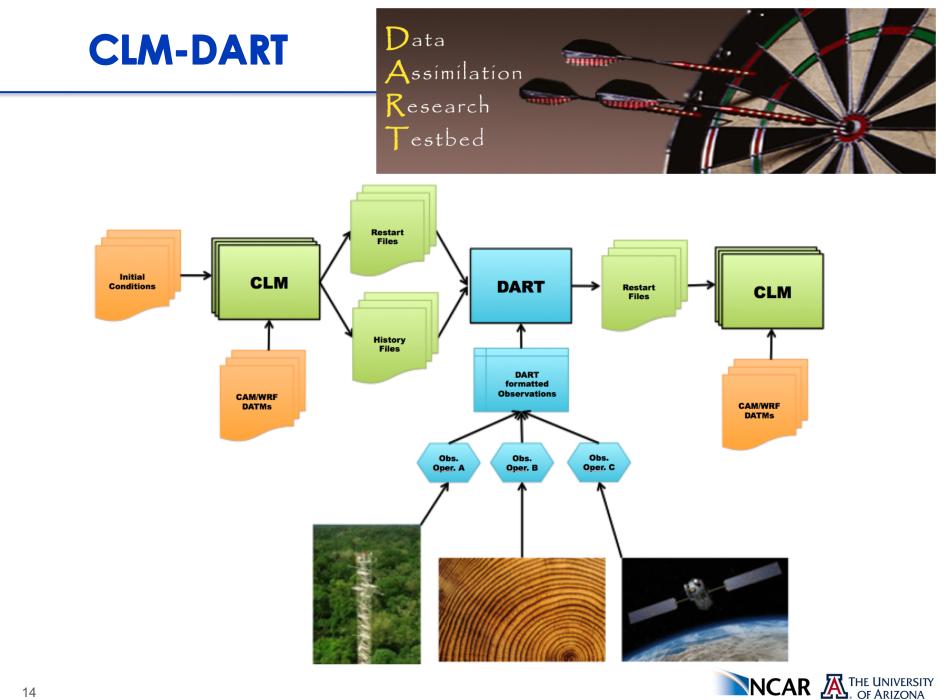
Yi Y. Liu^{1,2*}, Albert I. J. M. van Dijk^{3,4}, Richard A. M. de Jeu⁵, Josep G. Canadell⁶, Matthew F. McCabe⁷, Jason P. Evans¹ and Guojie Wang⁸



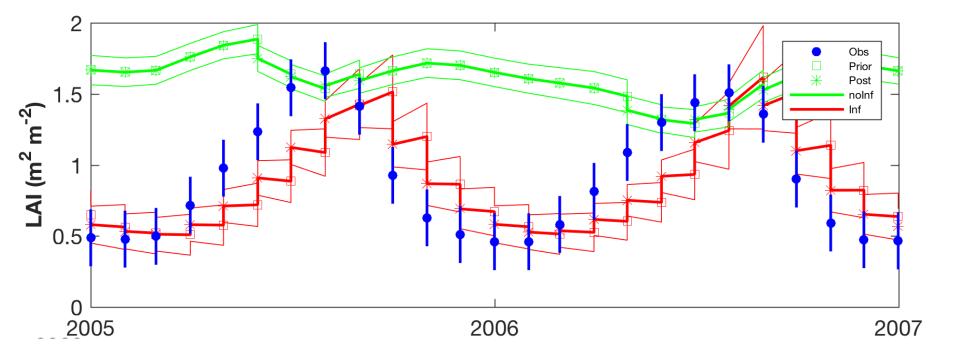
LAI and Biomass – observations





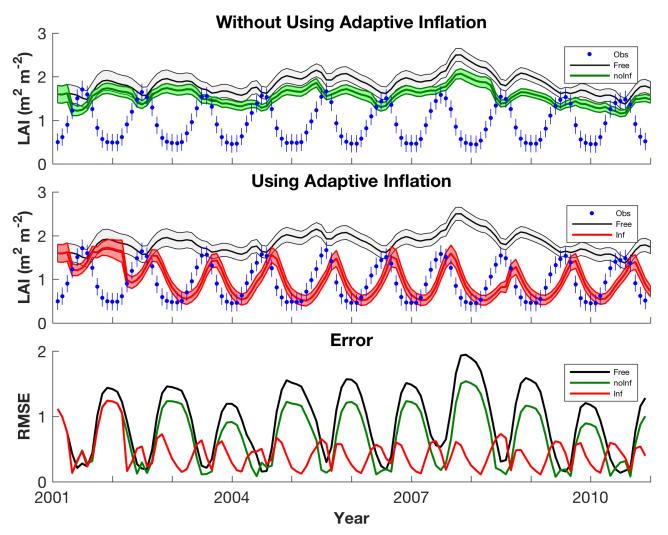


Ensemble forecast is updated by observations



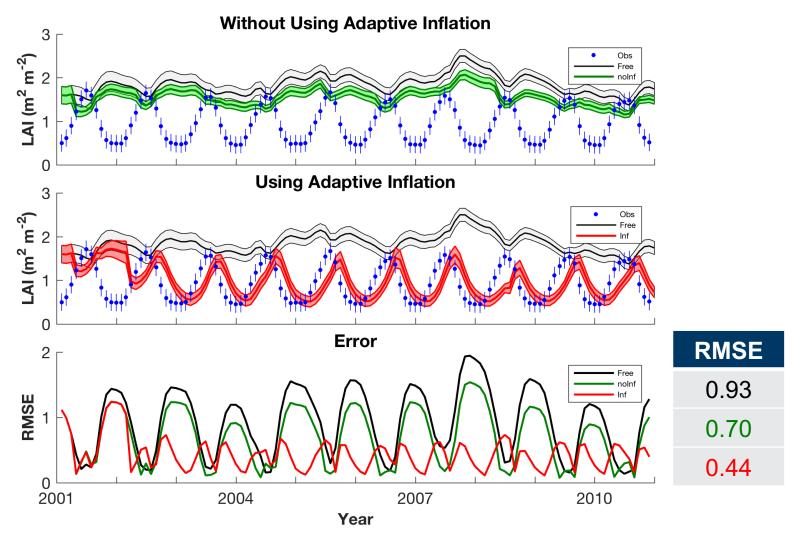


Assimilating LAI requires adaptive inflation



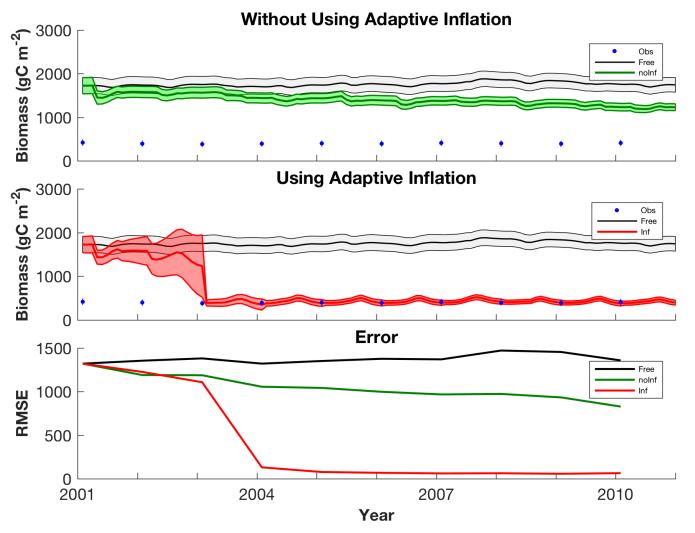


50% reduction in LAI RMSE with assimilation



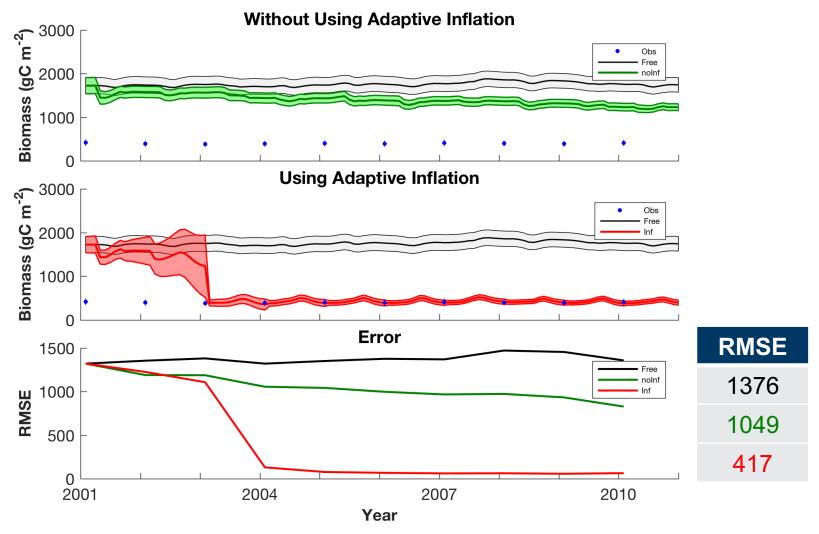


Assimilating Biomass using adaptive inflation



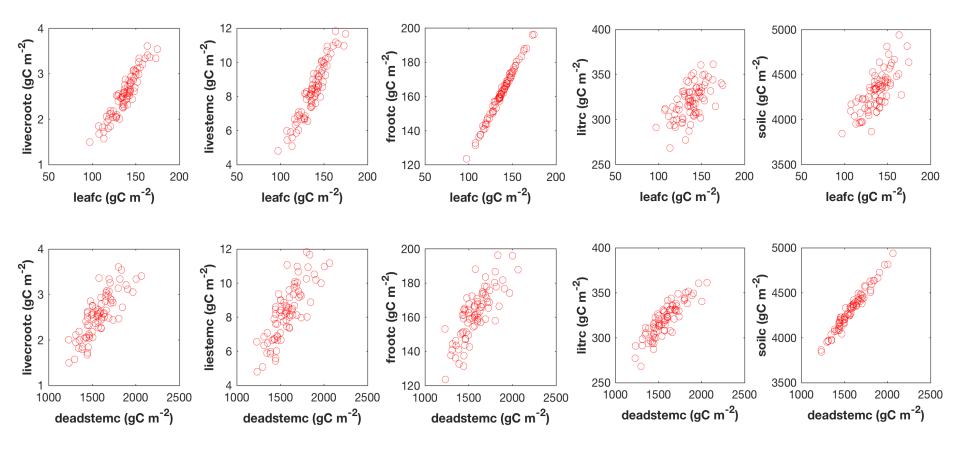


70% reduction in Biomass RMSE with assimilation



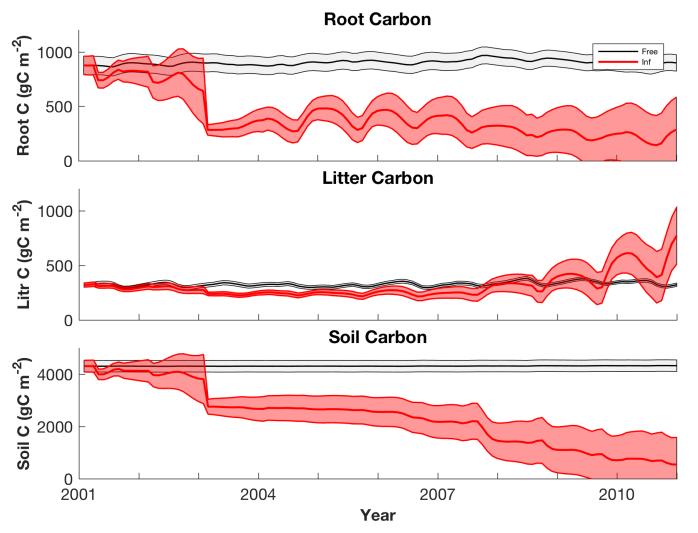


Observed and unobserved states



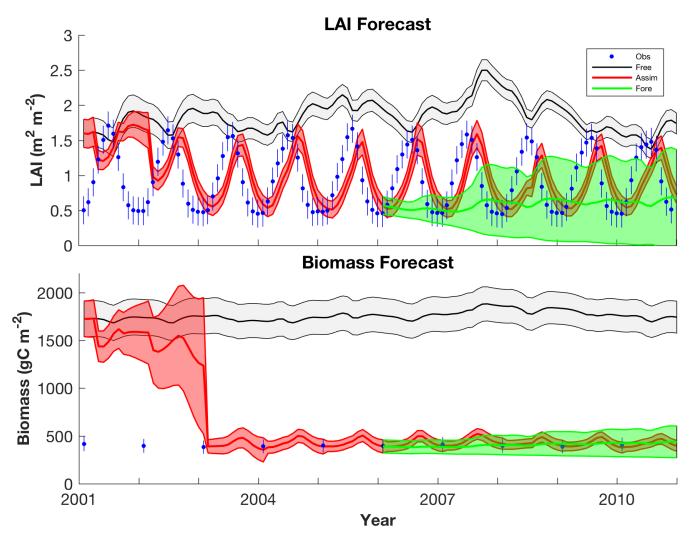


Unobserved State variables are also updated



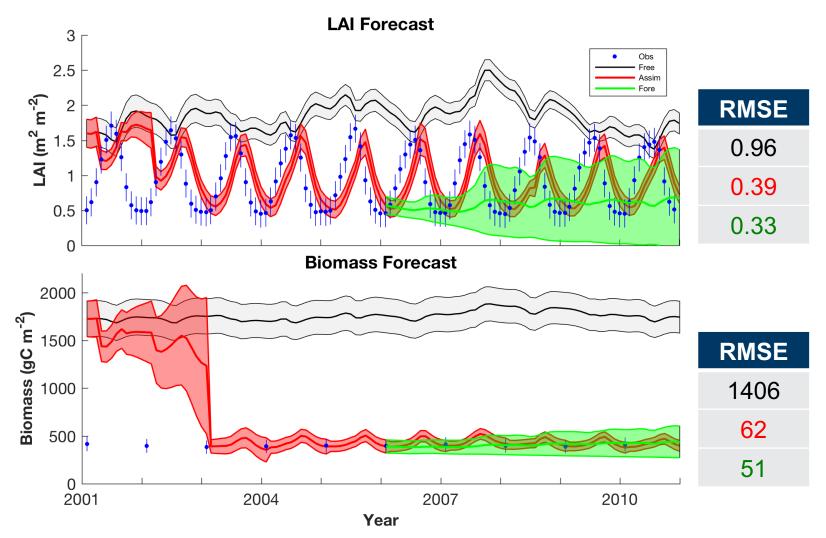


Longer-term forecasts are improved as well



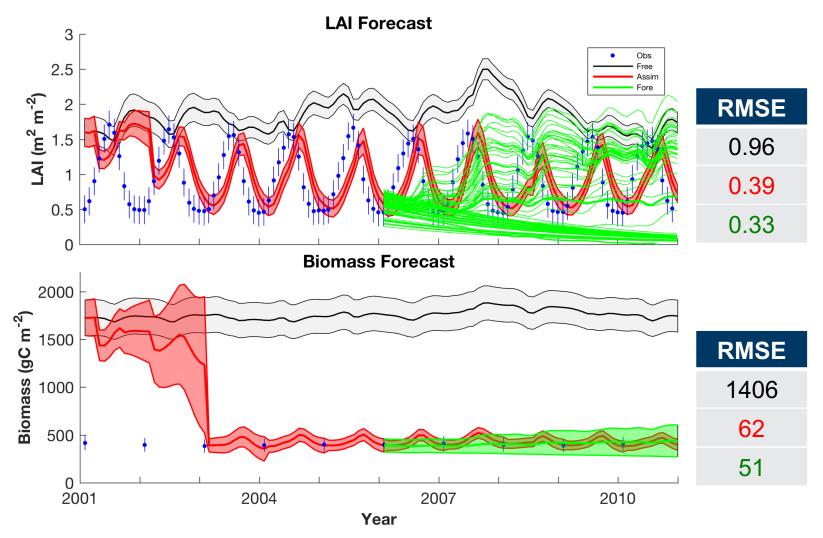


Longer-term forecasts are improved as well





But interestingly the ensemble splits





- 1) Forecasts benefit from accurate initial conditions
- 2) Impact persists from years to decades for different C pools
- 3) Spun-up model had too high biomass, and inaccurate seasonal cycle in LAI
- 4) Large reductions in error during assimilation and forecast periods
- 5) Adaptive inflation is required to account for large model error



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www.image.ucar.edu/DAReS/DART/



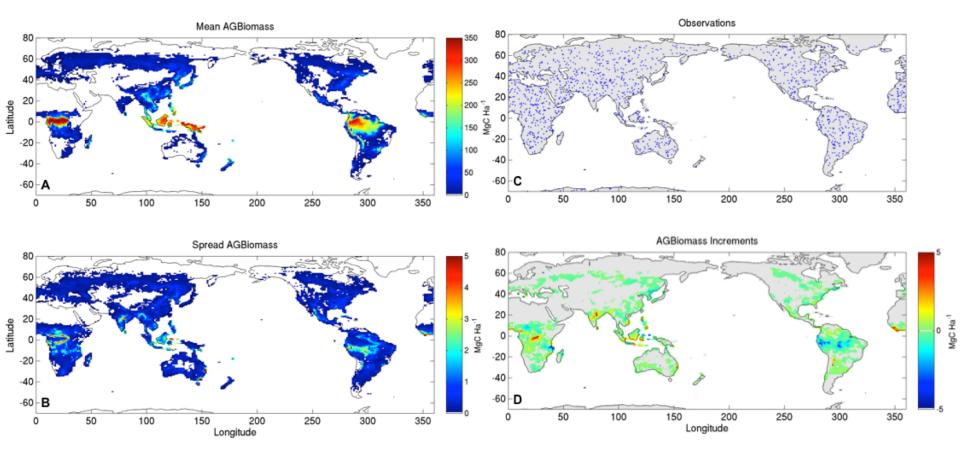
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Georgia O'Keeffe – "Black Mesa Landscape"

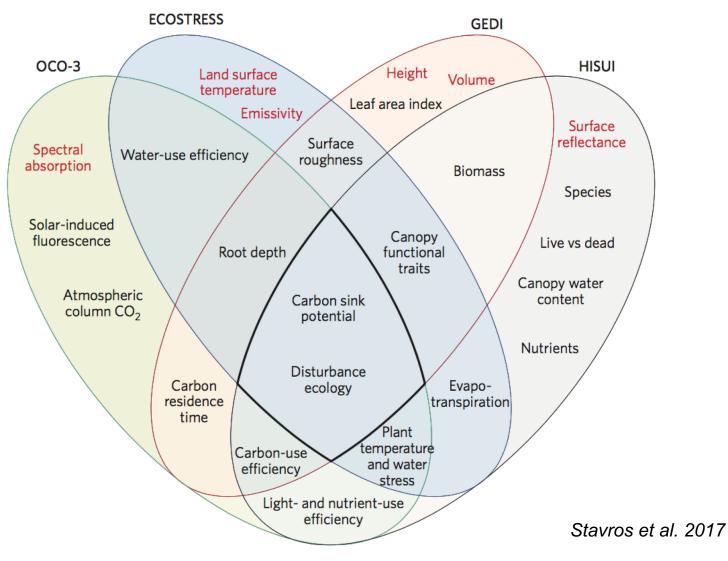


Global Biomass OSSE



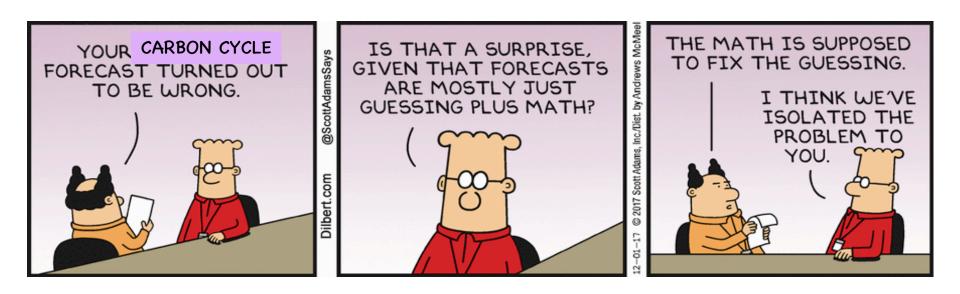


New observations from ISS





So, what about that model error?



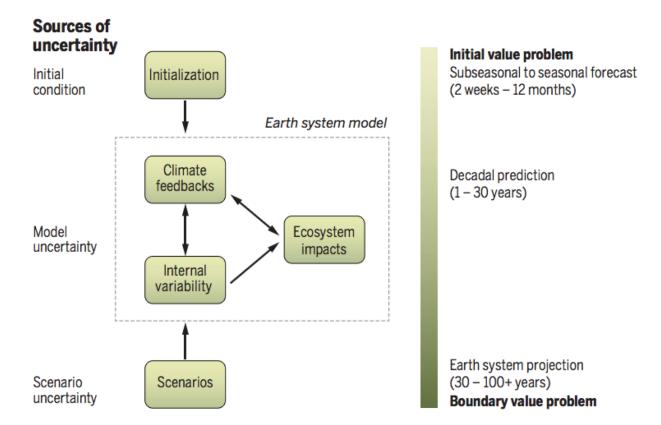


Sources of Uncertainty?

Climate, ecosystems, and planetary futures: The challenge to predict life in Earth system models

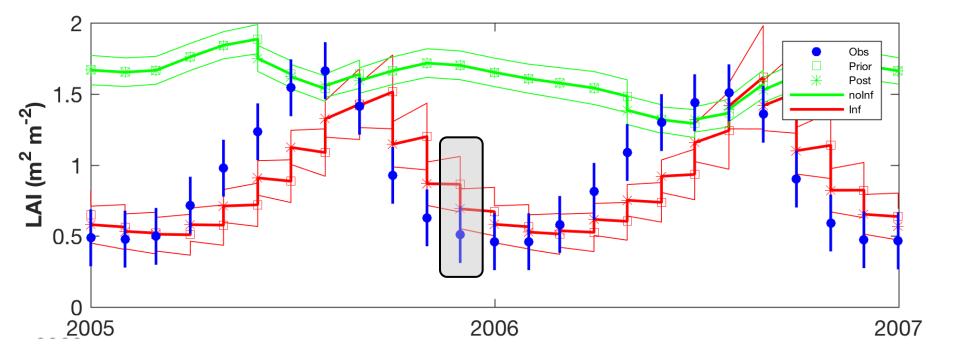
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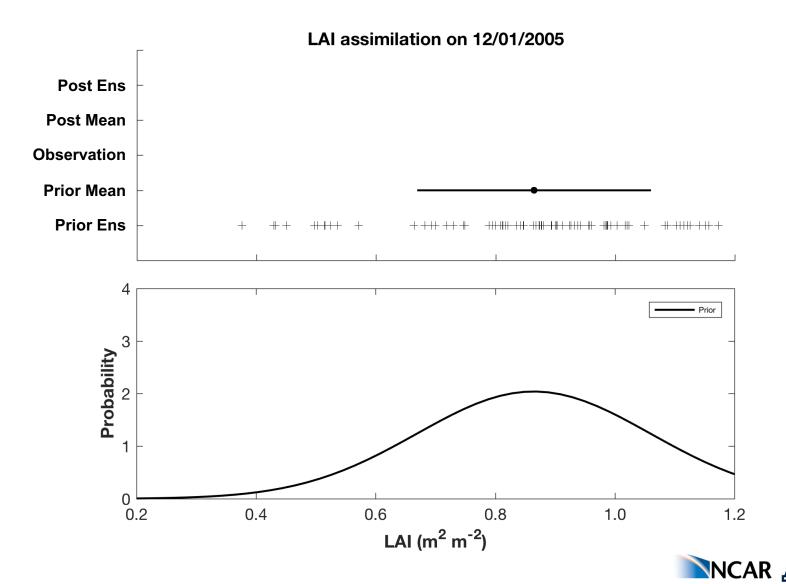


Ensemble forecast is updated by observations



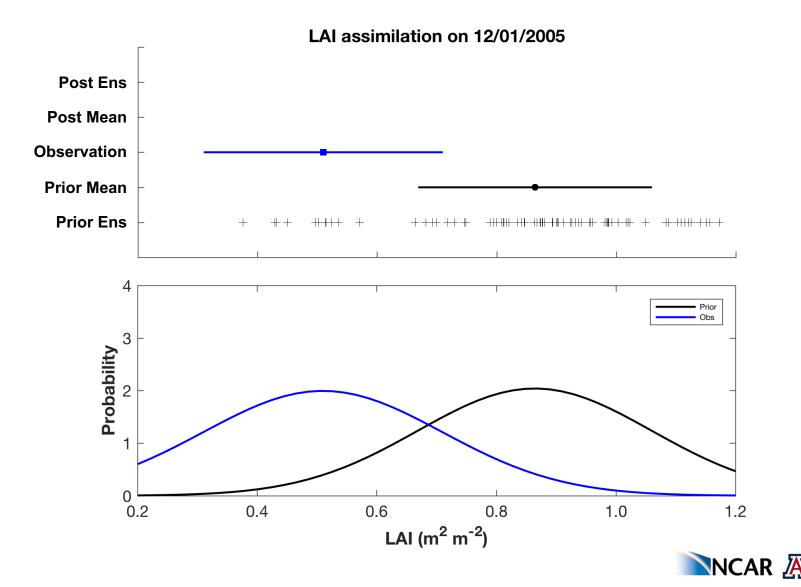


Normal is fitted to the prior/forecast ensemble...



rsity

...we have an observation with an uncertainty...



THE UNIVERSITY

... use EAKF to calculate posterior/analysis

LAI assimilation on 12/01/2005 Post Ens ++ ++++ + **Post Mean** Observation **Prior Mean Prior Ens** +4 Prior Obs **Probability** Post 1 0 0.4 0.6 0.2 0.8 1.0 1.2 LAI $(m^2 m^{-2})$

