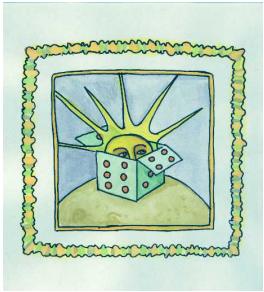


# Robust Data Assimilation

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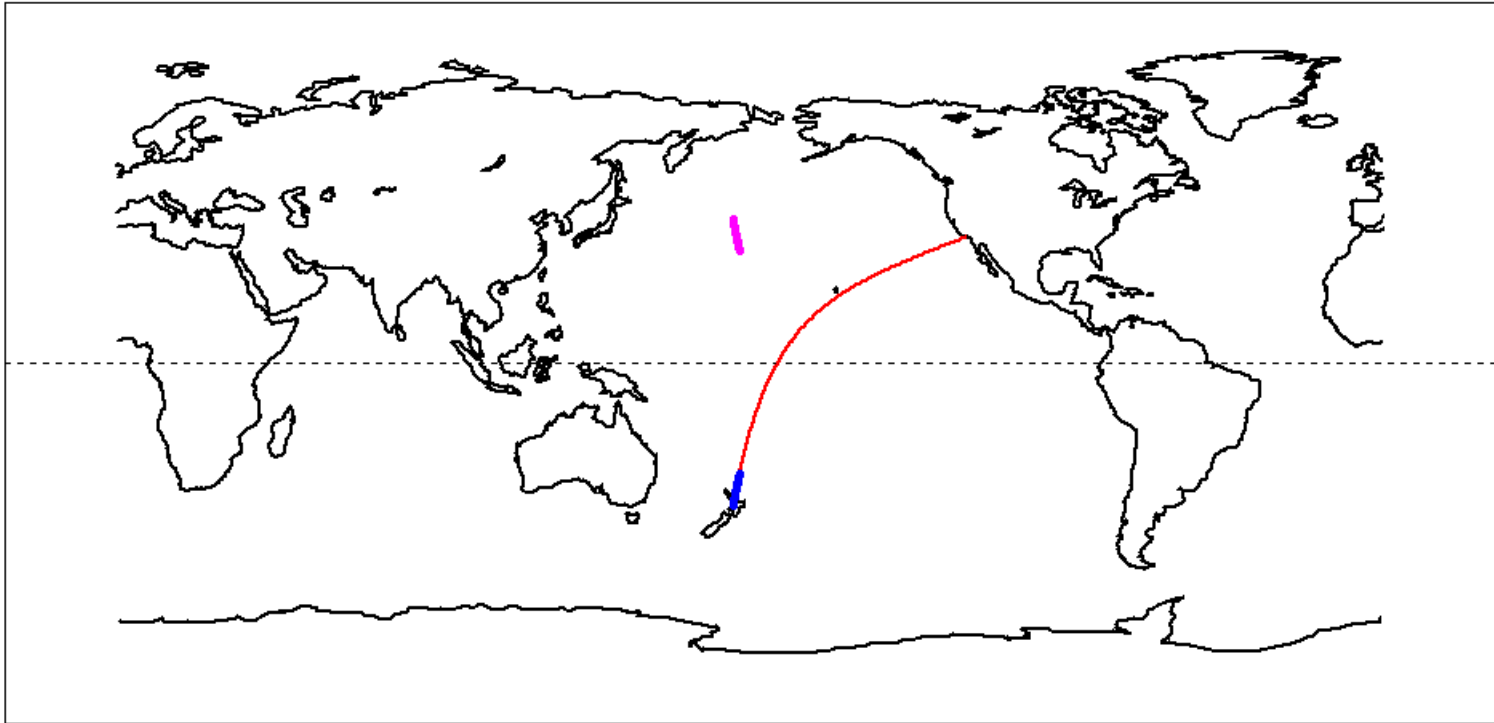
Douglas Nychka, Jeff Anderson, Chris Snyder  
The Data Assimilation Initiative  
National Center for Atmospheric Research



*Supported by the National Science Foundation DMS*

# What this project is about.

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# National Center for Atmospheric Research

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$\approx$  1000 people total, several hundred PH D (physical) scientists,

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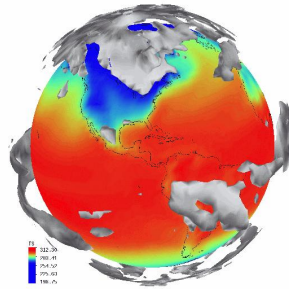


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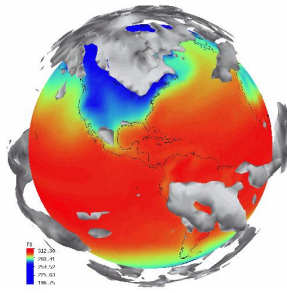
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Climate,



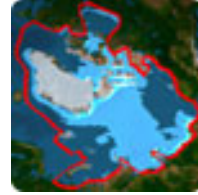
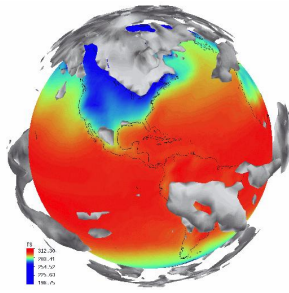


Climate,



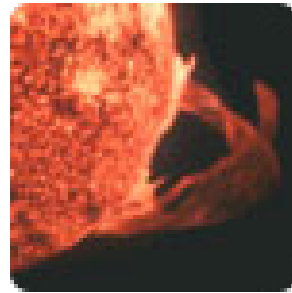
Weather,

Climate,



Weather,

the Sun,



# Ocean-atmosphere interactions,



Ocean-atmosphere interactions,



Ecosystems, Economic impacts,



Ocean-atmosphere interactions,



Ecosystems, Economic impacts,



Air quality,

# Instrumentation, Scientific computing



and ...

*Institute for Mathematics Applied to the Geosciences*

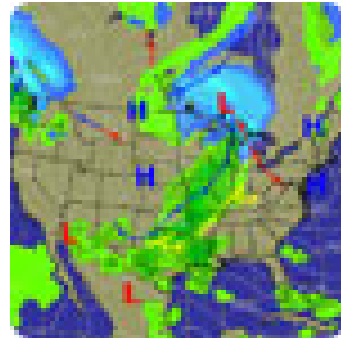
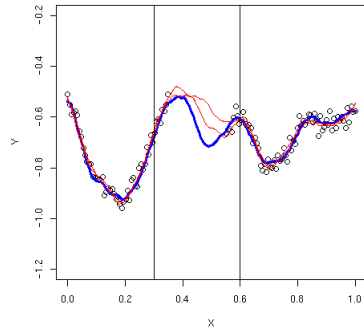


- Geophysical Turbulence Program
- Geophysical Statistics Project
- Data Assimilation Initiative

*Institute for Mathematics Applied to the Geosciences*



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# Some grand challenge problems:

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How will rainfall change in 50 years?

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*Combine complex numerical models with a variety of observations*

# Data/Model Fusion

---

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Combine predictions made by a numerical model with observed data to estimate the state of a system,  $x$ . This is also called a *filter*.

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*Standard approach is the Kalman Filter ...  
but it fails for large, nonlinear problems!*



# Ensemble Kalman Filter

---

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The uncertainty in the state of the system is represented by a *small sample* of possible states.

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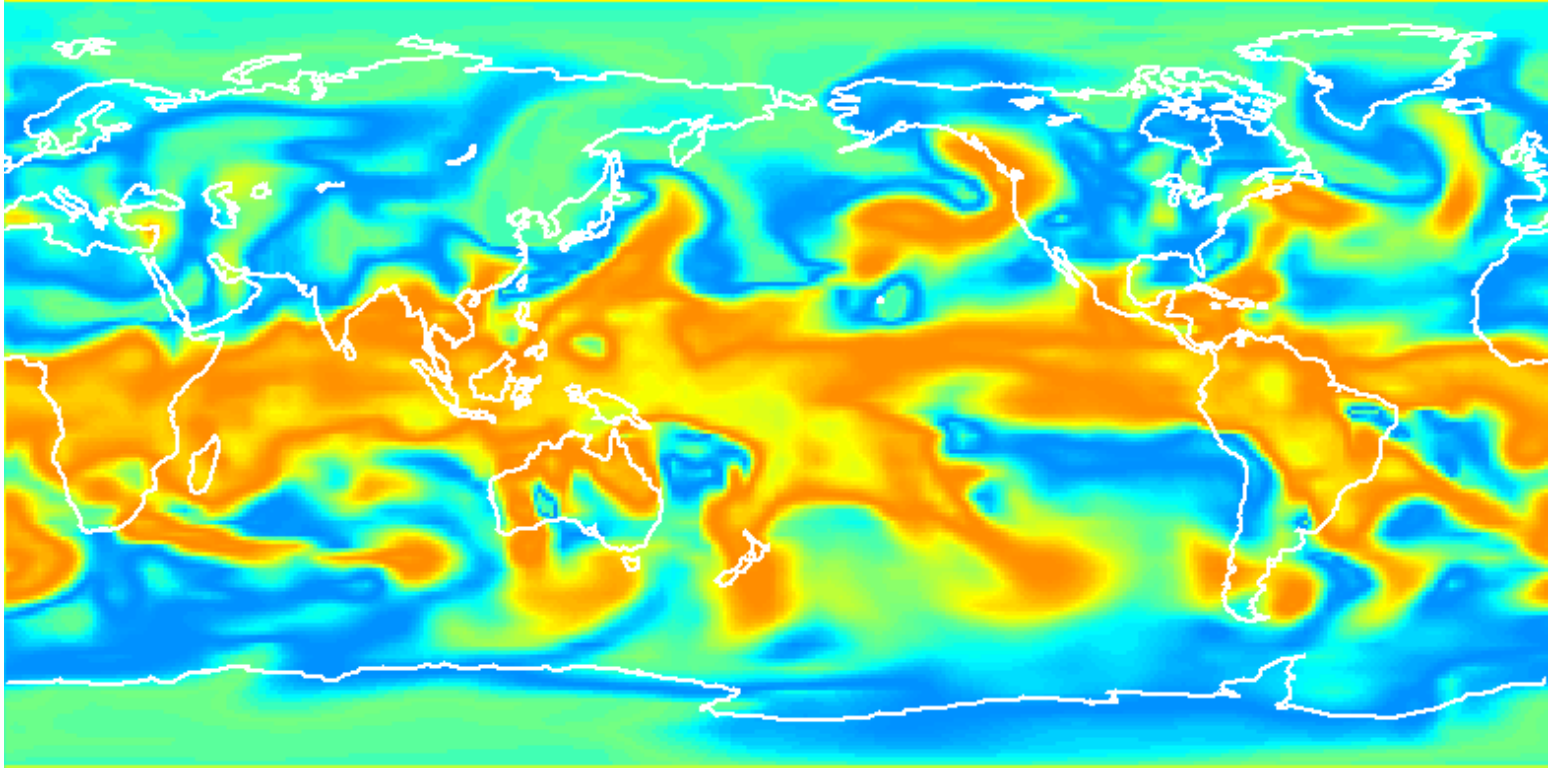
Means, variances and other statistics are found directly from the ensemble:

e.g.

$$\text{Mean field} = (\mathbf{x}_1 + \mathbf{x}_2 + \dots + \mathbf{x}_m)/m$$

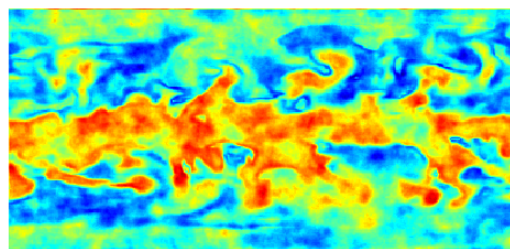
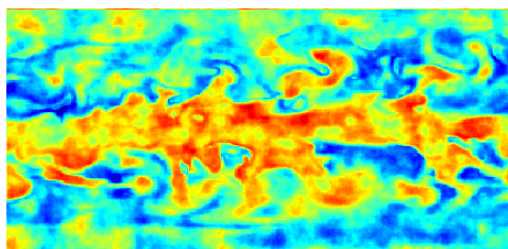
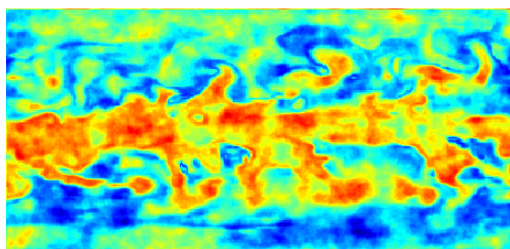
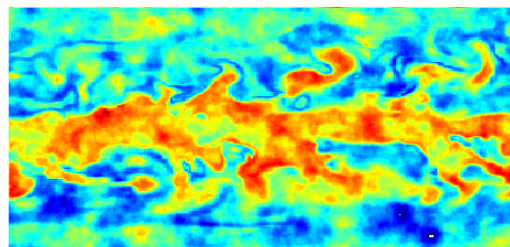
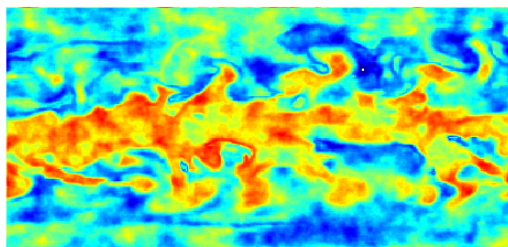
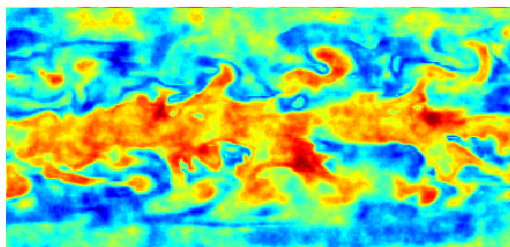
## As an example: the global water vapor field

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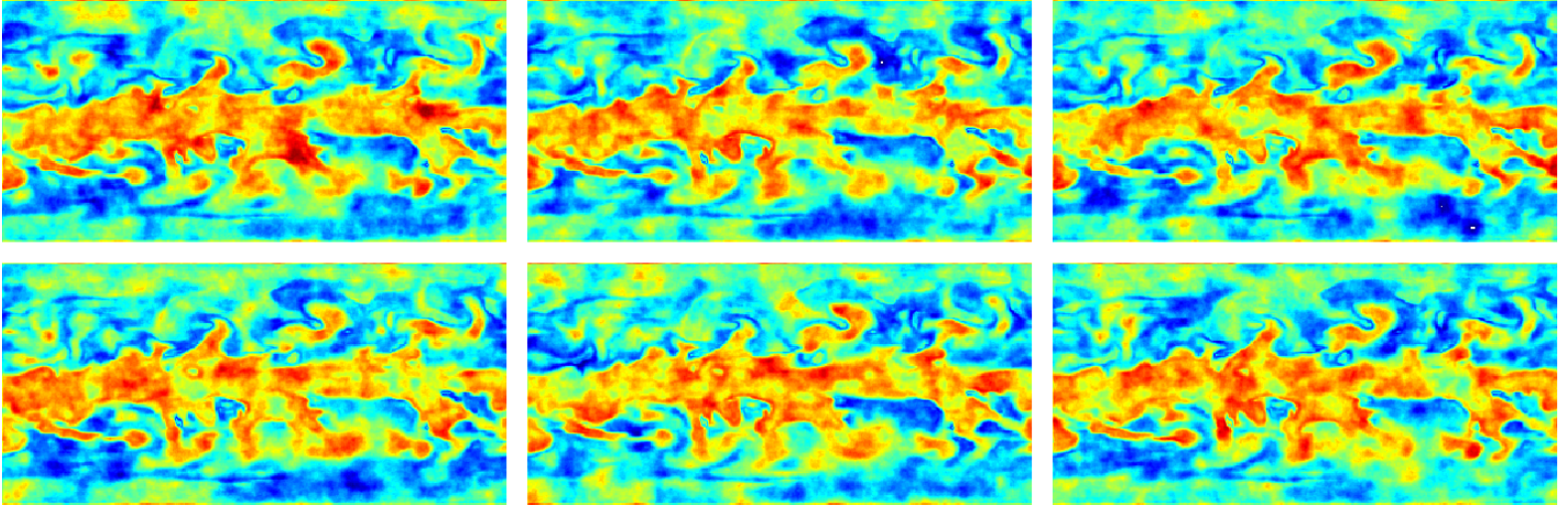


Middle layer of the atmosphere,  $\approx 200\text{km}$  resolution.  
(WET, DRY)

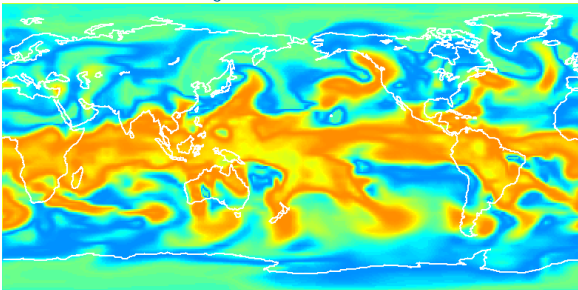
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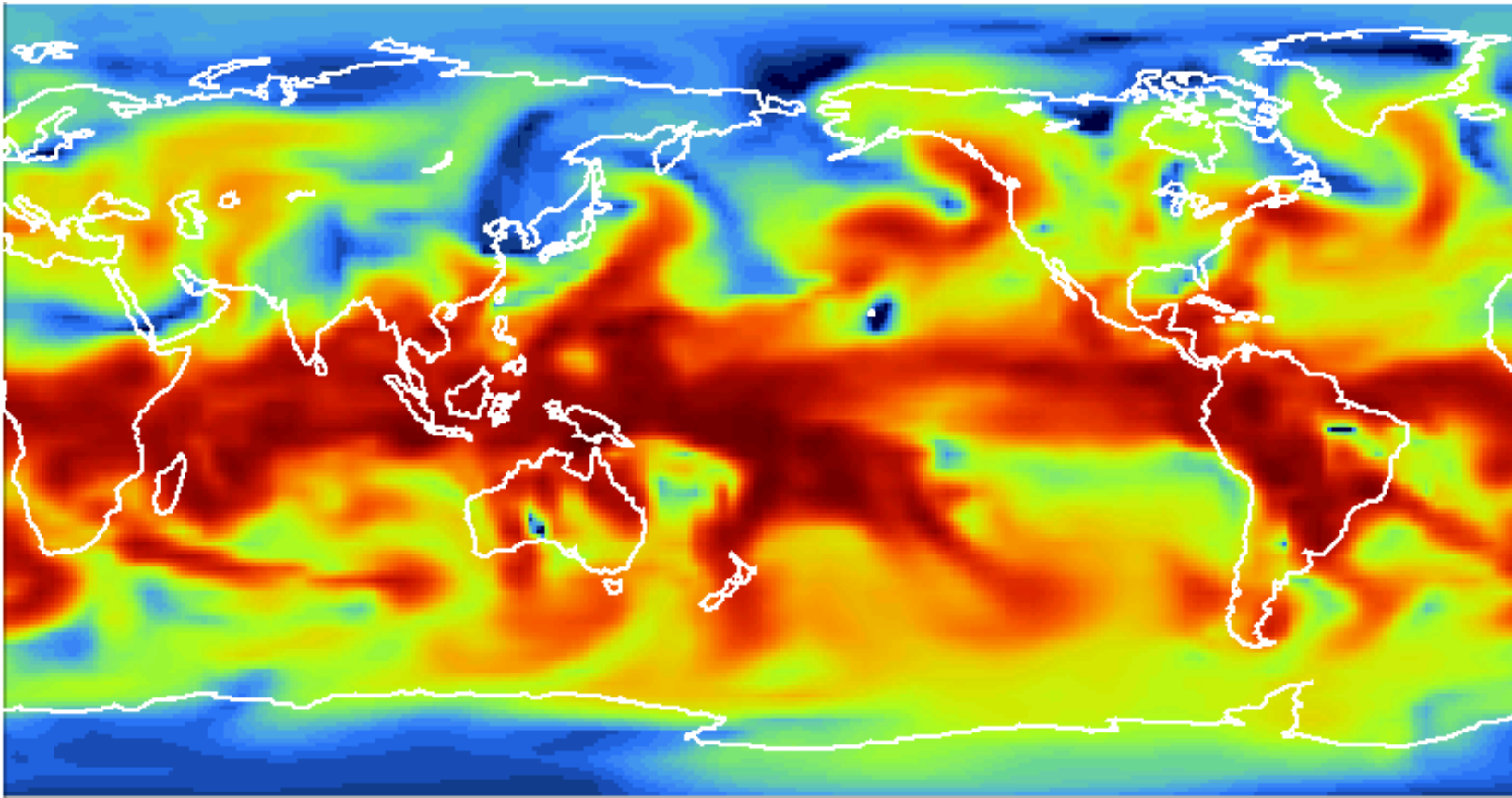


*The mean field*



# Assimilation of water vapor

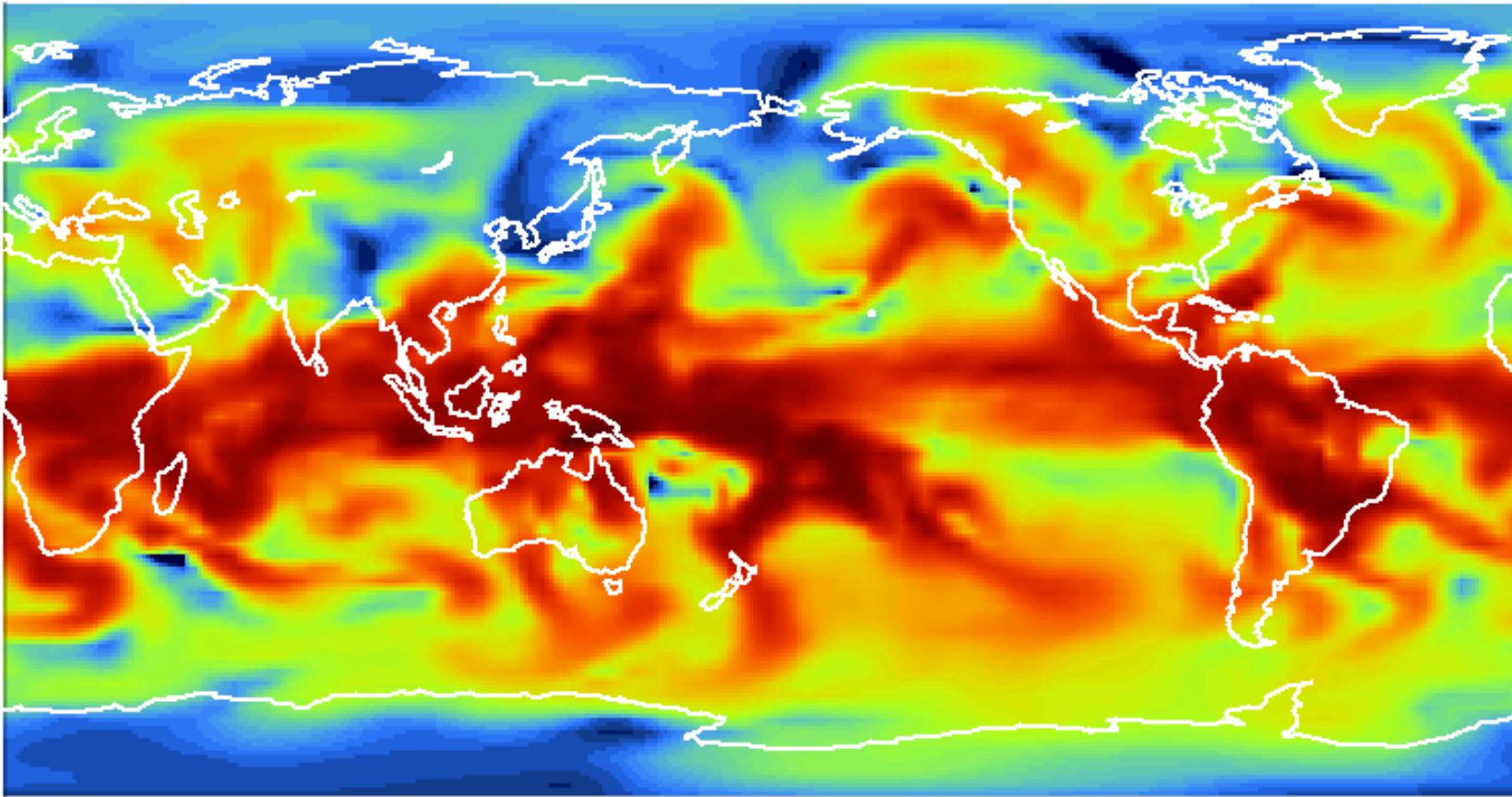
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(WET, DRY)

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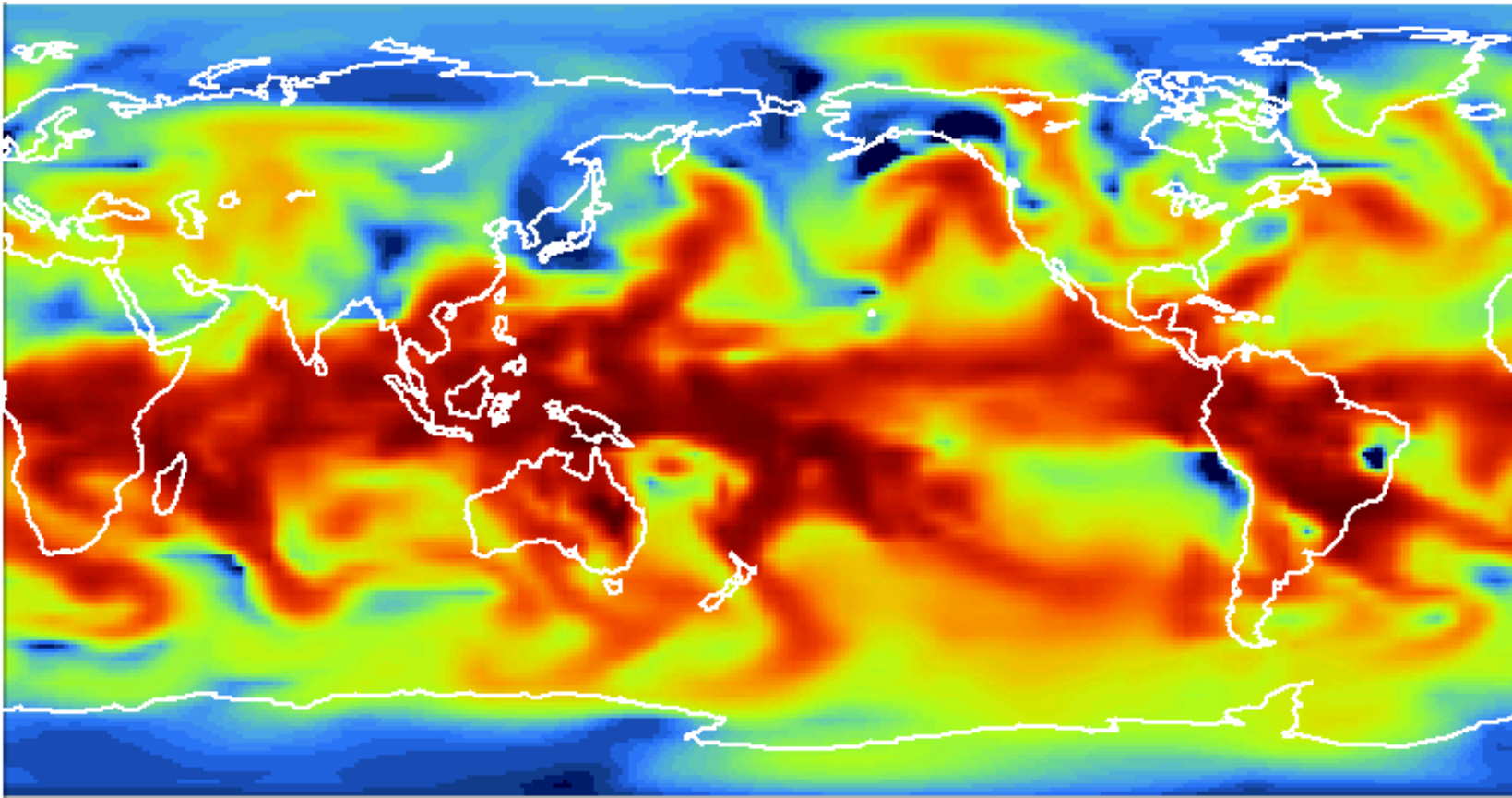
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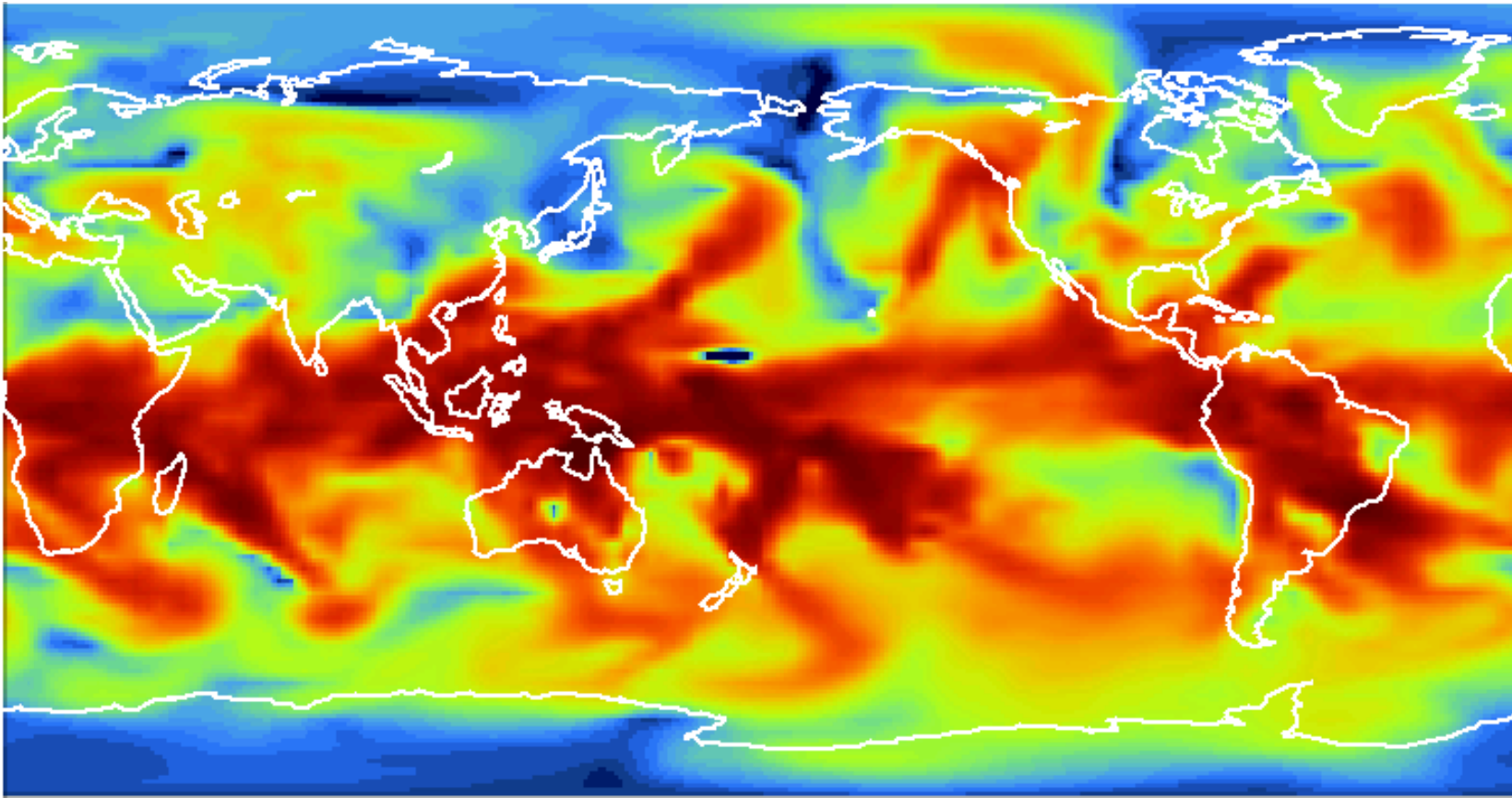


(WET, DRY)



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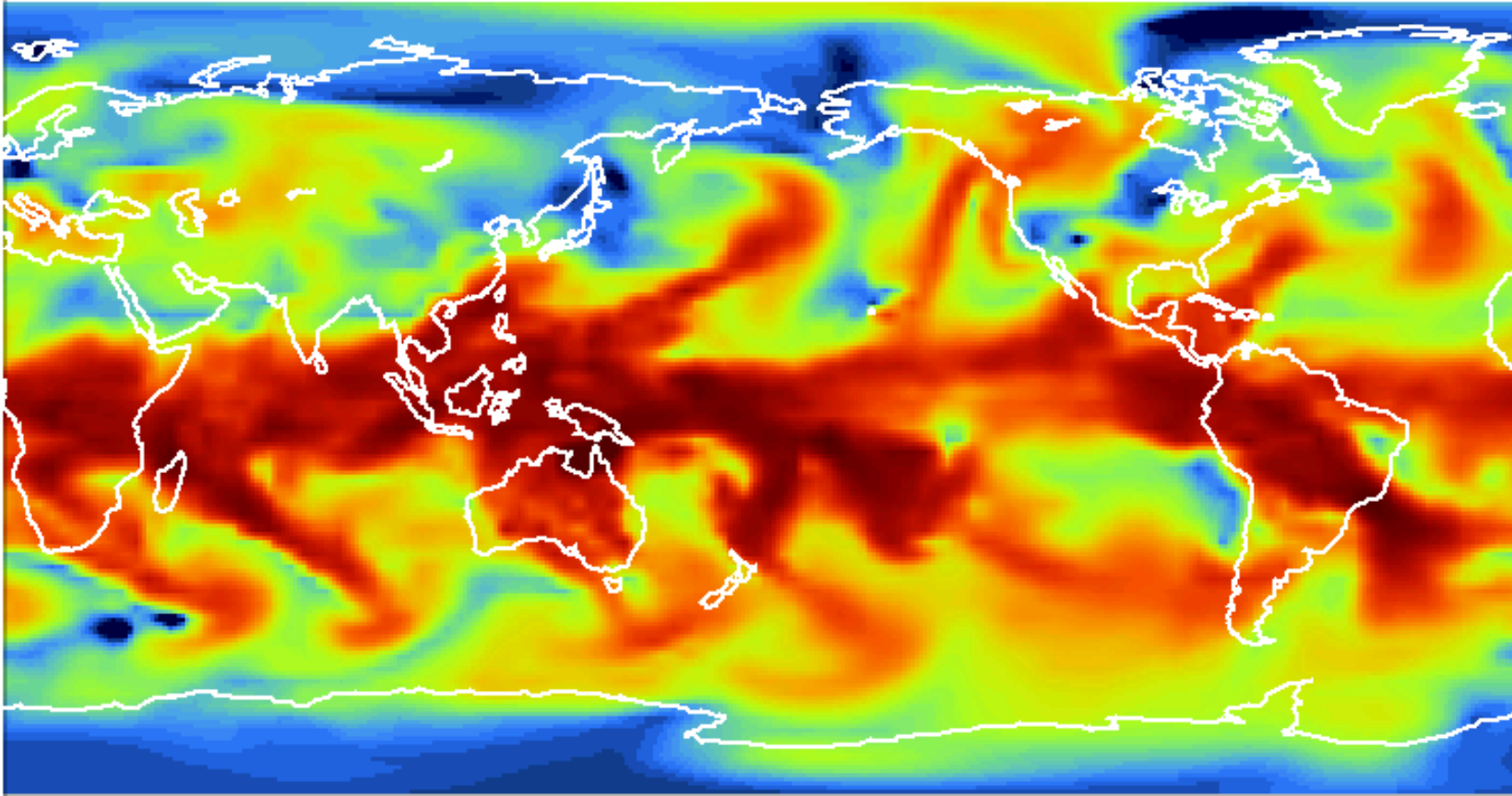
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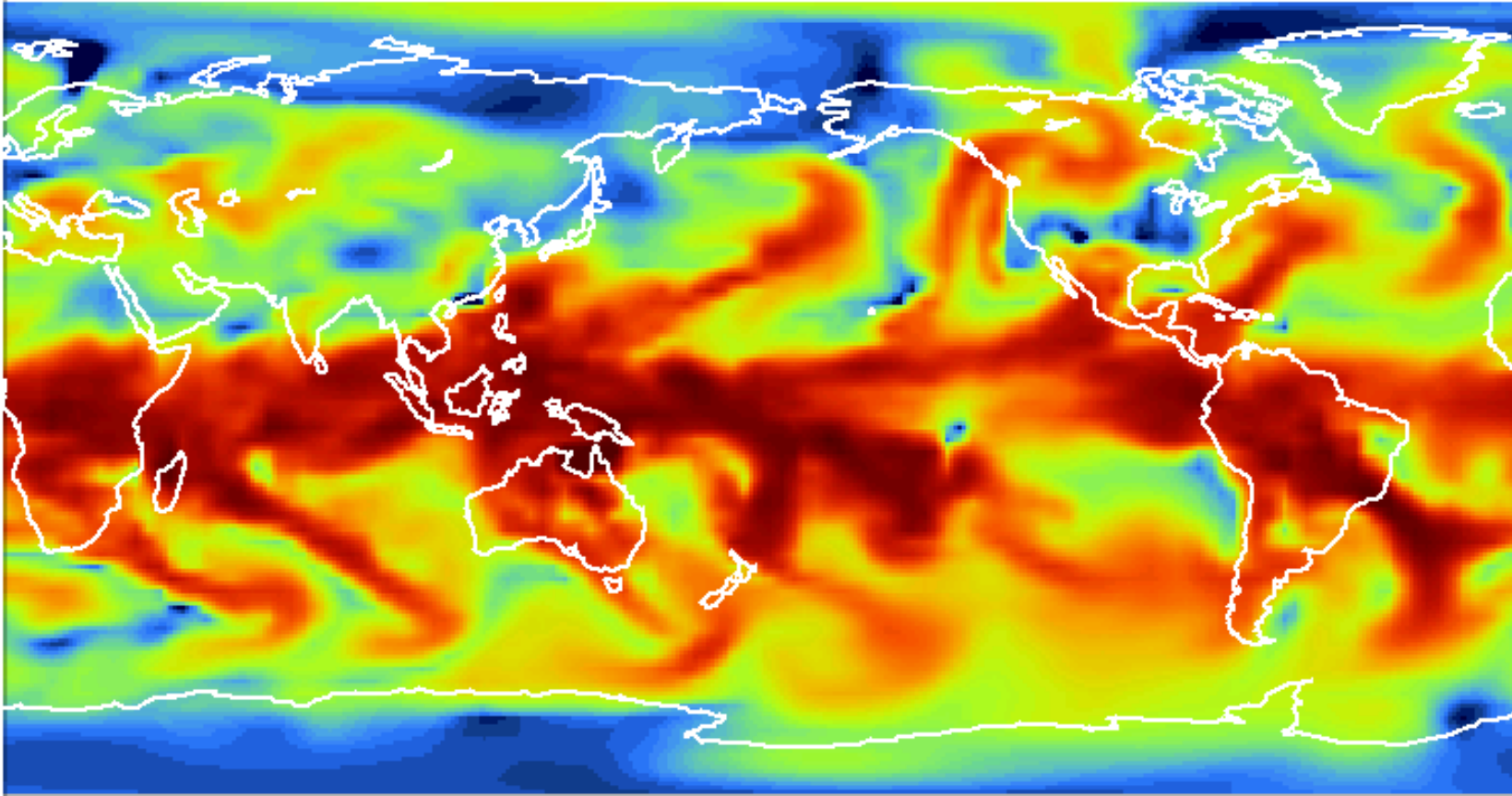
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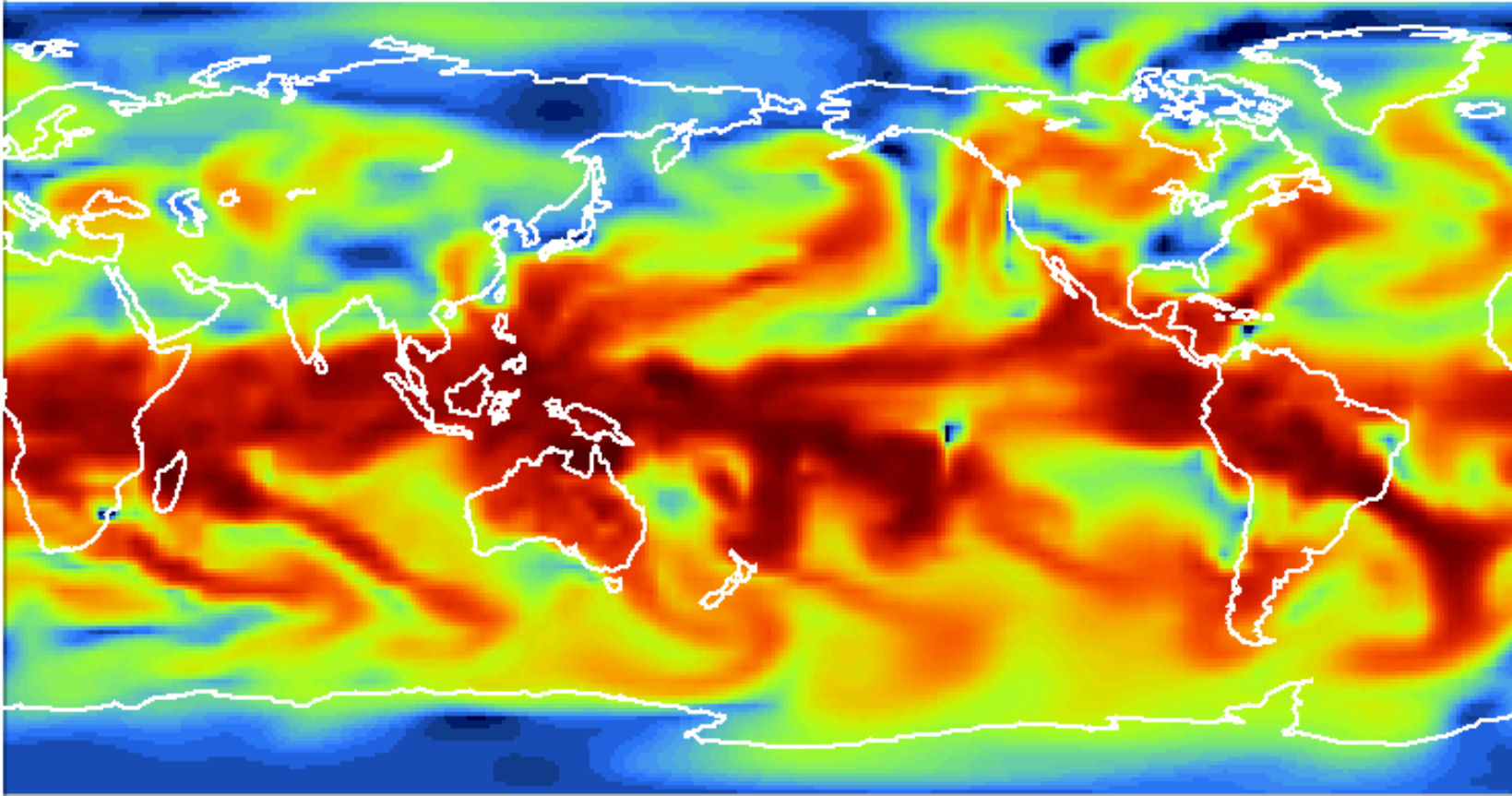
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(WET, DRY)

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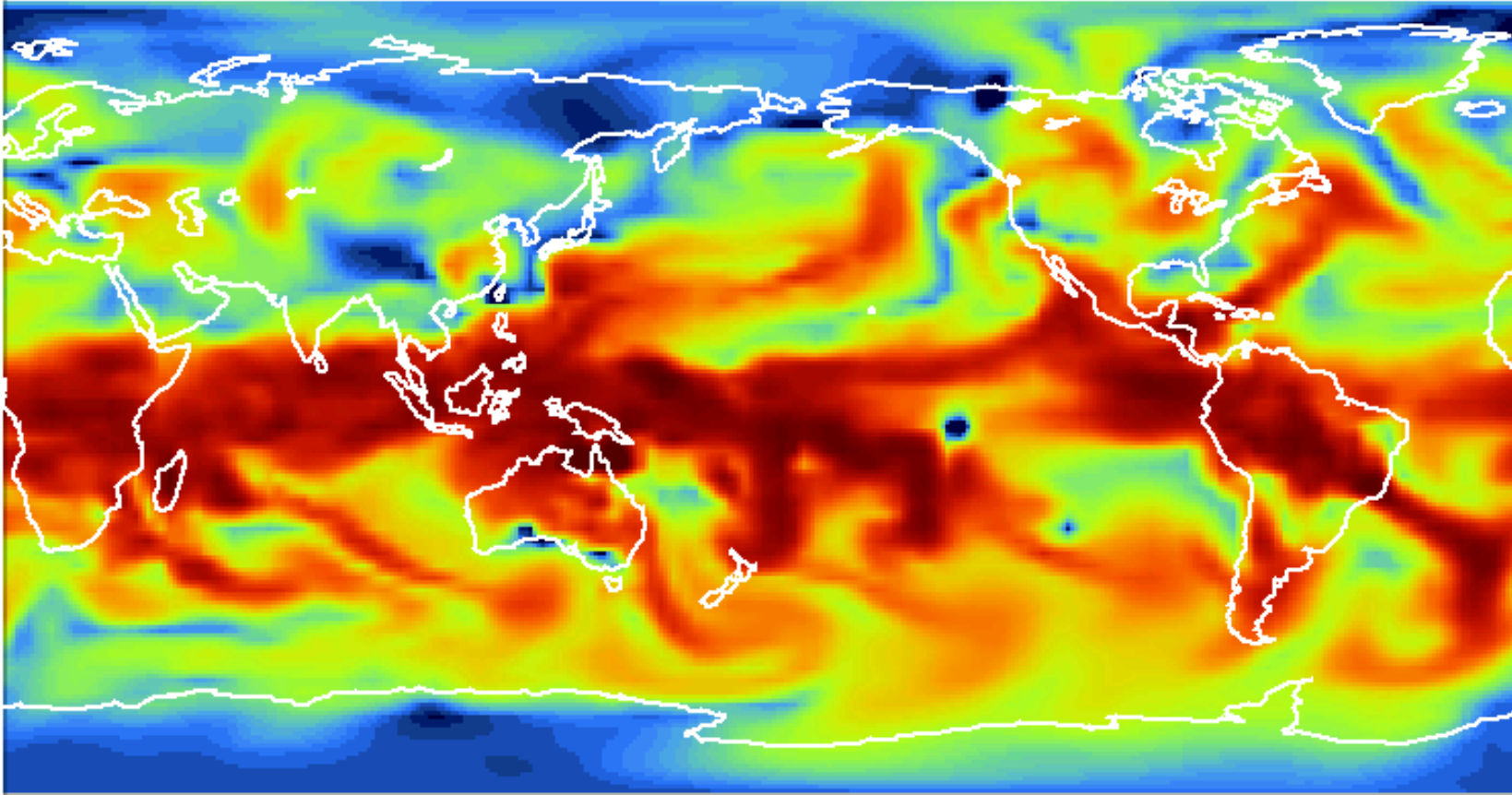
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(WET, DRY)

# Assimilation of water vapor – final

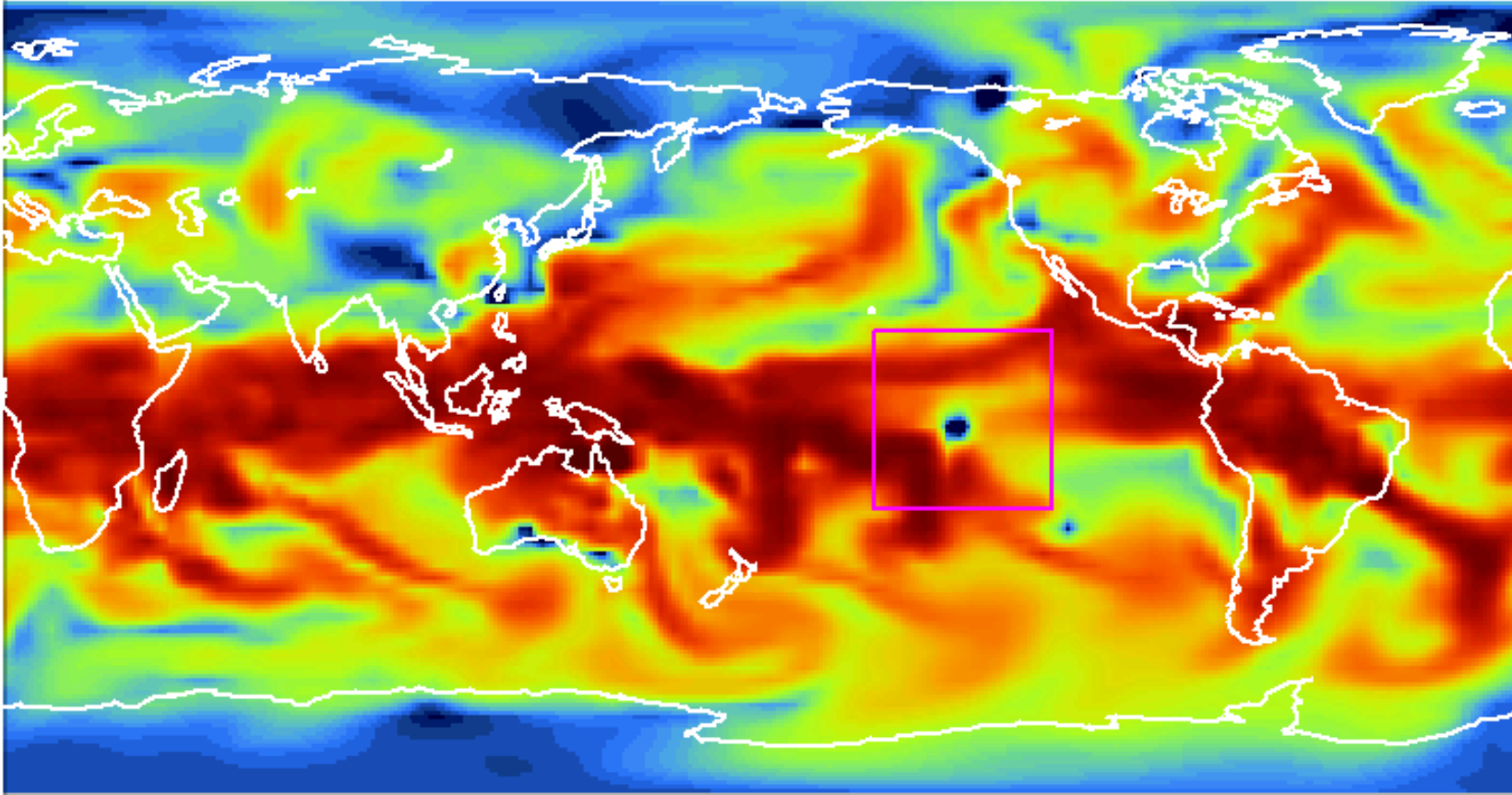
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(WET, DRY)

# Assimilation of water vapor: Robustness

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(WET, DRY)

# Robustness

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# Robustness

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*Key:*

Create a robust filter using the uncertainty from the ensemble spread to decide if a new observation is an outlier.



# The RIPS Project

---

*A robust ensemble filter for data assimilation: A forecasting system to handle outliers.*

- **Adapt the Ensemble Kalman Filter to detect and handle unusual, bad observations.**

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- *Have some fun!*