Spatial Analysis to Quantify Numerical Model Bias and Dependence: How Many Climate Models Are There?

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Introduction

Climate models and questions of interest Data

Climate model biases for Mean state and Trend

Correlation between model biases Mean State Trend

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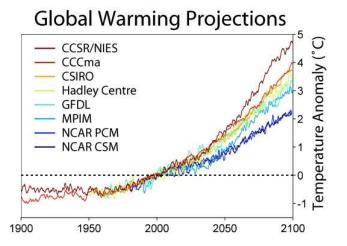
Intergovernmental Panel on Climate Change (IPCC)

- Established in 1988 by two United Nations organizations, the World Meteorological Organization (WMO) and the United Nations Environment Programme (UNEP)
- Goal: assess the "risk of human-induced climate change"
- Global climate model: numerical model that gives climate output on grids
- ▶ We have 20+ climate models developed by various organizations over the world

Intergovernmental Panel on Climate Change (IPCC)

	Group	Country	IPCC I.D.	Resolution
1	Beijing Climate Center	China	BCC-CM1	192 × 96
2	Canadian Center for Climate Modelling & Analysis	Canada	CGCM3.1	96 × 48
3	Météo-France/			
	Centre National de Recherches Météorologiques	France	CNRM-CM3	128 × 64
4	CSIRO Atmospheric Research	Australia	CSIRO-Mk3.0	192 × 96
5	US Dept. of Commerce/NOAA/Geophysical			
	Fluid Dynamics Laboratory	USA	GFDL-CM2.0	144×90
6	US Dept. of Commerce/NOAA/Geophysical			
	Fluid Dynamics Laboratory	USA	GFDL-CM2.1	144×90
7	NASA/Goddard Institute for Space Studies	USA	GISS-AOM	90 × 60
8	NASA/Goddard Institute for Space Studies	USA	GISS-EH	72×46
9	NASA/Goddard Institute for Space Studies	USA	GISS-ER	72 × 46
10	LASG/Institute of Atmospheric Physics	China	FGOALS-g1.0	128 × 60
11	Institute for Numerical Mathematics	Russia	INM-CM3.0	72 × 45
12	Institut Pierre Simon Laplace	France	IPSL-CM4	96 × 72
13	Center for Climate System Research,			
	National Institute of Environmental Studies,		MIROC3.2	
	and Frontier Research Center for Global Change	Japan	(medres)	128×64
14	Meteorological Institute of the University of Bonn,			
	Meteorological Research Institute of KMA,	Germany/		
	and Model and Data group	Korea	ECHO-G	96×48
15	Max Planck Institute for Meteorology	Germany	ECHAM5/MPI-OM	192 × 96
16	Meteorological Research Institute	Japan	MRI-CGCM2.3.2	128×64
17	National Center for Atmospheric Research	USA	CCSM3	256 × 128
18	National Center for Atmospheric Research	USA	PCM	128 × 64
19	Hadley Centre for Climate Prediction and Research/			
	Met Office	UK	UKMO-HadCM3	95×73
20	Hadley Centre for Climate Prediction and Research/			
	Met Office	UK	UKMO-HadGEM1	192×145

Intergovernmental Panel on Climate Change (IPCC)



Questions of interest

- How can we quantify the model bias?
- Relationship between bias in the mean state and bias in the trend?
- Are the climate model outputs random samples from a distribution symmetric around true climate?
- Especially, are the model biases correlated?
 - ⇒ How many models do we really have?

Observation vs model output

- ▶ Monthly averages in 1970-1999 (unit: ° C) of surface temperature
- Latitude range: 45° S 72° N
- Observations: combined data set from CRU (Climate Research Unit, East Anglia) and the Hadley Centre (UK), a few missing data
- ▶ IPCC model outputs: 19 models, no missing data
- Discrepancy of grids: bilinear interpolation of the model outputs to the observation grid
- Naive imputation for the missing observations

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Mean State

Trend

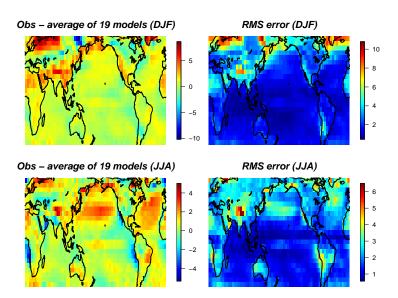
Biases for Mean state

- X(s, t): DJF (or JJA) averages of the observation at location s and year t
- $ightharpoonup Y_i(\mathbf{s},t)$: i^{th} model output
- ▶ Difference: $D_i(\mathbf{s}, t) = X(\mathbf{s}, t) Y_i(\mathbf{s}, t)$

$$D_i(\mathbf{s},t) = b_i(\mathbf{s}) + u_i(\mathbf{s},t)$$

- b_i is the bias for the mean state
- ► Model b_i based on $\bar{D}_i(\mathbf{s}) = \frac{1}{30} \sum_{t=1}^{30} D_i(\mathbf{s}, t)$

Averaged bias and RMS



Spatial model for the bias

$$b_i(\mathbf{s}) = \mu_{0i} + \mu_{1i} L(\mathbf{s}) + \mu_{2i} \mathbf{1}_{(\mathbf{s} \in \mathsf{land})} + \mu_{3i} A(\mathbf{s}) + a_i(\mathbf{s})$$

- ▶ a_i: mean zero Gaussian random field
- Covariance structure of a_i: simple nonstationary covariance model valid on sphere

$$a_i(\mathbf{s}) = (\delta_i \mathbf{1}_{(\mathbf{s} \in \mathsf{land})} + 1) Z_i(\mathbf{s})$$
 $(\delta_i > 0)$

- Cov{ $Z_i(\mathbf{s}_1), Z_i(\mathbf{s}_2)$ } = $\alpha_i \mathcal{M}_{\nu_i+1}(\mathbf{d}/\beta_i)$ (\mathbf{d} : chordal distance between \mathbf{s}_1 and \mathbf{s}_2)
- Could apply more complex model for Nonstationarity (Jun and Stein 2007, *Technometrics*, To appear):

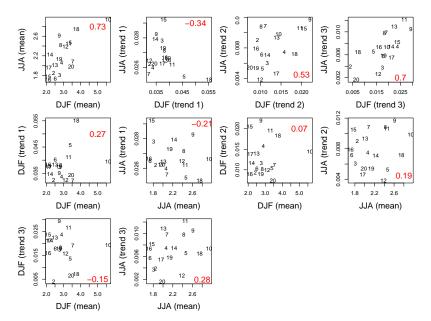
eg)
$$a_i(\mathbf{s}) = \{\eta_i(L)\frac{\partial}{\partial L} + \psi_i(L)\frac{\partial}{\partial L}\}Z_i(\mathbf{s}) + d_iZ_i(\mathbf{s}).$$



Biases for Trend

- X(s, t): seasonal averages (DJF or JJA) of observation at location s and year t
- $ightharpoonup Y_i(\mathbf{s},t)$: i^{th} model output
- ▶ Regress X and Y_i on $t \bar{t}$, separately
- ▶ Bias is defined as the difference between slope from X and slope from Y_i (Trend 1)
- ➤ A lot of "noise" in the observation slope: smooth both observation and model output beforehand (Trend 2)
- ► Take spatial averages of observation and model output and then calculate the absolute difference between observation slope and model slope (Trend 3)

Biases for Mean state vs Trend



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Quantify cross-correlation

 $ightharpoonup \sigma_{ij}(\mathbf{s}) = \text{Cov}\{a_i(\mathbf{s}), a_j(\mathbf{s})\}$

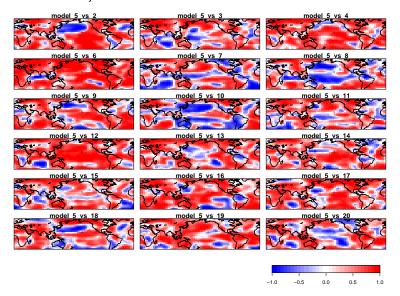
: correlation between i^{th} and j^{th} model biases at location **s**

▶ Apply Gaussian kernel to $\tilde{D}_{ij}(\mathbf{s}) = \tilde{D}_i(\mathbf{s})\tilde{D}_j(\mathbf{s})$, where $\tilde{D}_i(\mathbf{s})$ is "filtered $\bar{D}_i(\mathbf{s})$ "

$$\hat{\sigma}_{ij}(\mathbf{s}) = \sum_{k=1}^{1656} K\left(\frac{|\mathbf{s}, \mathbf{s}_k|}{h}\right) \tilde{\bar{D}}_{ij}(\mathbf{s}_k) \cdot \left[\sum_{k=1}^{1656} K\left(\frac{|\mathbf{s}, \mathbf{s}_k|}{h}\right)\right]^{-1}$$

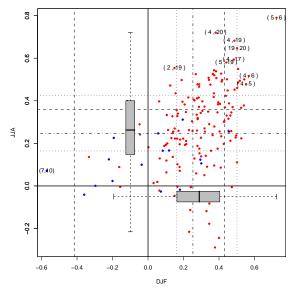
Estimated correlation between biases

Figure gives r_{5j} , $j = 2, \dots, 20$ (DJF, mean state)



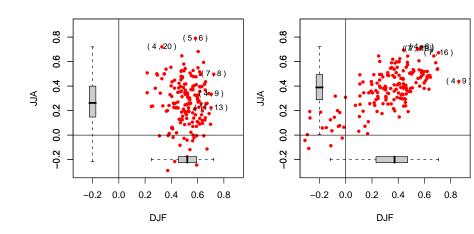
Estimated correlation between biases

Figure gives r_{ij} averaged over space (mean state)



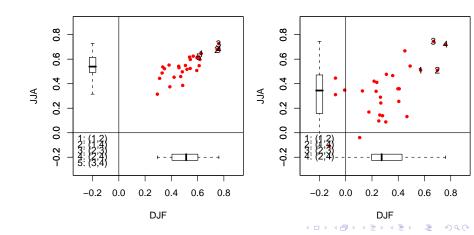
Estimated correlation between biases

Figure gives r_{ij} averaged over space (trend)



Issues with correlation for Trend

- ► Four ensemble members of model 2 (1,2,3,4)
- ▶ Two ensemble members of model 5 (5,6)
- ▶ Two ensemble members of model 6 (7,8)



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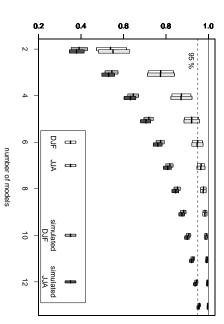
Mean State

Trend

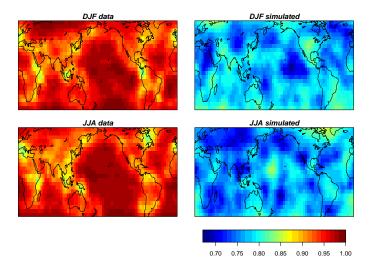


How many eigenvalues needed?

bandwidth 800 km



First top 5 eigen values (mean state)



Multidimensional scaling

With correlation matrices as similarity measure, we can form subgroups of climate models

