Modelling Interactions Between Weather and Climate

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Earth's climate system displays variability on many scales
 space: 10⁻⁶m - 10⁷ m



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- time: seconds 10^6 years (and beyond)

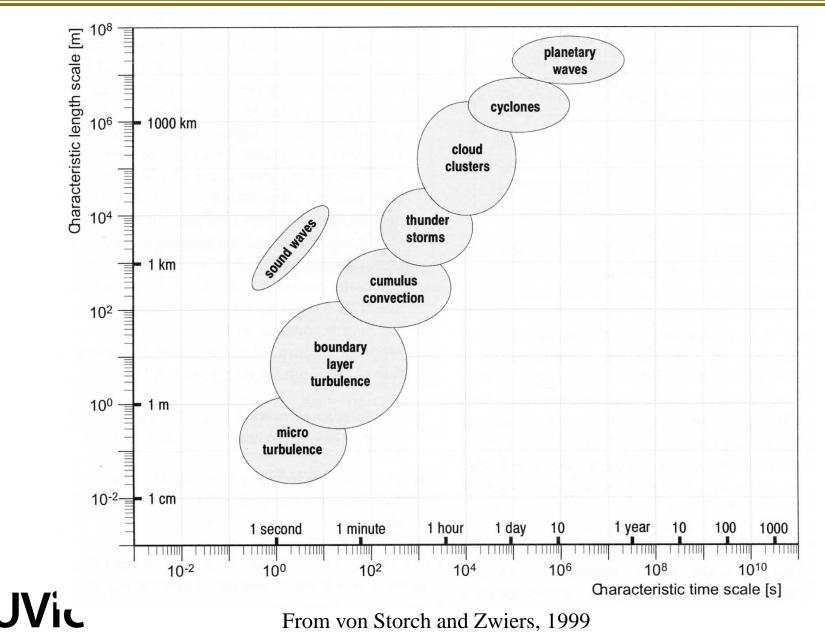


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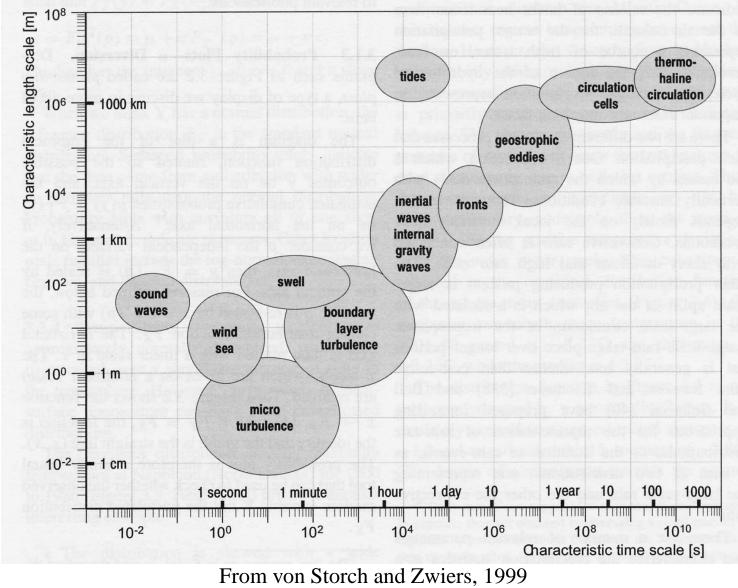
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Modelling Interactions Between Weather and Climate – p. 4/33

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two examples: coupled atmosphere/ocean boundary layers, extratropical atmospheric low-frequency variability

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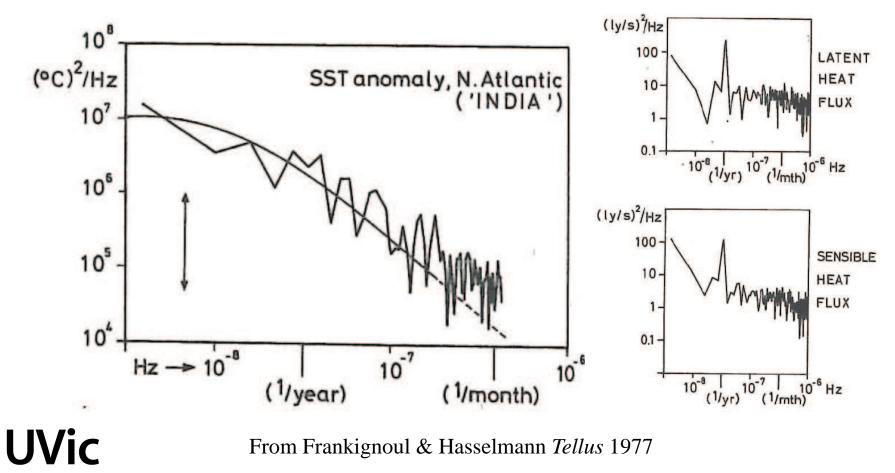
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Smaller (but still large) separation \Rightarrow stochastic corrections needed **UVic**

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- Observations from North Atlantic weathership "INDIA"



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with spectrum

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We'll be coming back to this again later on

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A simple example

As a simple example of a coupled fast-slow system consider

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Intuition suggests that as $\tau \to 0$

$$\frac{d}{dt}x \simeq x - x^3 + \sqrt{\tau}(\Sigma + x)|x| \circ \dot{W}$$



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i.e. depending on $\overline{x}(0)$ system settles into bottom of one of two **UVic** potential wells $\overline{x} = \pm 1$

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Note: averaging is projection operator only if scale separation \overline{UVic} between \overline{u} and u'

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Diffusion matrix $\sigma(\mathbf{x})$ defined by lag correlation integrals

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 $\Rightarrow x(t) \rightarrow 1 + \zeta \text{ such that}$ $\frac{d}{dt}\zeta = -2\zeta + (1 + \Sigma)^2 \dot{W}$

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N/i dependence of stationary distribution of y on x

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- Informally, what is required is that the autocorrelation function of y decay sufficiently rapidly with lag for large timescale separations the delta-correlated white noise approximation is reasonable
- Crucially: none of this assumes that the fast process is stochastic. Effective SDEs (L) and (N) arise in limit $\tau \to 0$ as approximation to fast *deterministic or stochastic* dynamics



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 $\blacksquare \ E_{y|x}\left\{y\right\} = \sqrt{\tau}x \ \ \text{,} \ \ \mathrm{std}_{y|x} = b^2/2$



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Stochastic terms remain in the strict $\tau \rightarrow 0$ limit

$$\frac{dx}{dt} = -(1-a)x + ab\dot{W}$$



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- "MTV" theory considers averaging assuming that weather influence strengthens in this limit
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$$\begin{aligned} \frac{dx}{dt} &= -x + \frac{a}{\sqrt{\tau}}y \\ \frac{dy}{dt} &= \frac{1}{\sqrt{\tau}}x - \frac{1}{\tau}y + \frac{b}{\sqrt{\tau}}\dot{W} \end{aligned}$$

$$E_{y|x} \left\{ y \right\} = \sqrt{\tau} x \quad , \quad \mathrm{std}_{y|x} = b^2/2$$

Stochastic terms remain in the strict $\tau \rightarrow 0$ limit

$$\frac{dx}{dt} = -(1-a)x + ab\dot{W}$$

Present analysis will not make MTV ansatz of increasing weather influence **UVic** as τ decreases; rather than a " $\tau = 0$ theory", it is a "small τ theory"

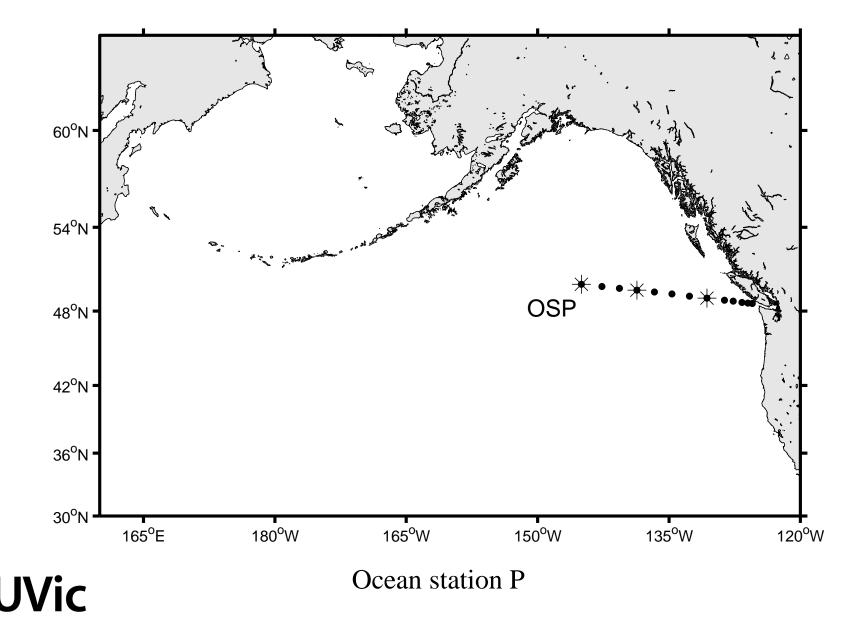
Atmosphere and ocean interact through (generally turbulent) boundary layers, exchanging mass, momentum, and energy



- Atmosphere and ocean interact through (generally turbulent) boundary layers, exchanging mass, momentum, and energy
- Idealised coupled model of atmospheric winds and air/sea temperatures:

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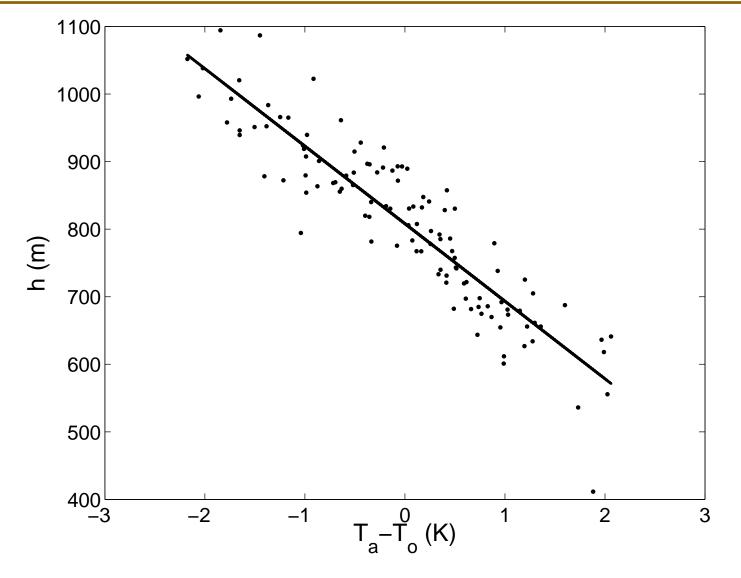
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Atmospheric boundary layer thickness determined by surface stratification

$$h(T_a, T_o) = \max\left[h_{min}, \overline{h}(1 - \alpha(T_a - T_o))\right]$$

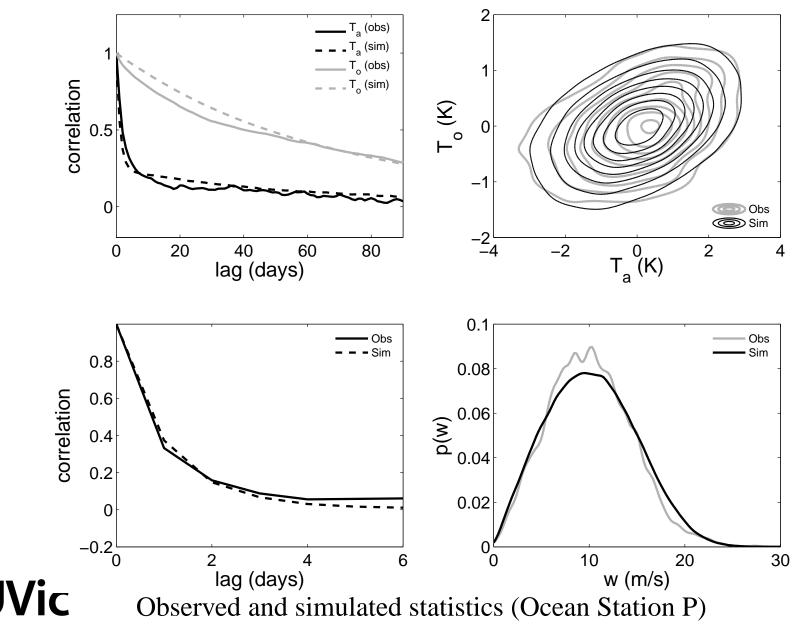
/ic



Boundary layer height and surface stability

Vic





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Observed timescale separations:

$$\frac{\tau_w}{\tau_{T_a}} \sim 0.7$$



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Averaging model (A) $\frac{d}{dt}\mathbf{T} = \overline{f}(\mathbf{T}) + \Sigma \dot{W}$ $\overline{f}_1(\ K \ / \ s \)$ $\overline{f}_2(K / s)$ 5 T₀ (K) 0 -5⊾ -5 -5 $T_a^0(K)$ -5 $T_a^0(K)$ 5 5 Vic 10 -5 -5 5 15 5 0 0 x 10⁻⁵ $\times 10^{-6}$ Modelling Interactions Between Weather and Climate – p. 23/33

Analytic expression for $\sigma(T_a, T_o)$

$$\sigma(T_a, T_o) = \frac{\beta}{\sqrt{\gamma_a^2 + \gamma_o^2}} \begin{pmatrix} \frac{\gamma_o}{\gamma_a} & -1\\ -1 & \frac{\gamma_a}{\gamma_o} \end{pmatrix} \psi(T_a - T_o)$$



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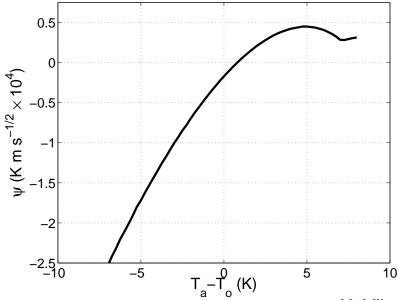
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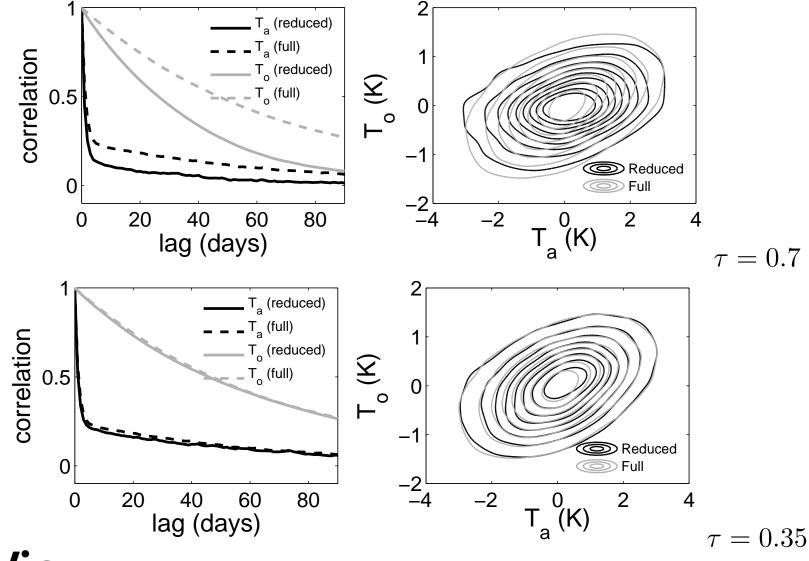
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Modelling Interactions Between Weather and Climate – p. 25/33

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Form of SDE did not account for feedback of stratification on h; physical origin of parameters in inverse model somewhat different than had been assumed



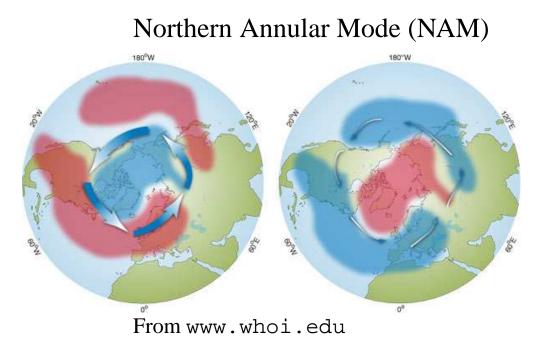
Variability of extratropical atmosphere on timescales of ~ 10 days + described as "low-frequency variability" (LFV)



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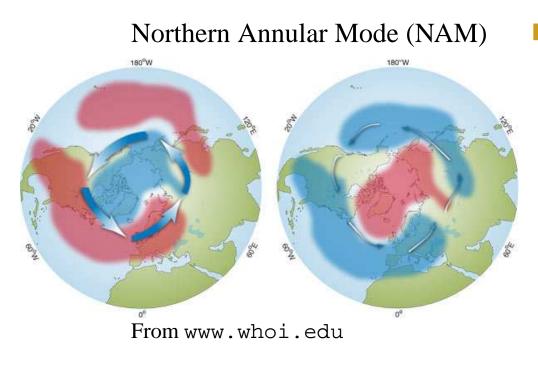


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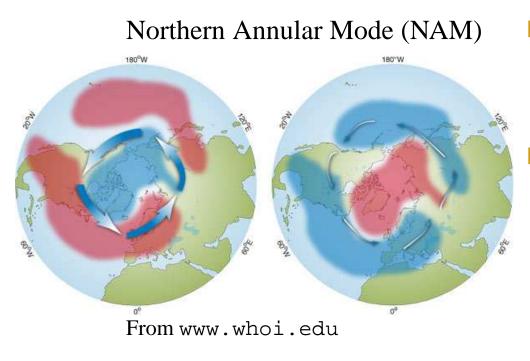
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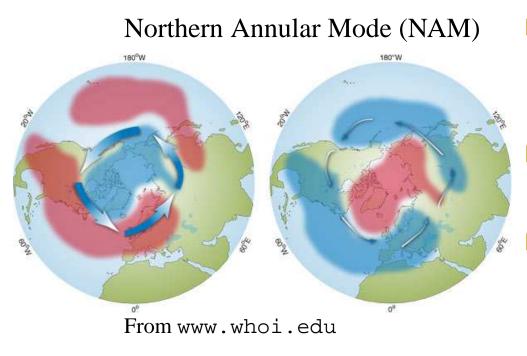
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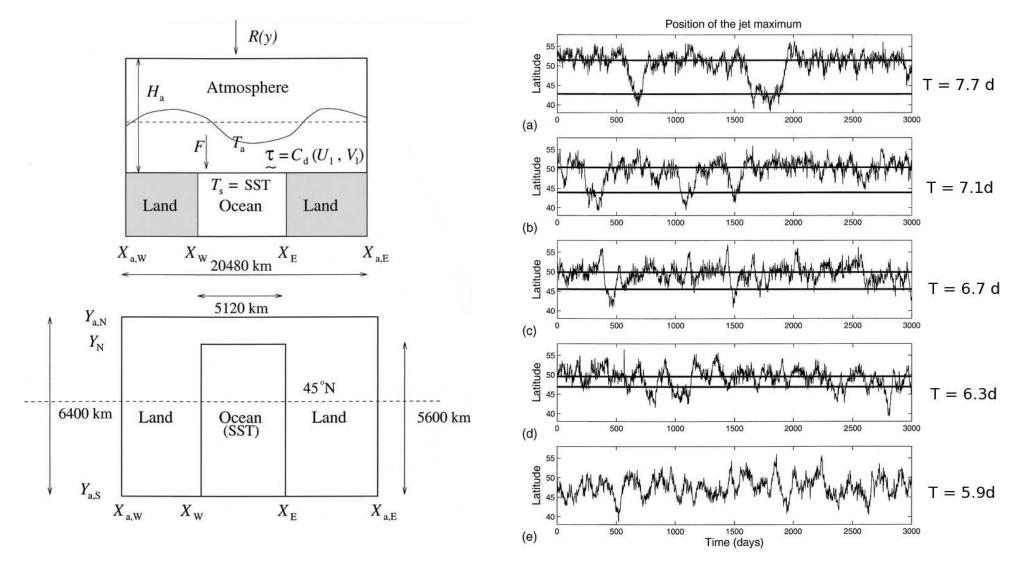


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- Stochastic reduction techniques ⇒ natural tool for investigating dynamics

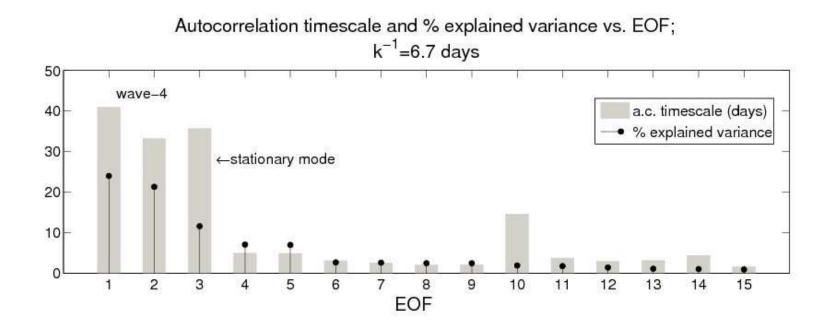






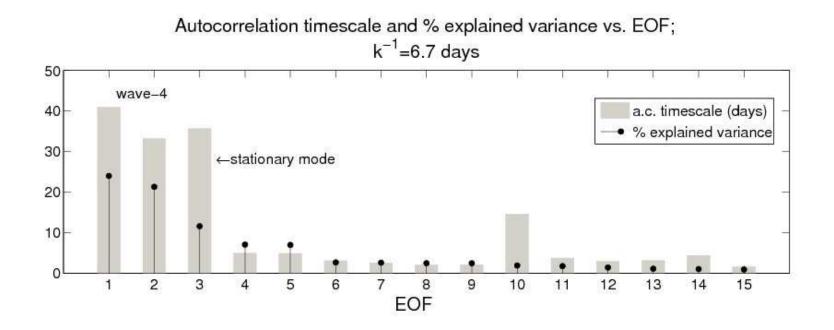
Kravtsov et al. JAS 2005

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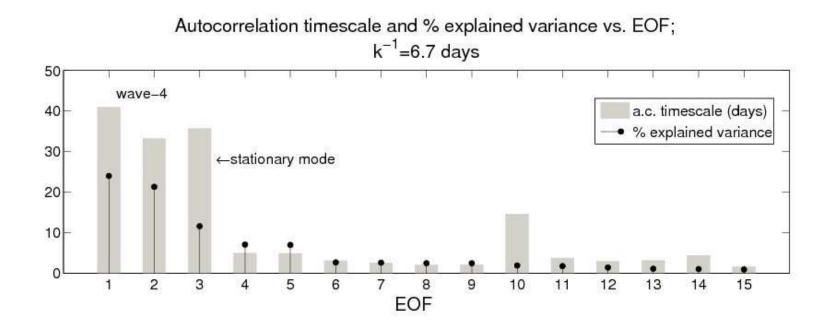
Using PCA decomposition, identify 2 slow modes: propagating wavenumber 4, stationary zonal





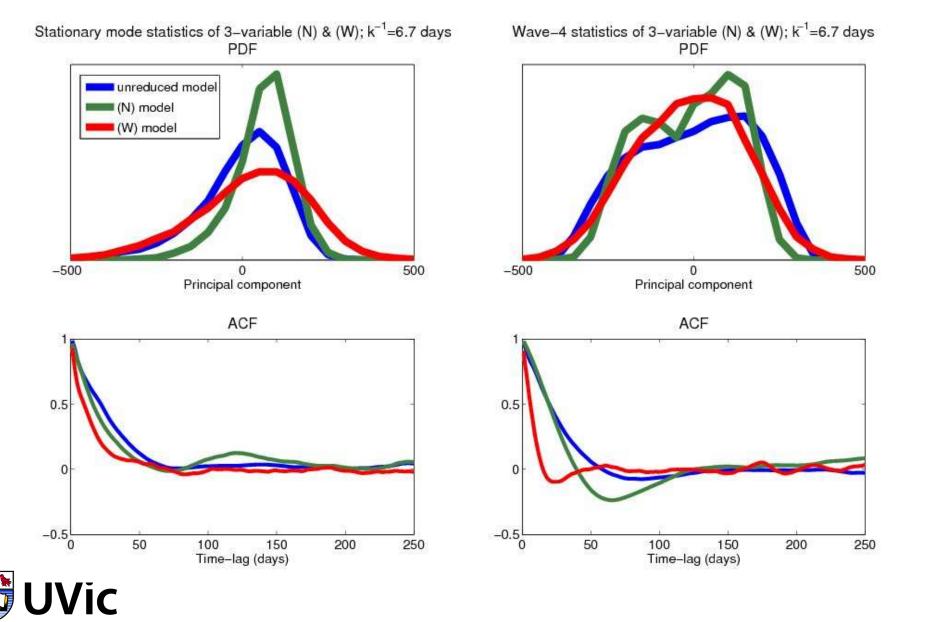
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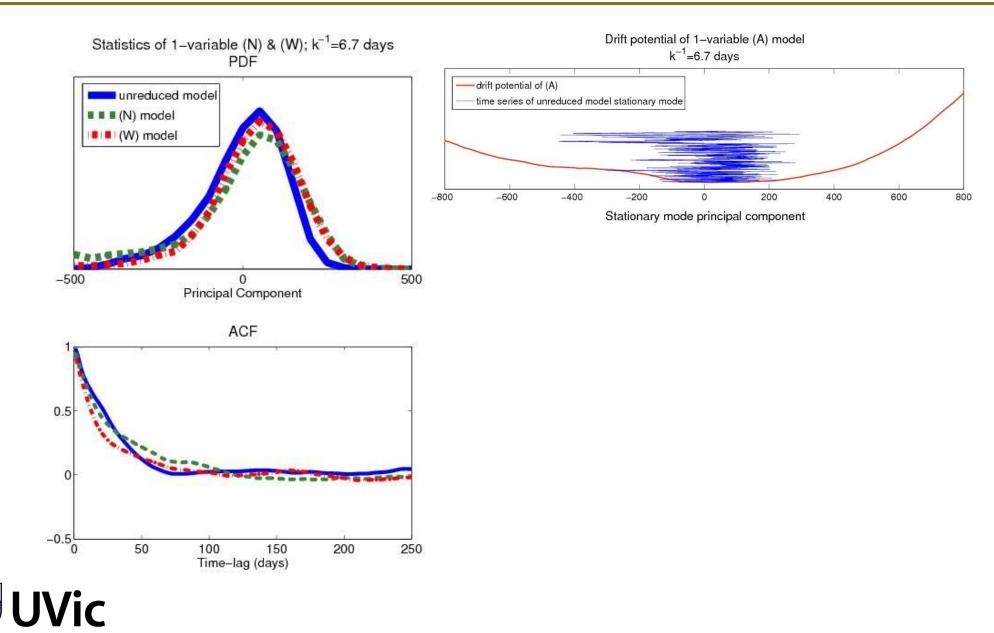


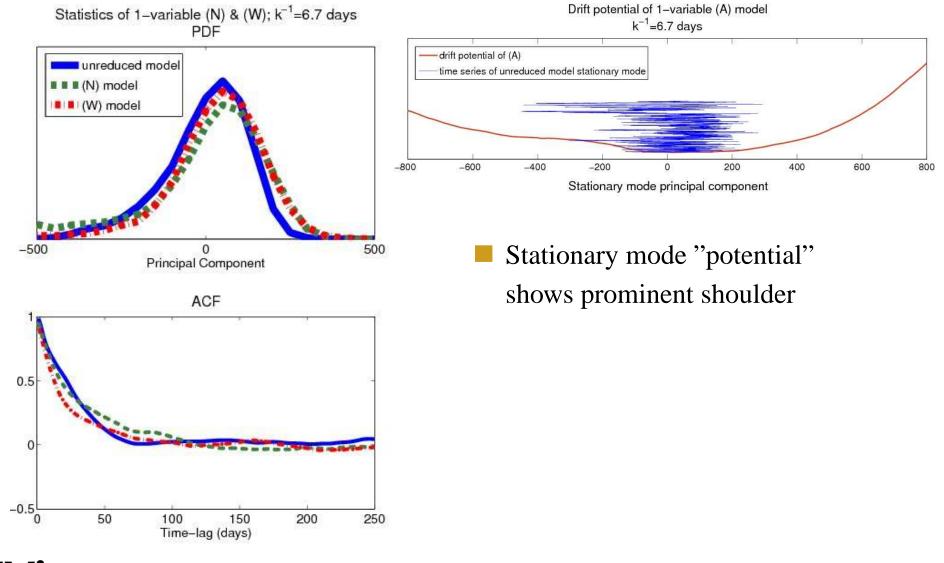


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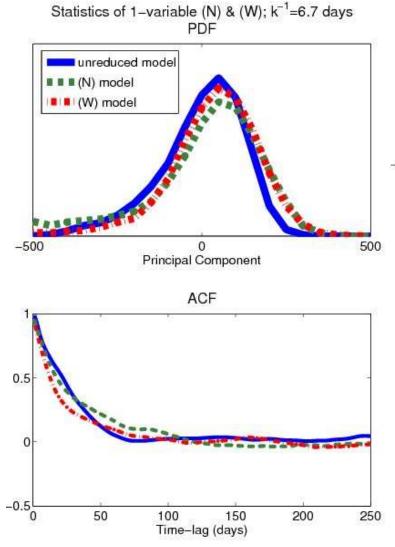
Consider reduction to 3-variable, 1-variable (stationary mode) models **JVic**



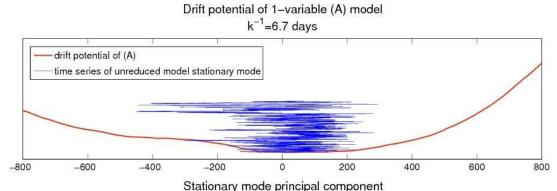




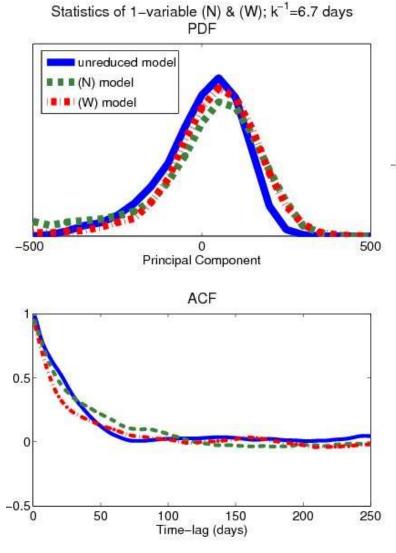


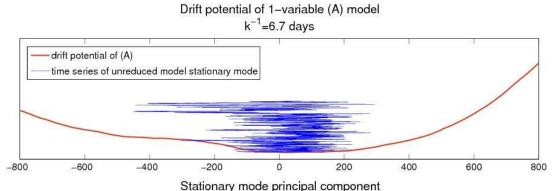


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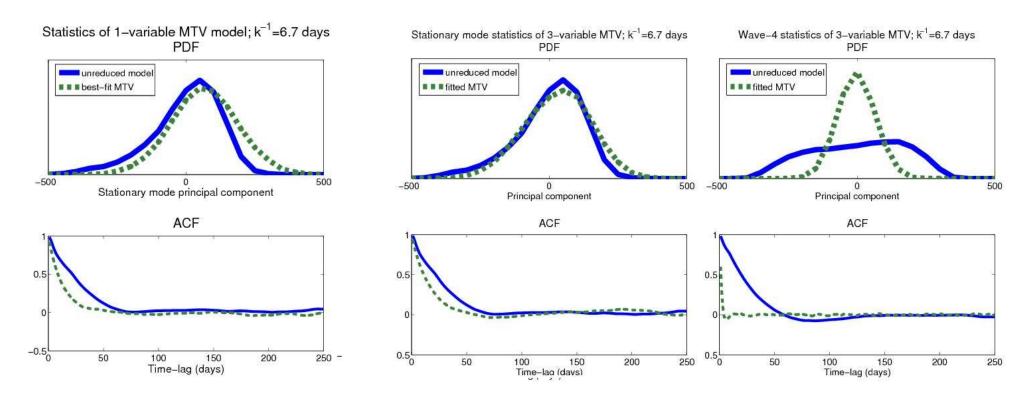


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- Non-gaussianity doesn't require state-dependent noise



MTV approximations with "minimal regression" tuning



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Real systems do not generally have a strong scale separation; an important outstanding problem is a more systematic approach to accounting for this