



Inverse Problem for Complex Computer Codes

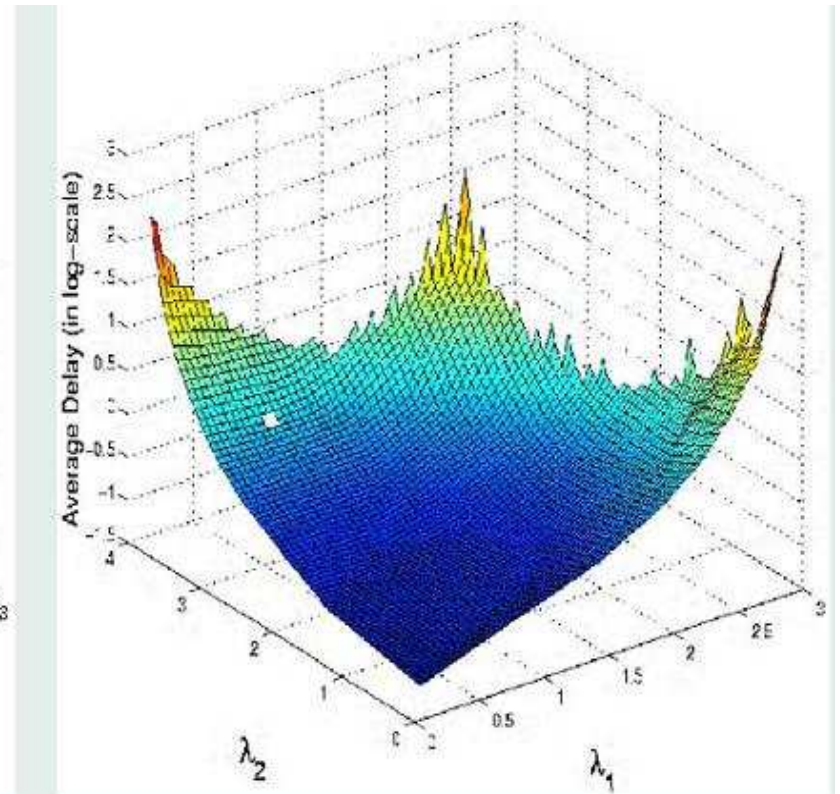
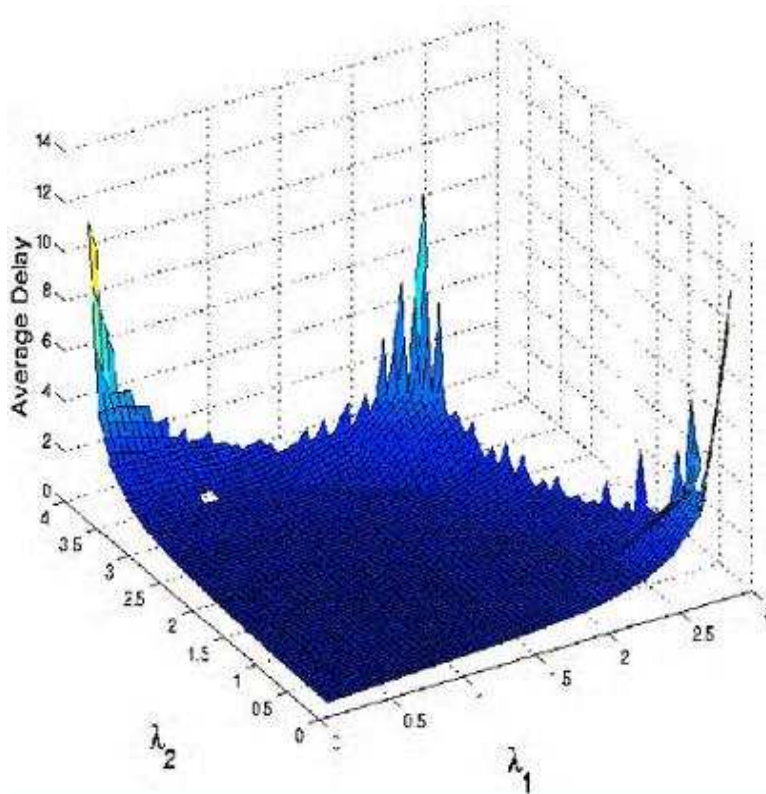
Pritam Ranjan

Simon Fraser University



Application

- Dell - IBM example



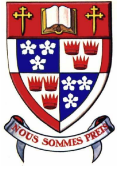
Inverse problem





Inverse problem

- Different than standard inverse problem?



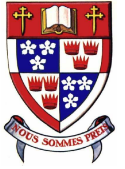
Inverse problem

- Different than standard inverse problem?
- Simulator is expensive



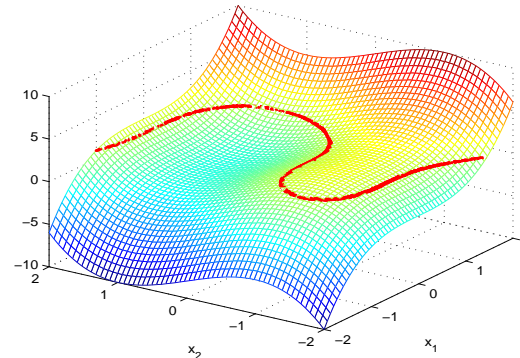
Inverse problem

- Different than standard inverse problem?
- Simulator is expensive
- Budget is fixed (say n)



Formulation of the problem

- Interested in only a contour $S(a) = \{x : y(x) = a\}$



- Choice of design points

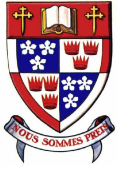
Steps of the solution





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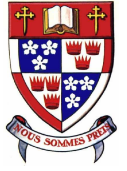
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4. Run the trial, get augmented data



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6. Extraction of the contour $S(a)$, where,
$$S(a) = \{x : y(x) = a\}$$



Overview

- Response surface
- Selection of new trials
- Contour extraction
- Example
- Summary
- Concluding remarks
- Current work



Surrogate model

- Deterministic simulators

$$y(x_i) = \mu + z(x_i); \quad i = 1, \dots, n,$$



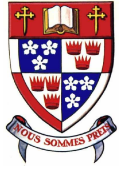
Surrogate model

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- Use Gaussian Process model

$$z(\mathbf{x}) \sim N(\mathbf{0}, \sigma^2 \mathbf{R})$$



Surrogate model

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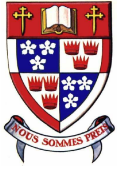
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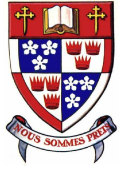
- Separable correlation structure

$$\text{corr}(z(x_i), z(x_j)) = R_{ij} = \prod_{k=1}^d \exp \left\{ -\theta_k (x_{ik} - x_{jk})^2 \right\}$$



Predicted surface

- Model fitting:
 - (a) Relatively few parameters to estimate ($\theta_1, \dots, \theta_d, \mu, \sigma^2$)
 - (b) Bayesian or Likelihood method of estimation
 - (c) Easy to modify the model (smoothness)



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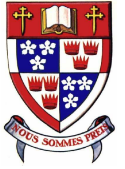
$$\hat{y}(x) = \hat{\mu} + r' \mathbf{R}^{-1} (\mathbf{y} - \mathbf{1}_n \hat{\mu})$$

where $r = (r_1(x), \dots, r_n(x))'$, & $r_i(x) = \text{corr}(z(x), z(x_i))$



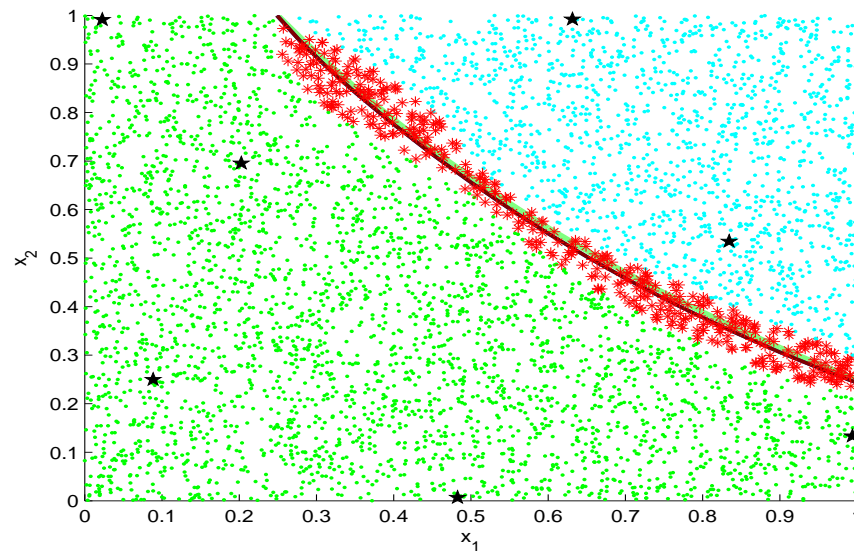
Selection of new trials

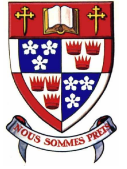
- Choose $x \in \chi$ s.t. $\hat{y}(x) \in (a - \epsilon, a + \epsilon)$



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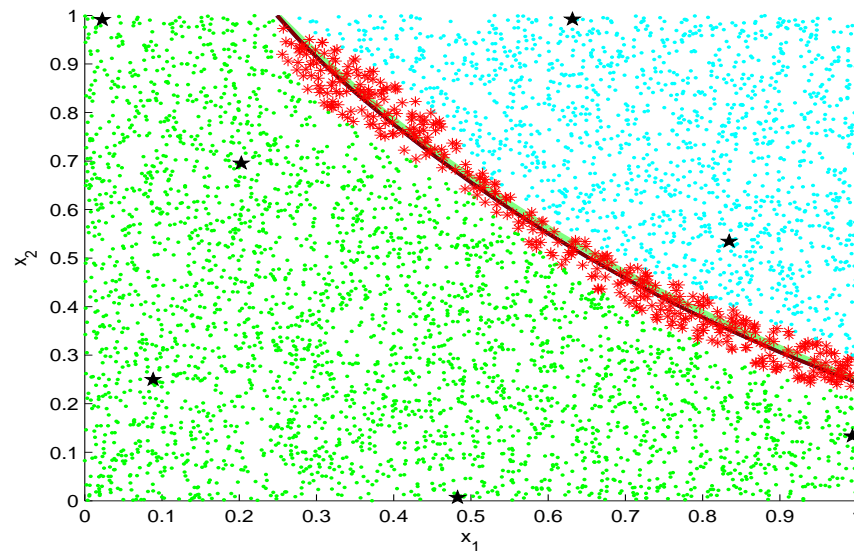
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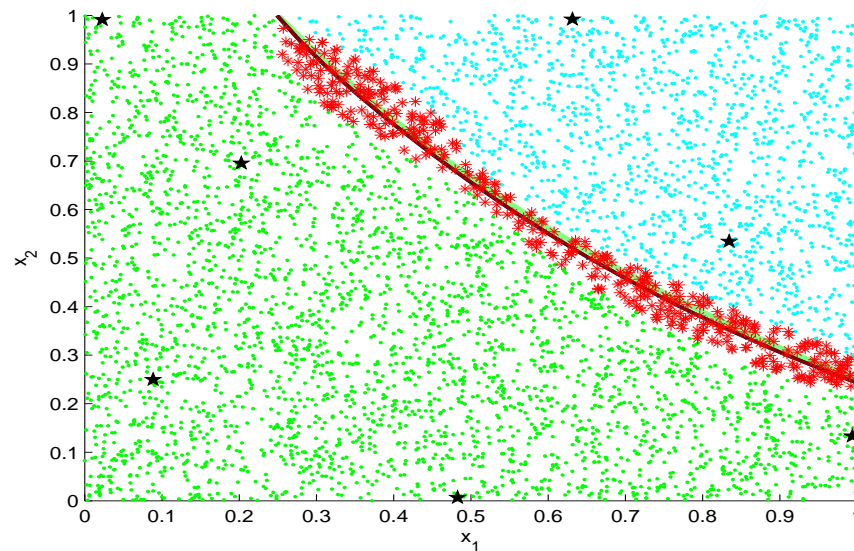


$$\begin{aligned} I(x) &= 0 && \text{if } y(x) \leq a - \epsilon(x) \\ &= \epsilon^2(x) - (y(x) - a)^2 && \text{if } a - \epsilon(x) < y(x) \leq a + \epsilon(x) \\ &= 0 && \text{if } a + \epsilon(x) < y(x) \end{aligned}$$



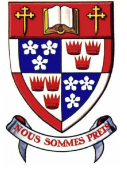
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- Hence, define $I(x) = \epsilon^2(x) - \min\{(y(x) - a)^2, \epsilon^2(x)\}$ and $\epsilon(x) = \alpha s(x)$



Selection of new trials (contd.)

- Temptation : maximize the improvement function



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$$\begin{aligned} E[I(x)] &= [\alpha^2 s^2(x) - (\hat{y}(x) - a)^2] \left[\Phi \left(\frac{a - \hat{y}(x)}{s(x)} + \alpha \right) - \Phi \left(\frac{a - \hat{y}(x)}{s(x)} - \alpha \right) \right] \\ &+ 2(\hat{y}(x) - a)s^2(x) \left[\phi \left(\frac{a - \hat{y}(x)}{s(x)} + \alpha \right) - \phi \left(\frac{a - \hat{y}(x)}{s(x)} - \alpha \right) \right] \\ &- \int_{a - \alpha s(x)}^{a + \alpha s(x)} (\hat{y}(x) - y)^2 \phi \left(\frac{\hat{y}(x) - y}{s(x)} \right) dy \end{aligned}$$



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- Minimizes the overall variability

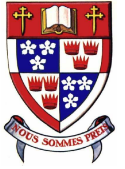


Selection of new trials (contd.)

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- Selects trial from $(a - \epsilon, a + \epsilon)$
- Minimizes the overall variability
- Optimization issues



Contour extraction

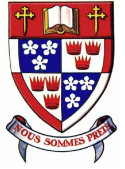
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Contour extraction

- Need an implicit function to model the contour
- Convenient feature of GASP model, recall that the predictor is $\hat{y}(x) = \hat{\mu} + r'\mathbf{R}^{-1}(Y - \hat{\mu}\mathbf{1}_n)$ therefore,

$$a = \hat{\mu} + r'\mathbf{R}^{-1}(Y - \hat{\mu}\mathbf{1}_n)$$



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- No other values of response should be used for contour extraction



▪

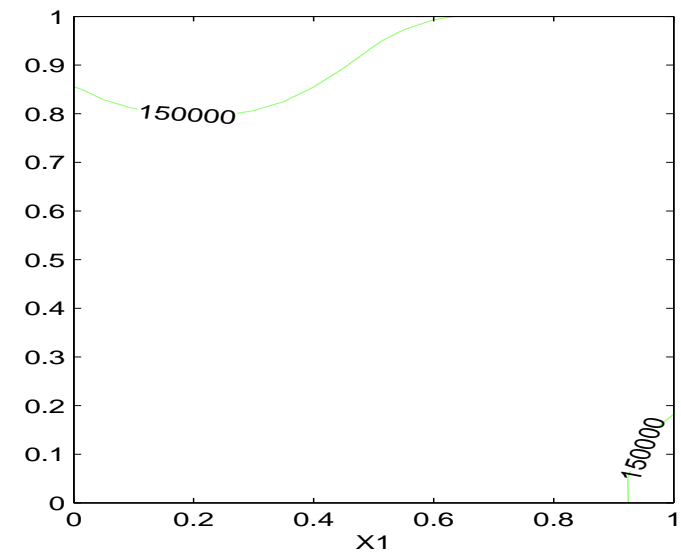
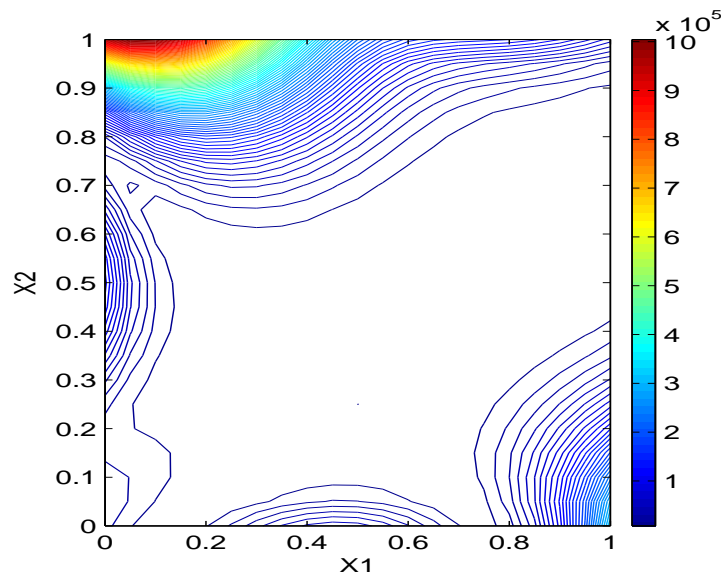
Example



Illustration / Example

■ Goldprice function

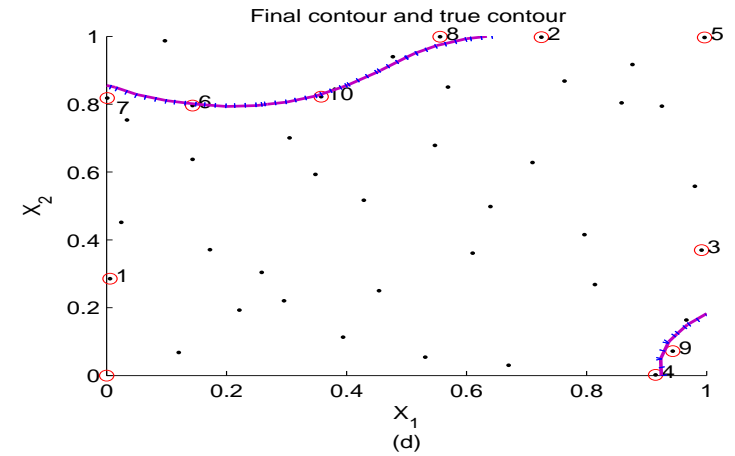
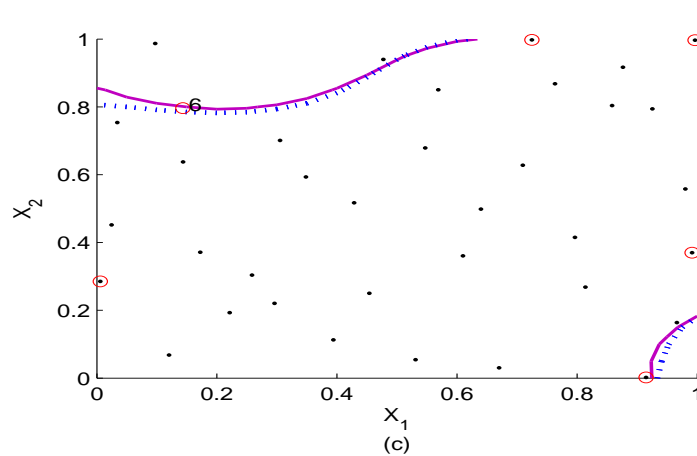
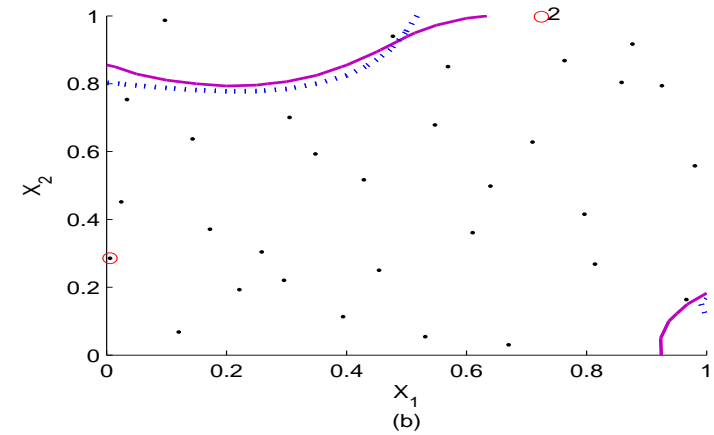
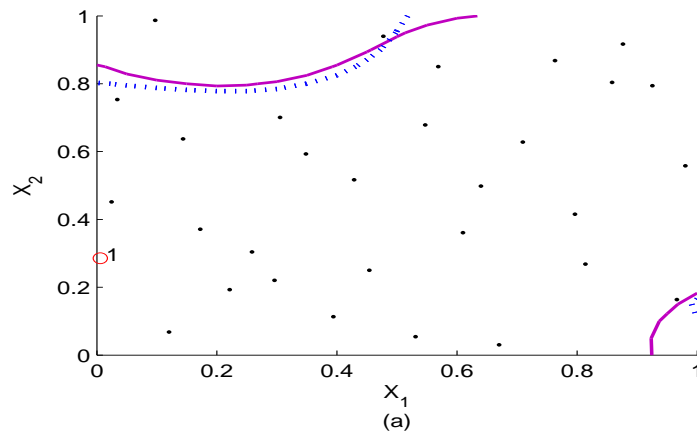
$$f(x, y) = [1 + (x + y + 1)^2(19 - 14x + 3x^2 - 14y + 6xy + 3y^2)] \\ * [30 + (2x - 3y)^2(18 - 32x + 12x^2 + 48y - 36xy + 27y^2)]$$





Example (contd.)

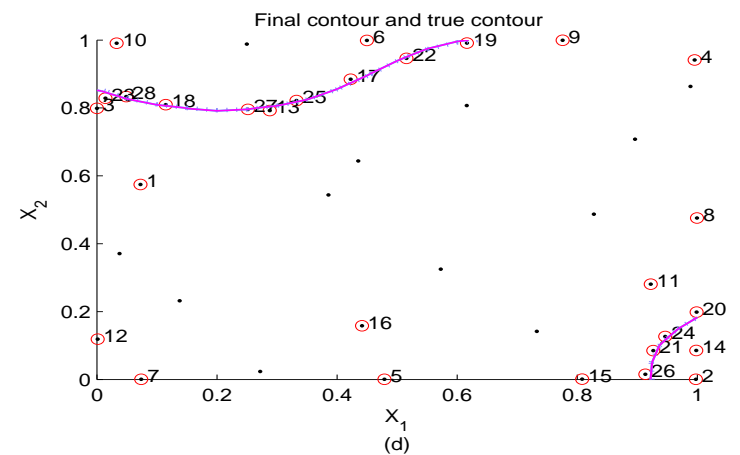
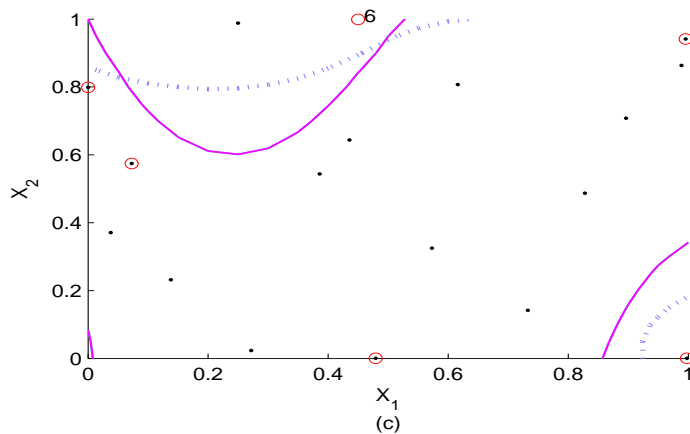
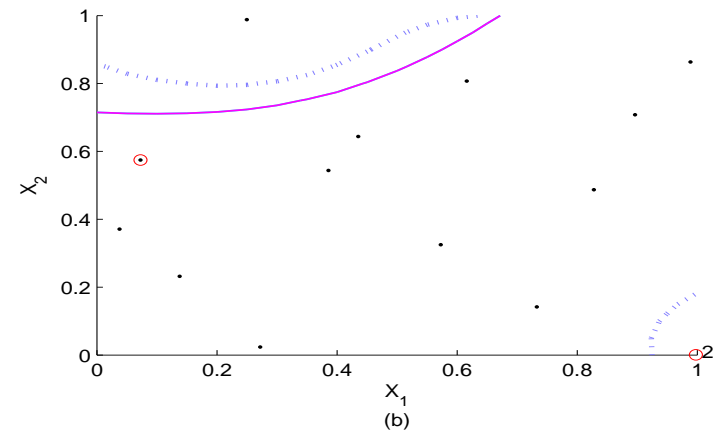
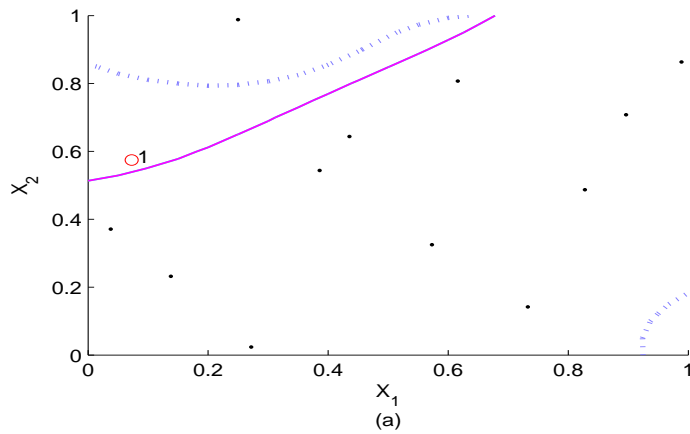
■ $n_0 = 30$ and $n = 40$





Example (contd.)

■ $n_0 = 12$ and $n = 40$

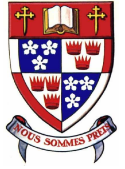




Aside: Goodness of fit measures

- Lack in Correlation between $C_{n_0,k}$ and truth

$$M_1 = \sum_{l=1}^d (1 - \text{corr}(x^{lk}, x^{lt}))$$



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$$M_2 = \frac{1}{|C_{n_0,k}|} \sum_{x \in C_{n_0,k}} d(x, C_t)$$

where, $d(x, C_t) = \min\{\|x - y\|_2 : y \in C_t\}$.



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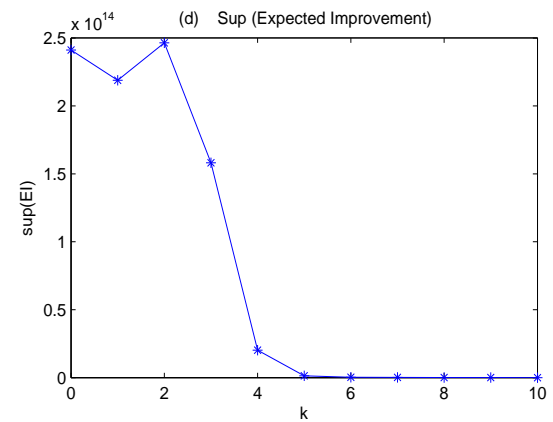
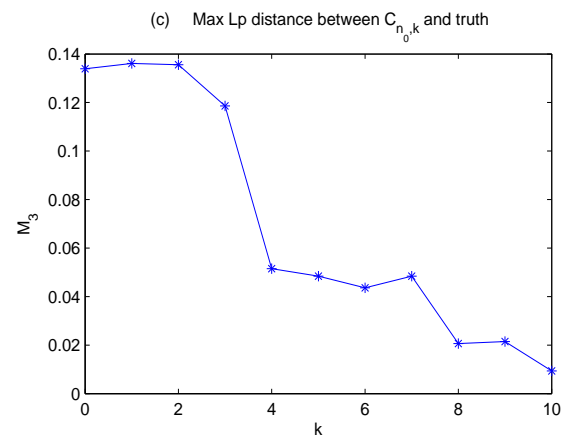
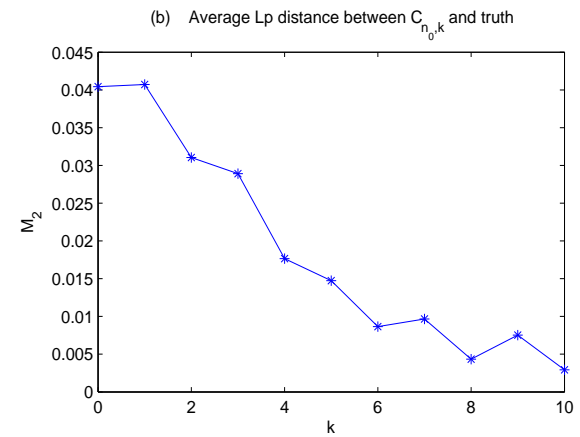
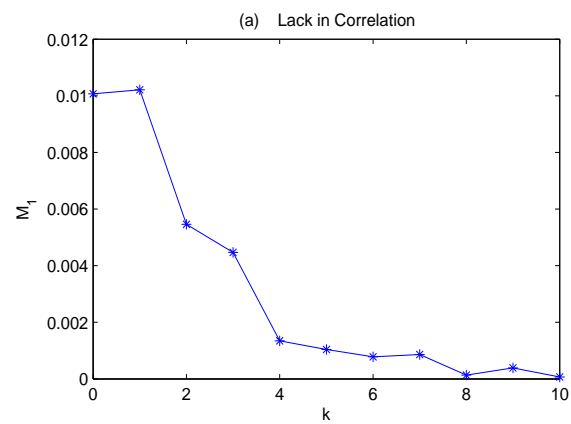
where, $d(x, C_t) = \min\{\|x - y\|_2 : y \in C_t\}$.

- Maximum L_2 distance between $C_{n_0,k}$ and truth

$$M_3 = \max\{d(x, C_t) : x \in C_{n_0,k}\}$$

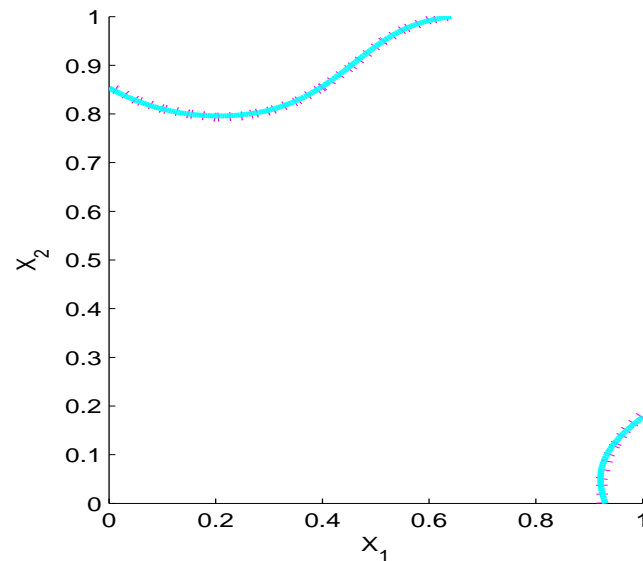


Example (contd.)





Example (contd.)



True contour and the implicit plot using GASP



Example (contd.)

■ Simulation study

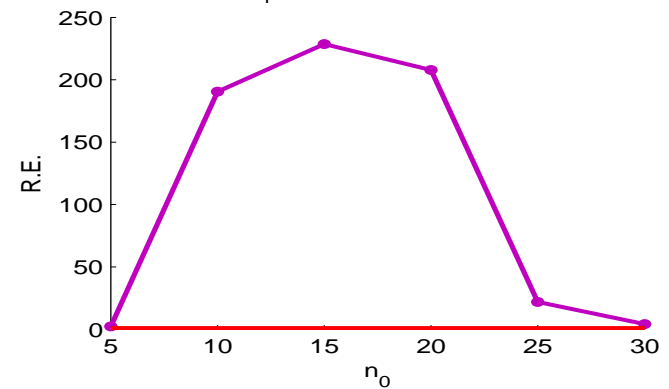
measures	$n_0 = 30, k = 5 (n = 35)$			$n_0 = 30, k = 10 (n = 40)$		
	LHC	Sequential	R.E.	LHC	Sequential	R.E.
M_1	0.4573	0.1108	4.13	0.1968	3.14e-04	625.51
M_2	0.1048	0.0371	2.82	0.0514	0.0053	9.70
M_3	0.4468	0.1540	2.90	0.2303	0.0246	9.36



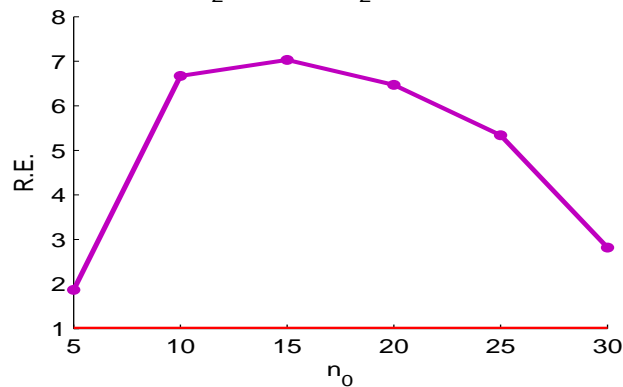
Example (contd.)

- Simulation study (contd):
here, $n_0 + k = 35$.

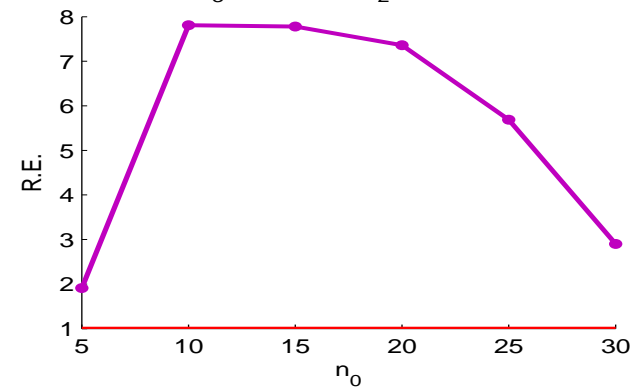
M_1 (Lack in Correlation)



M_2 (Average L_2 Distance)



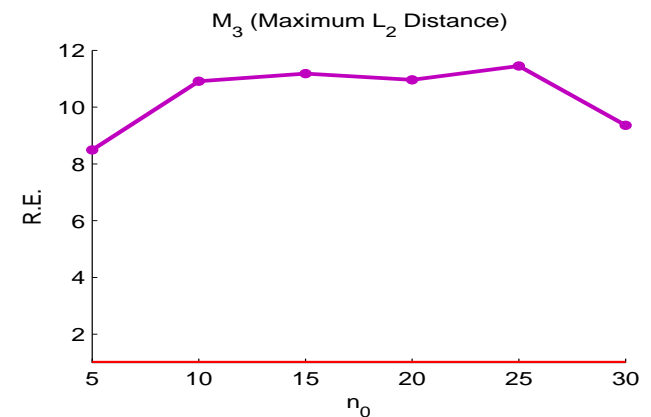
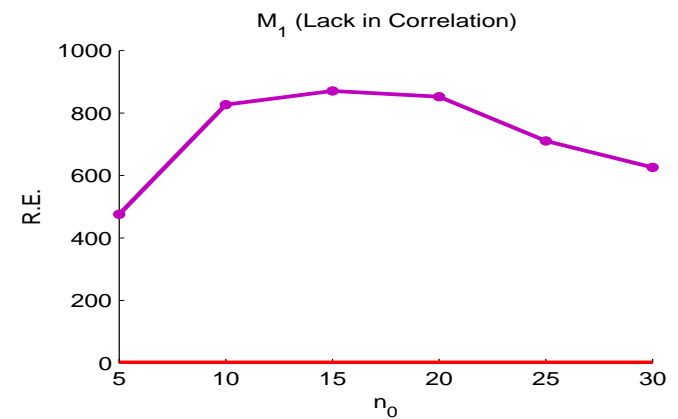
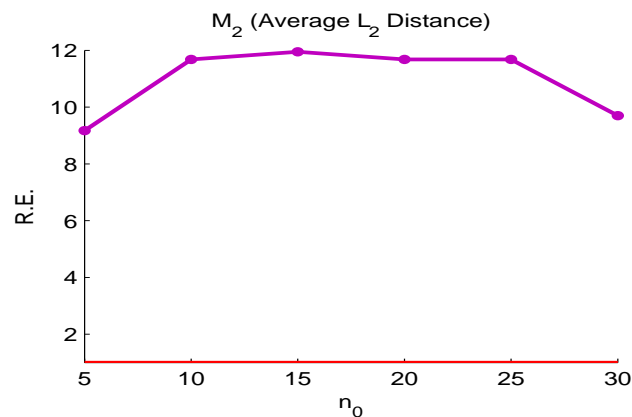
M_3 (Maximum L_2 Distance)

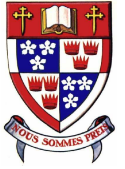




Example (contd.)

- Simulation study (contd):
here, $n_0 + k = 40$.





Summary

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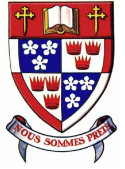
Summary

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3. Selected new trials using *Expected Improvement function*



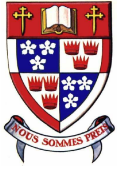
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5. Repeat step-2 to step-4, until budget allows



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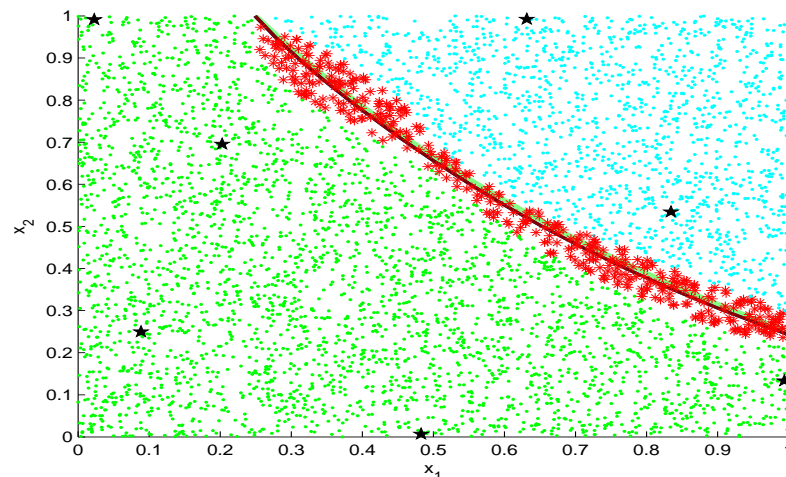
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4. Updated the design
5. Repeat step-2 to step-4, until budget allows
6. Extract the contour from the final surface



Concluding remarks

- Choice of n_0
- Goodness of fit measures (C_t versus C_{k+1})
- Choice of band radius (α)

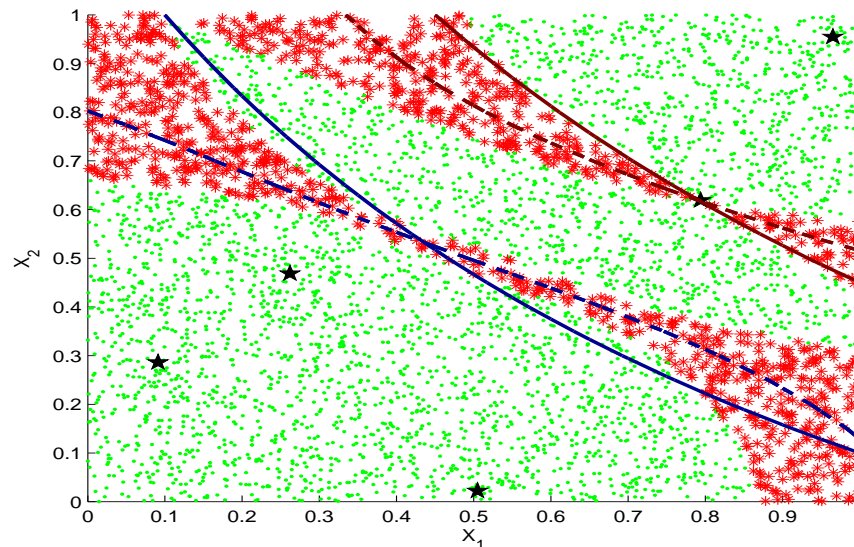
Recall that the ϵ -band is $(a - \alpha s(x), a + \alpha s(x))$
and $y(x) \sim N(\hat{y}(x), s^2(x))$



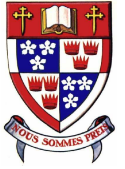


Related work

- Multiple contours

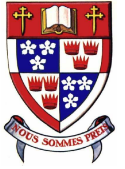


Without loss of generality : $a_1 < a_2 < \dots < a_k$



Related work

- Group-sequential approach for trials selection



Related work

- Group-sequential approach for trials selection
- Inverse problem for expensive simulators with functional response (nuclear waste dumping)



Thank you!