Modeling sea ice as a granular material, including dilatancy effect

Bruno Tremblay

Lamont Doherty Earth Observatory

Outline

- Introduction Different Approach to Sea Ice Modeling
- Observations
- Granular Model
- Model Against Observations?

Model Against Observations... continued

Momentum Equation

$$\rho h \frac{du}{dt} = \tau_a + \tau_w - \rho h f k \times u - \rho g h \nabla H + \nabla \cdot \sigma$$

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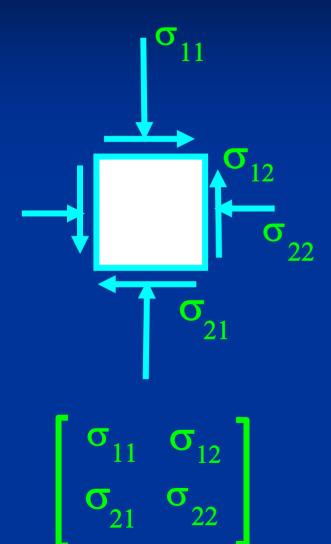
Internal ice stress term

Modeling sea ice

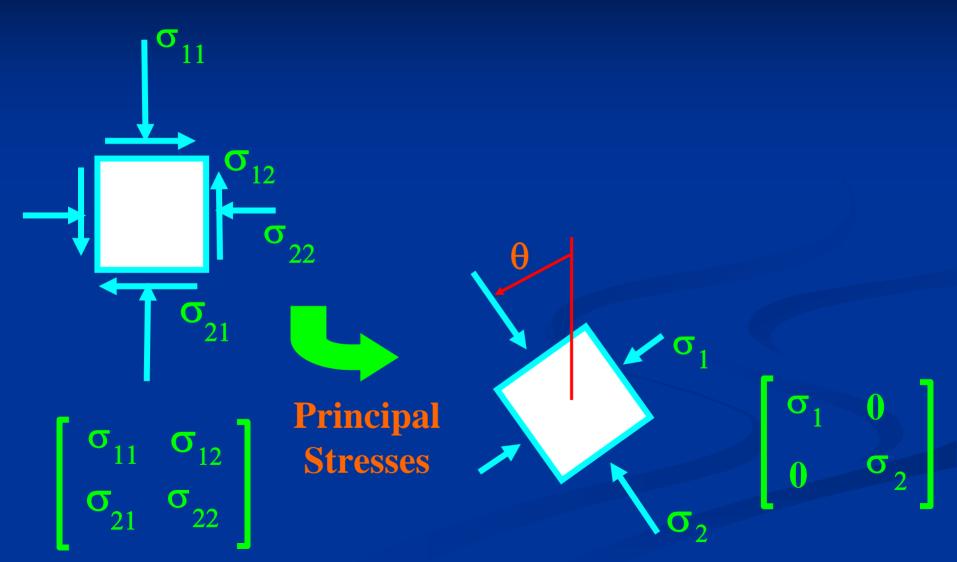
Deformation

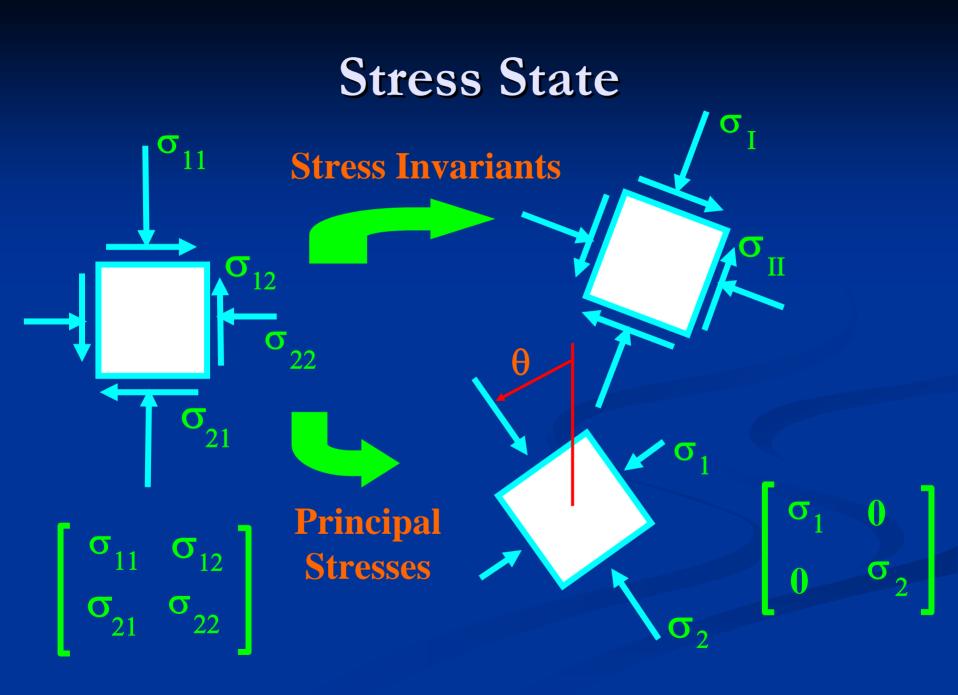
■ Elastic: small, reversible ■ Plastic: large, irreversible Elastic-Plastic (EP) [1974] ■ Viscous-Plastic (VP) [1979] Elastic-Viscous-Plastic (EVP) [1998] Granular material model VP [1997] ■ yield curve + flow rule

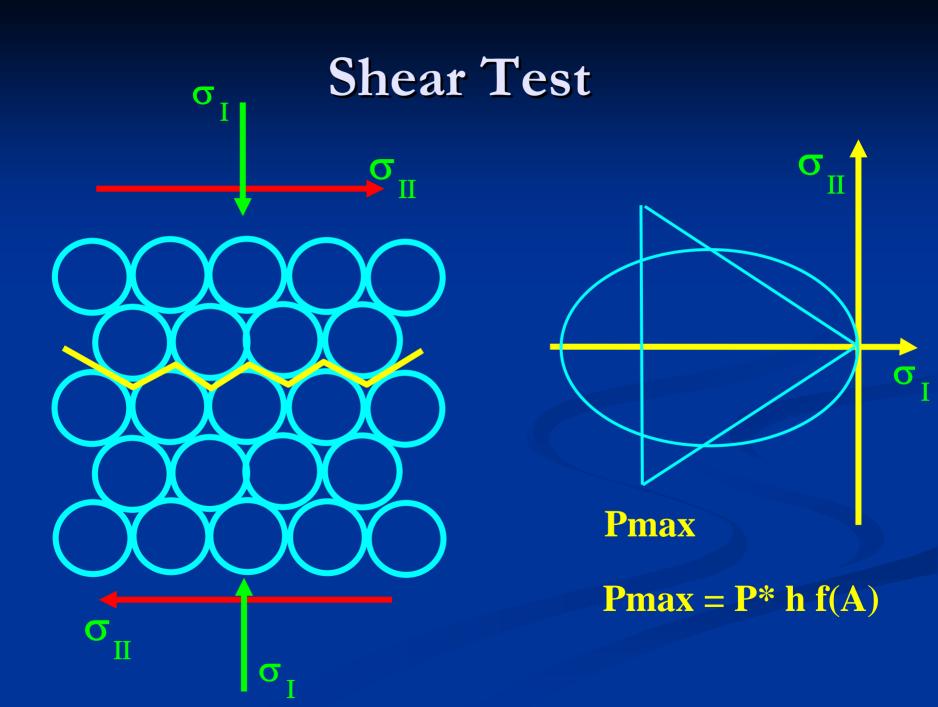




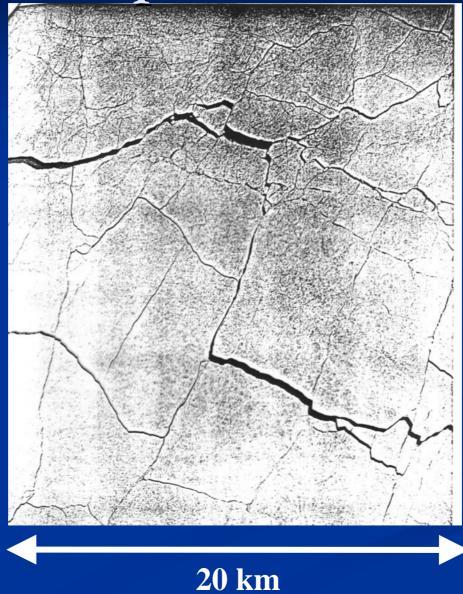
Stress State



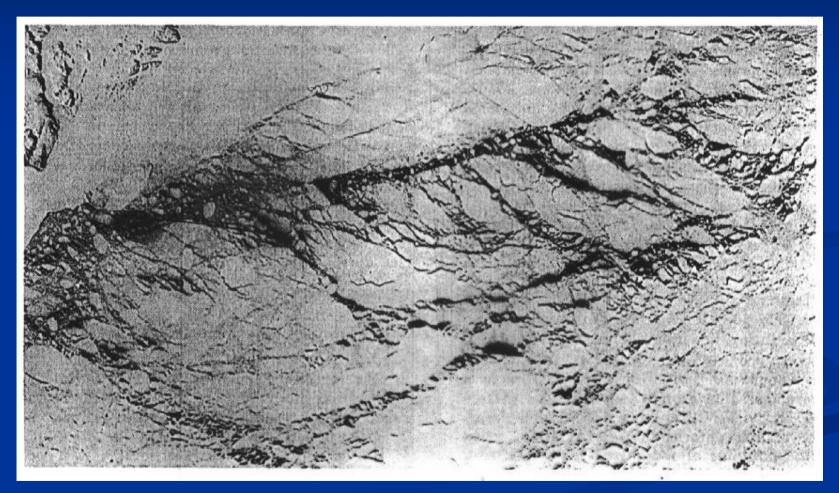




Fracture pattern in sea ice



Fracture pattern in sea ice



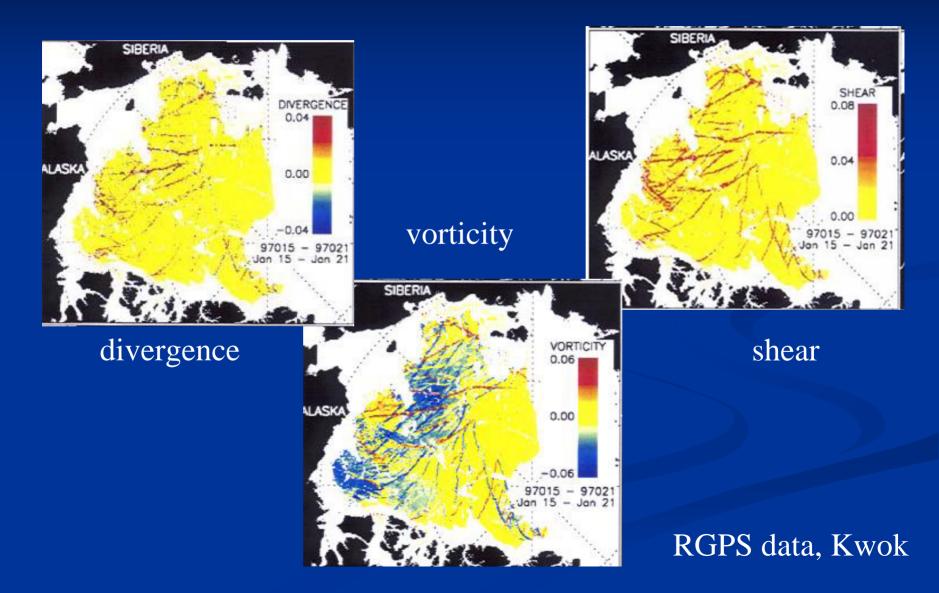
Scale: 200km

Lead pattern north of Greenland

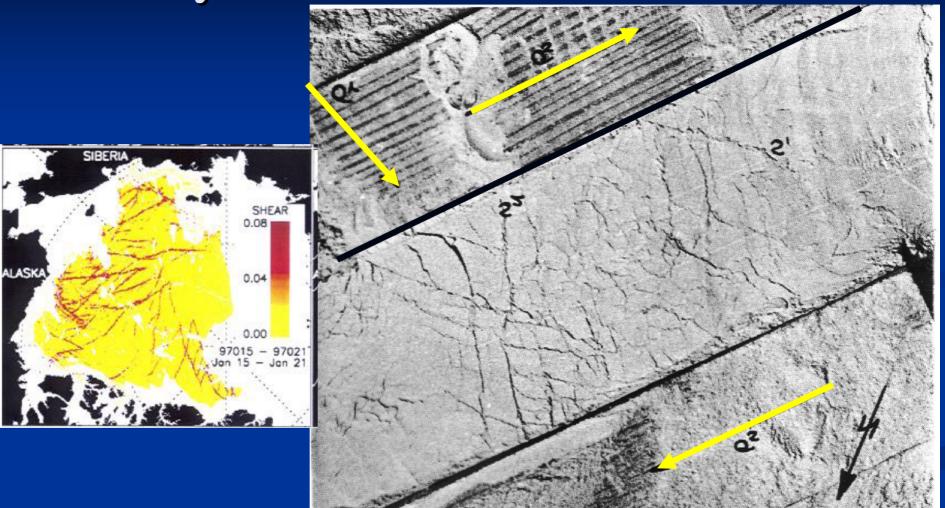


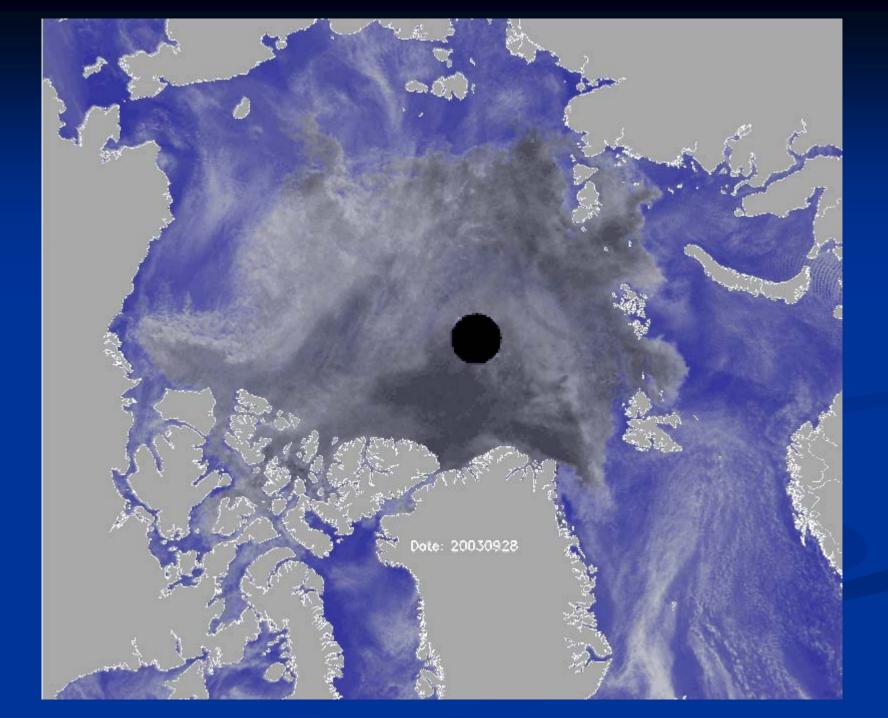
Scale: 500km

Sea ice deformation



Clay under shear deformation

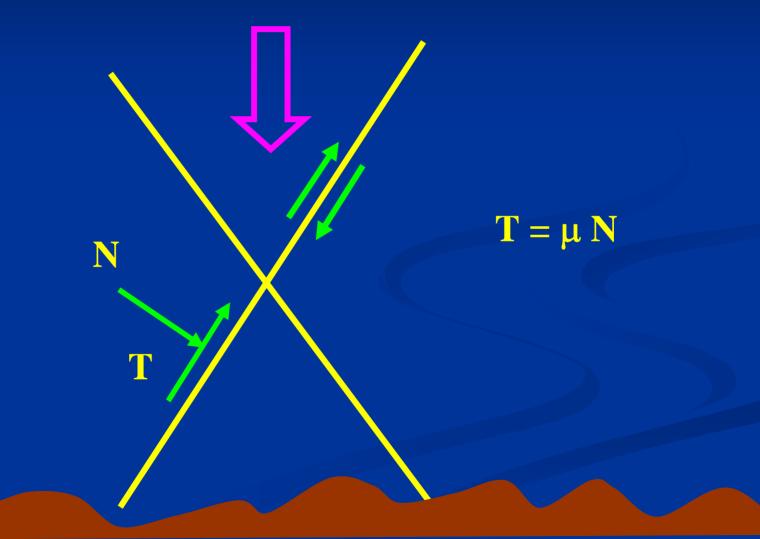




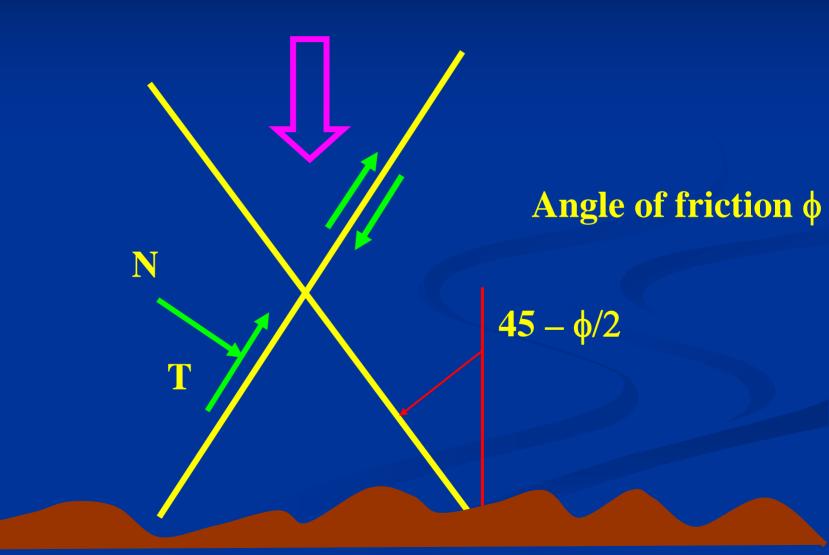
Compression test on concrete



The Model



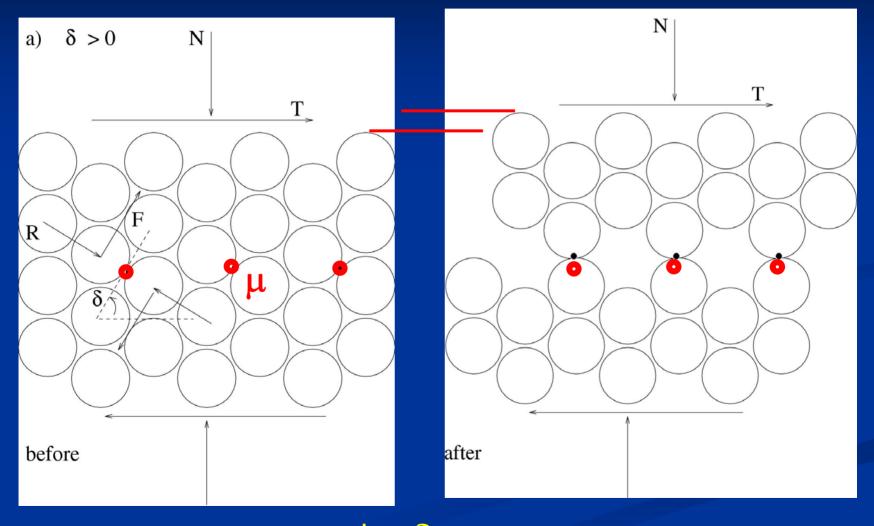
The Model



Summary

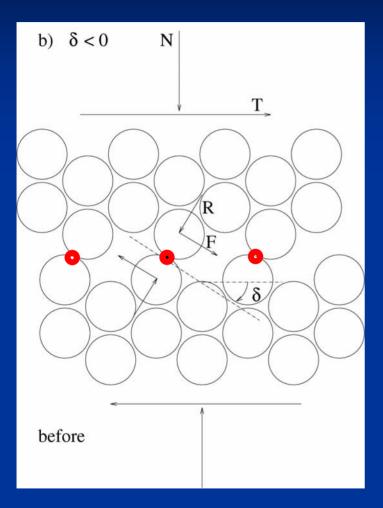
- You identify fracture patterns from satellite pictures
- You calculate the angle of friction from the fracture patterns
- You stick that into the model
- ... and then the model tends to produce to fast ice drifts...

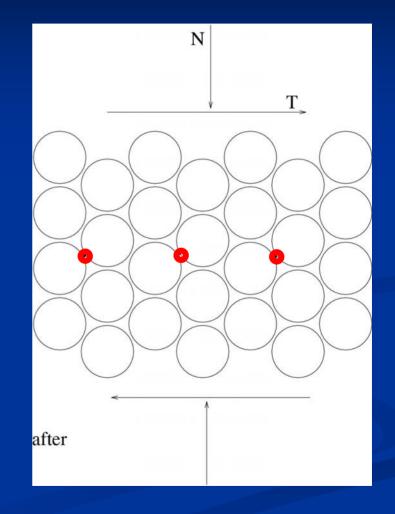
Dilatation δ



 $\phi = \delta + \mu$

Dilatation





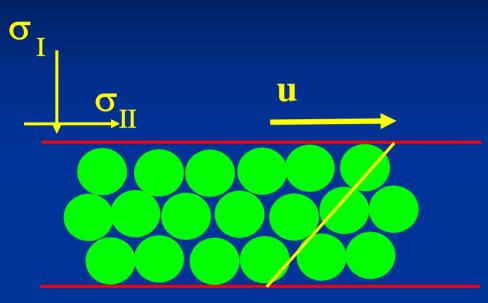
Rheology

$$\sigma_{ij} = -p\delta_{ij} - \eta \dot{\epsilon}_{kk} \delta_{ij} + 2\eta \dot{\epsilon}_{i,j},$$

$$\eta = \min\left(\frac{p \sin\phi}{\sqrt{(\dot{\boldsymbol{\epsilon}}_{11} - \dot{\boldsymbol{\epsilon}}_{22})^2 + 4\dot{\boldsymbol{\epsilon}}_{12}^2}}, \eta_{\max}\right)$$

0

Or... in 1-D



 $\tau = \mu \ du/dy$

U

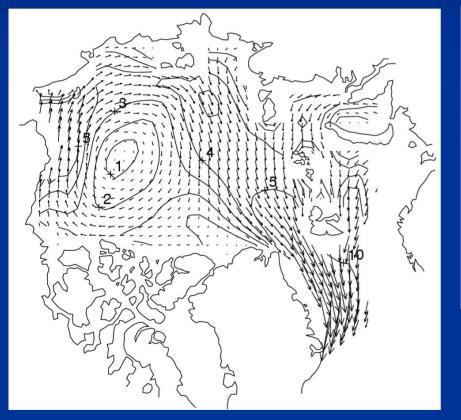
Fluid

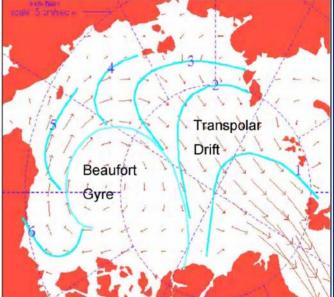
 $\sigma_{II} = \frac{\mu \sigma_{I}}{du/dy}$

Comparison with data?

Sea ice drift
Sea ice thickness/extent
Shear lines

Mean sea ice drift

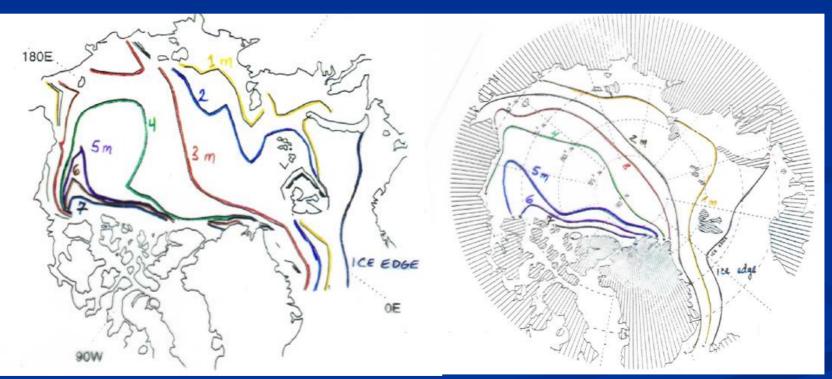




Sea ice thickness

simulated

observed

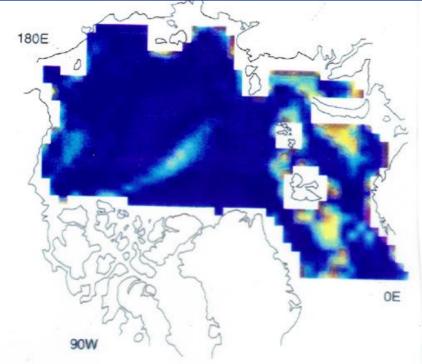


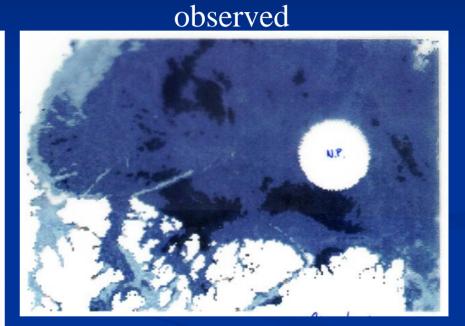
Tremblay Mysak 1997

Bourke Garrett, 1986

Shear lines

simulated

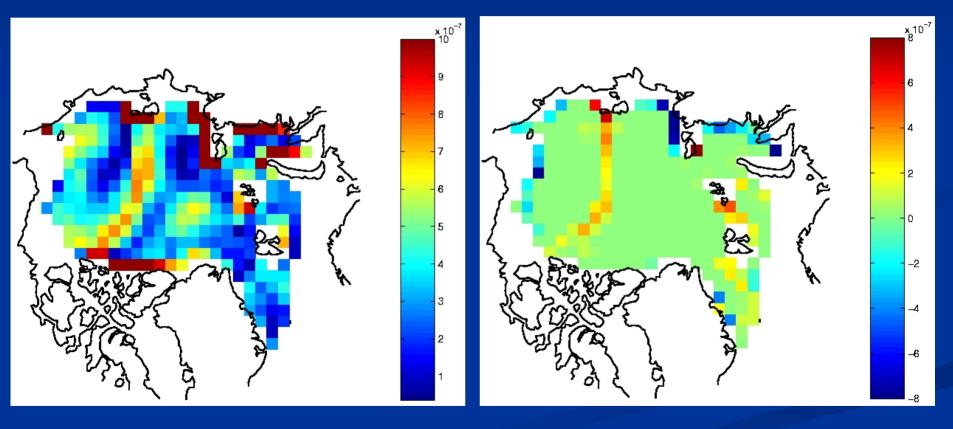




Tremblay Mysak 1997

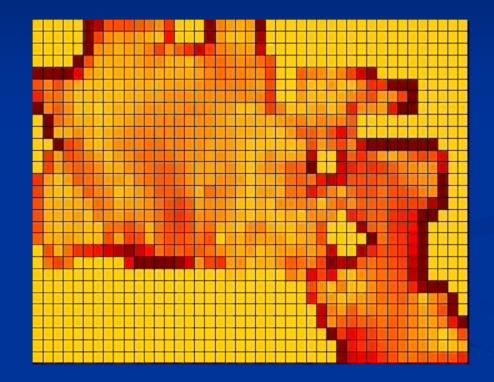
SSMI passive microwave

Shear lines



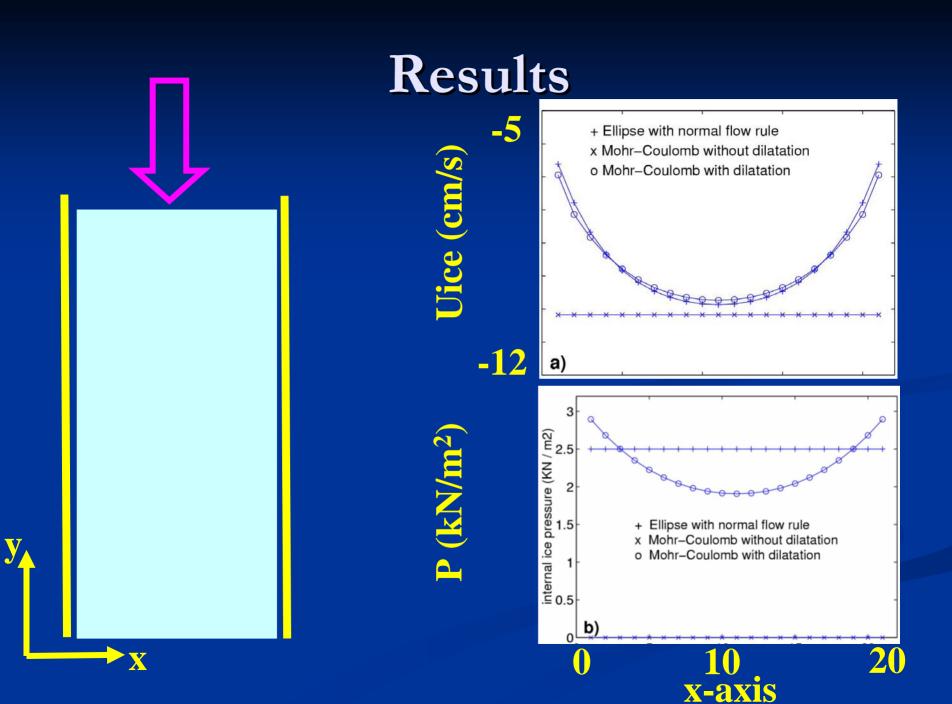
Shear

Divergence

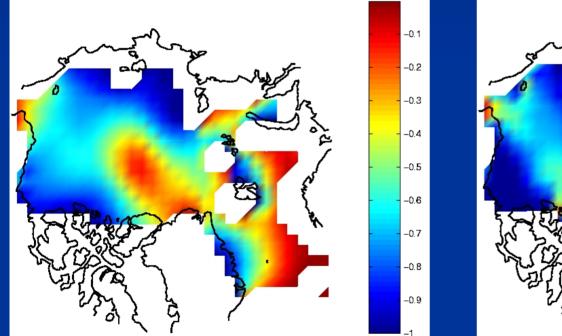


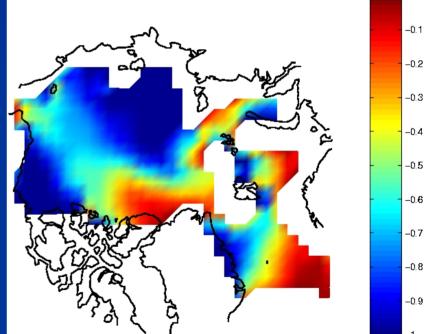
Dilatation effects?

Flow down a channelArctic simulation



Internal Ice Pressure (normalized)





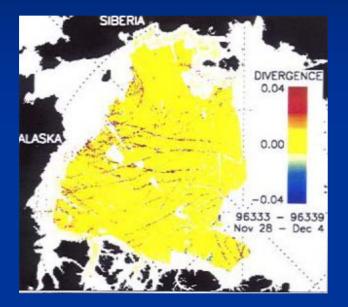
no dilatation

dilatation

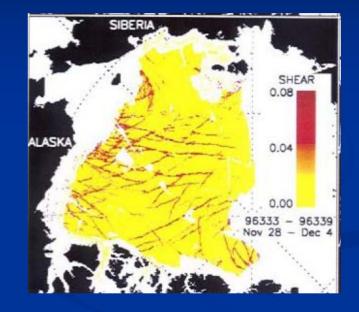
Plastic OR Viscous?

- Plastic OR Viscous?
- Are model iterated until convergence?

Sea ice deformation



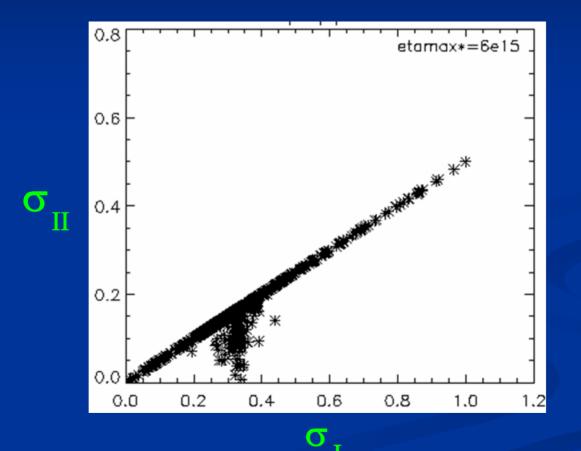
divergence



shear

RGPS data, Kwok

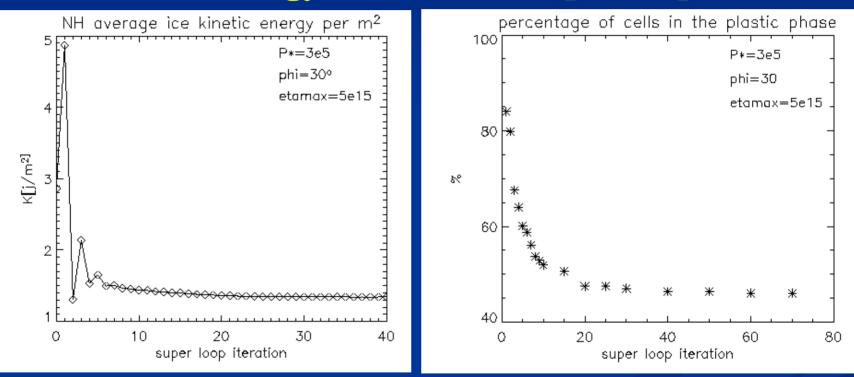
Stress state on the yield curve



Model integration

Kinetic energy

% plastic phase

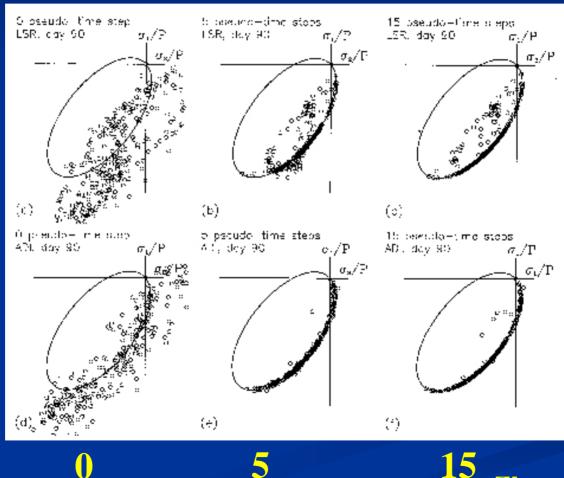


Super loop iteration

Stress states

Line Successive Relaxation

Alternating Direction Implicit



Pseudo time step

Zhang Rothrock, 2000



Should modeler use a larger P* in their sea ice simulation ? This would lead to more points in the viscous regime as observed...

■ What about the mean kinetic energy of the pack then?

Since most of stress state are observed to be "nonplastic", should we take more care about how we model the low deformation state? (viscous? elastic?)



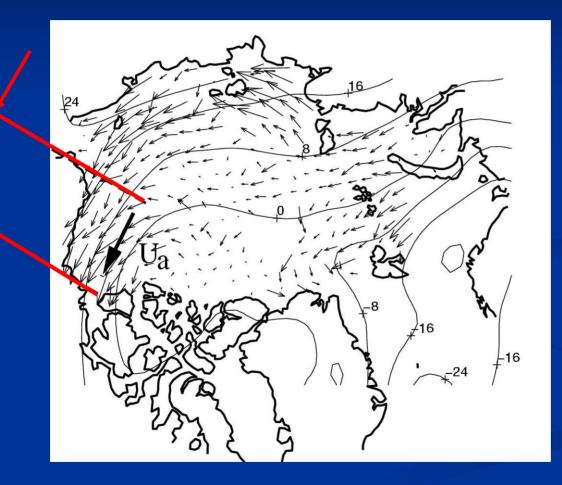
Evidence for a higher P*

From Model:

Kreyscher et al, 1998 → P* = 15,000 kN/m²
 Hibler Walsh 1982 → P* = 27,000 kN/m²

From Observations:

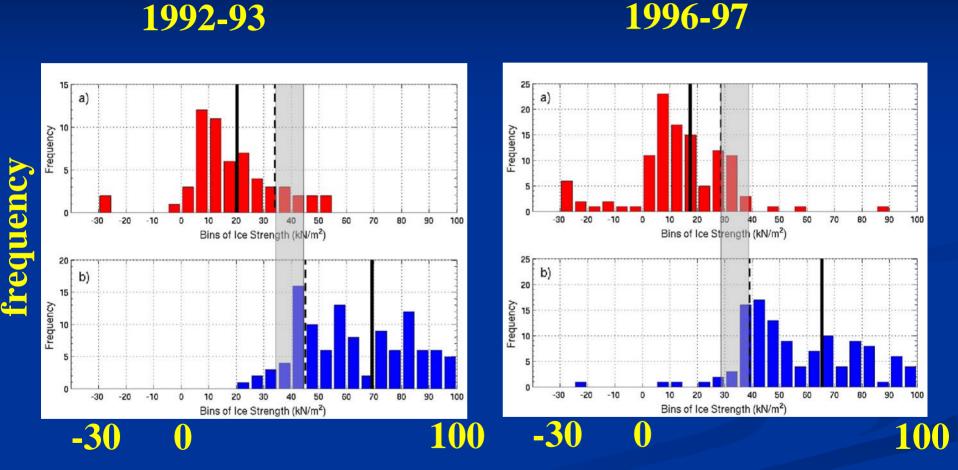
Pstar from satellite/NCEP data



L

 $F = \tau a L$ P*h > or < F

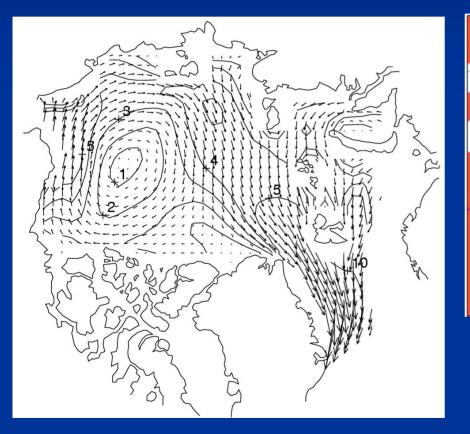
Ice strength estimates P* -93 1996-97

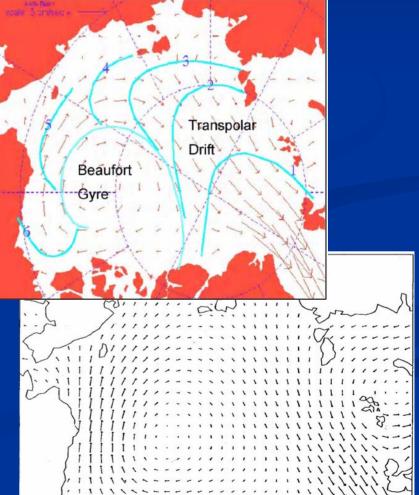


P* (kN/m²)

Tremblay Hakakian, 2006

Mean sea ice drift





The Model

