Conservative Finite Volume Schemes for Meteorological Applications

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Motivation

Balancing gravity

Momentum conservation vs. Coriolis

A low-Mach / low-Froude conservative scheme low Mach number Godunov-Type scheme robust, exact projection low-Froude extension



Scales in the Atmosphere

Three-dimensional compressible flow equations

$$\rho_{t} + \nabla \cdot (\rho \boldsymbol{v}) = 0$$

$$(\rho \boldsymbol{v})_{t} + \nabla \cdot (\rho \boldsymbol{v} \circ \boldsymbol{v}) + \frac{1}{\mathbf{M}^{2}} \nabla p + \frac{1}{\mathbf{Ro}} \boldsymbol{\Omega} \times \rho \boldsymbol{v} = \boldsymbol{S}_{\rho \boldsymbol{v}} - \frac{1}{\mathbf{Fr}^{2}} \rho g \boldsymbol{k}$$

$$(\rho e)_{t} + \nabla \cdot (\boldsymbol{v} [\rho e + p]) = S_{\rho e}$$

$$(\rho Y_{j})_{t} + \nabla \cdot (\rho Y_{j} \boldsymbol{v}) = S_{\rho Y_{j}}$$

$$(\rho e) = rac{p}{\gamma - 1} + rac{1}{2}
ho v^2 +
ho \sum_{j=1}^N Q_j Y_j$$

Many asymptotic regimes — a single numerical scheme?

The "Truth"

Why conservation?

The integral conservation law

$$\int_{\Omega} \Phi \, d\boldsymbol{x} \Big|_{t_1}^{t_2} = -\int_{t_1}^{t_2} \oint_{\partial\Omega} \boldsymbol{f}_{\Phi} \cdot \boldsymbol{n} \, d\sigma \, dt$$

is uniformly valid for arbitrary control volumes

 \downarrow

Mathematically sound subgrid closures

()

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Spurious winds over steep orography

- atmosphere at rest
- 3000 m mountain
- 3D compressible inviscid flow eqs.
- standard finite volume scheme
- 128×32 grid cells
- velocities after about 60 min

Various finite difference / finite volume schemes produce comparable results.



Accumulation of unbalanced truncation errors

- The background pressure / temperature structure of the atmosphere is (almost) everywhere dominated by hydrostatic balance.
- Mathematically, this follows from the distinguished limits

$$\mathbf{Fr}^2/\mathbf{M}^2 = O(1), \text{ Ro} \gg \mathbf{M}^2, \ (\mathbf{M} \to 0)$$

• Vertical momentum balance

$$(\rho w)_t + \nabla \cdot (\rho v w) + \frac{1}{\text{Ro}} \boldsymbol{k} \cdot (\boldsymbol{\Omega} \times \boldsymbol{v}) = -\left(\frac{1}{\mathbf{M}^2} \frac{\partial p}{\partial z} + \frac{1}{\mathbf{Fr}^2} \rho\right).$$

• Numerical truncation errors for 30 vertical layers, 2nd order scheme

$$(\delta w)_{\text{num.}} = O\left(\frac{1}{\mathbf{M}^2}\Delta x^2\right) \sim \frac{(1/30)^2}{(0.03)^2} \sim O(1)$$

Origin of unbalanced truncation errors



Archimedes' principle



Archimedes' principle

Piecewise linear potential temperature



No accumulation of unbalanced truncation errors

Inversion layers at a mid-mountain level



No accumulation of unbalanced truncation errors



N. Botta, et al.: Well-Balanced Finite Volume Methods for Near-Hydrostatic Flows, JCP, (2004)

Convergence vs. marginal resolution (Schaer's Test)

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 $2 \boldsymbol{\Omega} \times \rho \boldsymbol{v}$

is the result of a coordinate transformation.

Standard numerical discretizations do not maintain momentum conservation.

Idea: Apply coordinate transformation to **conservative moving grid discretization** in the inertial frame.

 $2 \boldsymbol{\Omega} \times \rho \boldsymbol{v} \Rightarrow \text{rotationterm} + \text{fluxterm}$

(work in progress with **E. Audusse**)



Shallow water version (1st order)

$$h_i^{n+1} = h_i^n - \frac{\Delta t}{|C_i|} \sum_j F_{ij}^h$$

$$\boldsymbol{q}_{i}^{n+1} = \underline{R(\Delta t)\boldsymbol{q}_{i}^{n}} - h_{i}^{n+1}\boldsymbol{\Omega} \times \boldsymbol{x}_{i} + h_{i}^{n}R(\Delta t)\boldsymbol{\Omega} \times \boldsymbol{x}_{i}$$

$$-\frac{\Delta t}{|C_i|} \sum_{j} \boldsymbol{F}_{ij}^{q} \\ -\frac{\Delta t}{|C_i|} \sum_{j} \left(F_{ij}^h \boldsymbol{\Omega} \times \boldsymbol{x}_{ij} \right)$$





Water height for stationary vortex test:

Top: Cross-wind scheme, Bottom: Standard scheme left to right: 20 cells horizontal / 20, 40, 80 cells in the vertical



Water height for stationary vortex test:

Top: Vertical cross section, Bottom: Horizontal cross section left to right: 20 cells horizontal / 20, 40, 80 cells in the vertical initial data, cross-wind scheme, standard scheme

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Three zero Mach number, anelastic regimes:

- 1. Inkompressible flow (no gravity)
- 2. Ogura-Phillips-Anelastic flow ($\theta = \mathbf{1} + \mathbf{M}^2 \theta'$)
- 3. Buoyancy-controlled flow $(\theta = \Theta_0(z) + \mathbf{M}^2 \theta')$

Regime 1: Incompressible flow

Leading order result:

$$p = P_{\infty} + \boldsymbol{\varepsilon}^4 \boldsymbol{p'}$$

Consequences:

$$\rho e = \frac{p}{\gamma - 1} + \boldsymbol{\varepsilon}^4 \frac{\rho \boldsymbol{v}^2}{2} \rightarrow \frac{P_{\infty}}{\gamma - 1} \qquad (\boldsymbol{\varepsilon} \rightarrow 0)$$

$$(\rho e)_t + \nabla \cdot ([\rho e + p] \boldsymbol{v}) = 0 \qquad \rightarrow \qquad \nabla \cdot \boldsymbol{v}^{(0)} = 0$$

$$(\rho \boldsymbol{v})_t + \nabla \cdot (\rho \boldsymbol{v} \circ \boldsymbol{v}) + \frac{1}{\boldsymbol{\varepsilon}^4} \nabla p = 0 \qquad \rightarrow \qquad (\rho \boldsymbol{v})_t^{(0)} + \nabla \cdot (\rho \boldsymbol{v} \circ \boldsymbol{v})^{(0)} + \nabla \boldsymbol{p'} = 0$$

 $\rho_t^{(0)} + \boldsymbol{v}^{(0)} \cdot \nabla \rho^{(0)} = 0$

Anelastic limits

Task:

Construct a scheme for low Mach number flows, which ...

- conserves mass, momentum, and total energy,
- is at least second order accurate in space and time,
- requires the solution of at most linear, scalar equations (possibly a few of them per time step)
- reduces, for M = 0, to the variable density, incompressible solver in Schneider et al., JCP, (1999)
- reduces, for M = 1, to a second order Godunov-type scheme

Conservative Low Mach Numerics

Explicit / implicit split for the Euler equations (R.K., JCP (1995); M. Minion & R.K, (2005))

$$\rho_t + \nabla \cdot (\rho \boldsymbol{v}) = 0$$

$$(\rho \boldsymbol{v})_t + \nabla \cdot (\rho \boldsymbol{v} \circ \boldsymbol{v}) + \nabla p + \left(\frac{1}{\mathbf{M}^2} - 1\right) \nabla \boldsymbol{p}_* = 0$$

$$(\rho e)_t + \nabla \cdot ([\rho e + \boldsymbol{\pi}] \boldsymbol{v}) = 0$$

$$\rho e = \frac{p}{\gamma - 1} + \mathbf{M}^2 \frac{\rho \mathbf{v}^2}{2}$$
$$\boldsymbol{\pi} = (1 - \mathbf{M}^2) \mathbf{p}_* + \mathbf{M}^2 p$$

Conservative Low Mach Numerics

Energy balance (Divergence correction for energy fluxes)

$$\mathbf{M}^{2} \left(\frac{1}{\Delta t} \left[\frac{\delta \boldsymbol{p_{*}}'}{\gamma - 1} + \left(\frac{\rho \boldsymbol{v}^{2}}{2} \right) \right]_{n}^{**} - \boldsymbol{v}^{**} \cdot \tilde{\nabla} \delta \boldsymbol{p_{*}}' \right] + (1 - \mathbf{M}^{2}) \tilde{\nabla} \cdot (\delta \boldsymbol{p_{*}}' \boldsymbol{v}^{**}) \right)$$
$$= -\left(\tilde{\nabla} \cdot (\rho h^{*} \boldsymbol{v}^{**}) - \frac{\Delta t}{2} \tilde{\nabla} \cdot (h^{*} \tilde{\nabla} \delta \boldsymbol{p}) \right)$$

 $\mathbf{M} = 0 \Rightarrow$ classical **linear** projection step

 $\mathbf{M} \ll 1 \Rightarrow$ linear, non-singular inclusion of weak compressibility

Conservative Low Mach Numerics

Advected homentropic vortex at M = 0.2



Convergence rates:
$${m v}
ightarrow h^2$$
 , $p
ightarrow h^{1.5}$, $ho
ightarrow h^1$

Low Mach number Godunov-Type scheme – Results

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low Mach number Godunov-Type scheme robust, exact projection

low-Froude extension

Second projection: discrete approximations of $\nabla \cdot \left(\frac{1}{\rho} \nabla p\right) = r$

Finite elements (with test functions ϕ_{ν}):

$$\forall \boldsymbol{\nu} : \int \left[\frac{1}{\rho} \nabla p \cdot \nabla \phi_{\boldsymbol{\nu}} - r \, \phi_{\boldsymbol{\nu}} \right] \, dx = 0$$
$$\overline{\boldsymbol{C}}_{i,j}$$

where

$$p(x,y) = \sum_{\mu} \hat{p}_{\mu} \phi_{\mu}$$

Finite volumes on dual cells

$$\oint_{\partial \overline{C}_{i,j}} \frac{1}{\rho} \nabla p \cdot \boldsymbol{n} \ d\sigma \ - \int_{\overline{C}_{i,j}} r \ dx = 0$$



Bilinear pressure distributions: FE vs. FV stencil

Example: (robust, second order)* stencils for $\Delta p = \nabla \cdot \nabla p$





Conforming **finite elements**

Finite volumes on dual cells:

* E. Süli: SIAM J. Num. Analysis, 28(5):1419-1430, 1991.

Bilinear pressure distributions: FE vs. FV stencil

Cell averaged updates

$$(\rho \boldsymbol{v})_{i,j}^{n+1} = (\rho \boldsymbol{v})_{i,j}^* - \Delta t \, \left(\begin{array}{c} \left(\partial_x p^{(2)} \right)_{i,j} \\ \left(\partial_y p^{(2)} \right)_{i,j} \end{array} \right)$$



conservative gradient approximation, e.g.,

$$\left(\partial_x p^{(2)}\right)_{i,j} \approx \frac{1}{2\Delta x} \left(\left[p_{i+\frac{1}{2},j+\frac{1}{2}} + p_{i+\frac{1}{2},j-\frac{1}{2}} \right] - \left[p_{i-\frac{1}{2},j+\frac{1}{2}} + p_{i-\frac{1}{2},j-\frac{1}{2}} \right] \right)$$

Bilinear pressure distributions: FV momentum updates

Local updates within cells $C_{i,j}$:

$$(\rho \boldsymbol{v})^{n+1}(x,y) = (\rho \boldsymbol{v})^*(x,y) - \Delta t \,\nabla p^{(2)}(x,y)$$

where

$$\nabla p^{(2)}(x,y)\Big|_{i,j} = \left(\begin{array}{c} \left(\partial_x p^{(2)}\right)_{i,j} + (y-y_j) \left(\partial_{xy}^2 p^{(2)}\right)_{i,j} \\ \left(\partial_y p^{(2)}\right)_{i,j} + (x-x_i) \left(\partial_{xy}^2 p^{(2)}\right)_{i,j} \end{array} \right)$$

Second projection modifies piecewise linear reconstruction:

$$\left(\partial_{x}(\rho v) \right)_{i,j}^{n+1} = \left(\partial_{x}(\rho v) \right)_{i,j}^{*} - \Delta t \left(\partial_{xy}^{2} p^{(2)} \right)_{i,j}$$
$$\left(\partial_{y}(\rho u) \right)_{i,j}^{n+1} = \left(\partial_{y}(\rho u) \right)_{i,j}^{*} - \Delta t \left(\partial_{xy}^{2} p^{(2)} \right)_{i,j}$$

Bilinear pressure distributions: FV momentum updates

Exact projection achieved with:

$$\left(\nabla \cdot \boldsymbol{u}\right)_{i,j}^{n+1} = \frac{1}{\left|\boldsymbol{\partial} \overline{\boldsymbol{C}}_{i,j}\right|} \oint_{\boldsymbol{\partial} \overline{\boldsymbol{C}}_{i,j}} \left(\frac{1}{\rho} \boldsymbol{m}\right)^{n+1} \cdot \boldsymbol{n} \ d\sigma$$

where

$$\boldsymbol{m}^{n+1}(x,y) \Big|_{i,j} = \begin{pmatrix} (\rho u)_{i,j}^{n+1} + (x-x_i) & (\partial_x(\rho u))_{i,j}^* & + (y-y_j) & (\partial_y(\rho u))_{i,j}^{n+1} \\ (\rho v)_{i,j}^{n+1} + (x-x_i) & (\partial_x(\rho v))_{i,j}^{n+1} & + (y-y_j) & (\partial_y(\rho v))_{i,j}^* \end{pmatrix}$$

Bilinear pressure distributions: Exact projection

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low Mach number Godunov-Type scheme robust, exact projection **low-Froude extension**

Regime 3: Buoyancy-controlled anelastic flow $\theta = \Theta_0(z) + \mathbf{M}^2 \theta'$

Leading order results:

 $p = P_0(z) + M^2 p'$ $\rho = R_0(z) + M^2 \rho'$ $R_0(z) = \Theta_0(z) P_0(z)^{1/\gamma}$

Consequences:

$$\rho e = \frac{p}{\gamma - 1} + \mathbf{M}^2 \frac{\rho \mathbf{v}^2}{2} + \rho g z \rightarrow \frac{\mathbf{P}_0(z)}{\gamma - 1} + R_0(z) g z \qquad (\mathbf{M} \to 0)$$

$$(\rho e)_t + \nabla \cdot ([\rho e + p] \boldsymbol{v}) = 0 \qquad \rightarrow \qquad \nabla \cdot \left(\boldsymbol{v}^{(0)} R_0(z) \left[\frac{\gamma}{\gamma - 1} \frac{\boldsymbol{P}_0}{R_0}(z) + gz \right] \right) = 0$$

 $\rho_t + \nabla \cdot (\rho \boldsymbol{v}) = 0 \qquad \rightarrow \qquad \nabla \cdot \left(\boldsymbol{v}^{(0)} R_0(z) \right) = 0$

Unfortunately

$$\left[\frac{\gamma}{\gamma-1}\frac{\boldsymbol{P_0}}{R_0} + gz\right] \equiv \boldsymbol{\Phi}(\boldsymbol{z}) \neq \text{const.} \quad \Rightarrow \quad \nabla_{||} \cdot \boldsymbol{u}^{(0)} = 0, \quad \text{and} \quad w^{(0)} = 0$$

Anelastic limits

Regime 3: Buoyancy-controlled anelastic flow $\theta = \Theta_0(z) + \mathbf{M}^2 \theta'$

Leading order results:

 $p = P_0(z) + M^2 p'$ $\rho = R_0(z) + M^2 \rho'$ $R_0(z) = \Theta_0(z) P_0(z)^{1/\gamma}$

Consequences (cont'd):

$$(\rho \boldsymbol{v})_t + \nabla \cdot (\rho \boldsymbol{v} \circ \boldsymbol{v}) + \frac{1}{\mathbf{M}^2} (\nabla p + \rho g) = 0 \quad \rightarrow \quad (\rho \boldsymbol{v})_t^{(0)} + \nabla \cdot (\rho \boldsymbol{v} \circ \boldsymbol{v})^{(0)} + (\nabla \boldsymbol{p'} + \boldsymbol{\rho'}) = 0$$

 $(P_0, \Theta_0, p', \rho')$ must be maintained as primary variables in a numerical implementation

Generalization to anelastic regimes:

Energy balance (Divergence correction for energy fluxes)

$$\mathbf{M}^{2} \left(\frac{1}{\Delta t} \left[\frac{\delta \boldsymbol{p_{*}}'}{\gamma - 1} + \left(\frac{\rho \boldsymbol{v}^{2}}{2} \right) \Big|_{n}^{**} - \Delta t \, \boldsymbol{v}^{**} \cdot \tilde{\nabla} \delta \boldsymbol{p_{*}}' \right] + (1 - \mathbf{M}^{2}) \tilde{\nabla} \cdot (\delta \boldsymbol{p_{*}}' \, \boldsymbol{v}^{**}) \right)$$
$$= -\left(\tilde{\nabla} \cdot (\rho h^{*} \, \boldsymbol{v}^{**}) - \frac{\Delta t}{2} \tilde{\nabla} \cdot (h^{*} \left[\tilde{\nabla} \delta \boldsymbol{p_{*}}' + \delta \boldsymbol{\rho_{*}}' \boldsymbol{k} \right]) \right)$$

Mass balance (Divergence correction for mass fluxes)

$$\frac{\mathbf{M}^2}{\Delta t} \delta \boldsymbol{\rho_*}' = -\left(\tilde{\nabla} \cdot (\boldsymbol{\rho^*} \, \boldsymbol{v^{**}}) - \frac{\Delta t}{2} \, \tilde{\nabla} \cdot (\left[\tilde{\nabla} \delta \boldsymbol{p_*}' + \delta \boldsymbol{\rho_*}' \boldsymbol{k} \right]) \right)$$

Anelastic limits

Potential Temperature:



Rising thermal plume ($\delta\theta/\theta = 0.1$) in a 10 km neutral atmosphere



An example

Conclusions