

# Some Applications of HOMs

Amik St-Cyr  
IMAGe/NCAR



# Overview:

- Preconditioning: Optimized Schwarz for climate modeling
- Adaptive mesh refinements (on the sphere)
- Efficient time-stepping for AMR and SEM
- Discontinuous Galerkin for non-hydrostatic modeling

# Classical Schwarz

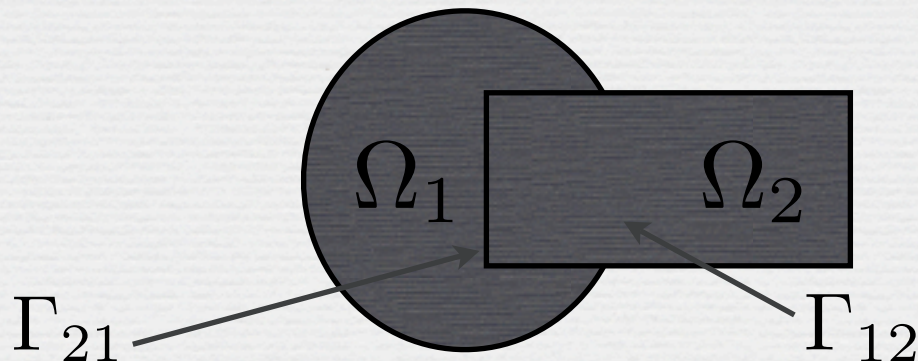
Suppose we need to solve:

$$\mathcal{L}u = f \quad \text{in } \Omega, \quad \mathcal{B}u = g \quad \text{on } \partial\Omega$$

Partition the original domain into 2

domains:

$$\begin{aligned} \mathcal{L}u_1^{n+1} &= f & \text{in } \Omega_1, & & \mathcal{L}u_2^{n+1} &= f & \text{in } \Omega_2, \\ \mathcal{B}(u_1^{n+1}) &= g & \text{on } \partial\Omega_1, & & \mathcal{B}(u_2^{n+1}) &= g & \text{on } \partial\Omega_2, \\ u_1^{n+1} &= u_2^n & \text{on } \Gamma_{12}, & & u_2^{n+1} &= u_1^n & \text{on } \Gamma_{21}. \end{aligned}$$





# The Robin method

- Lions (1990)
- Used to accelerate convergence of Schwarz
- Free positive parameter: how to find its correct value?
- Convergence rate not demonstrated theoretically

$$\mathcal{L}u_j^{k+1} = u_j^{k+1} - \Delta u_j^{k+1} = f_j$$

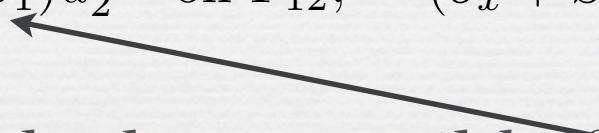
$$pu_j^{k+1} + \frac{\partial u_j^{k+1}}{\partial \mathbf{n}_{jl}} = pu_l^k + \frac{\partial u_l^k}{\partial \mathbf{n}_{jl}} \text{ on } \partial\Omega_j \cap \partial\Omega_l \text{ for } l \in \mathcal{N}(\Omega_j)$$

$$u_j^{k+1} = u_0 \text{ on } \partial\Omega_j \cap \partial\Omega$$



# Optimized approach

• Inspired by the Robin problem:

$$\begin{aligned}
 (\eta - \Delta)u_1^{n+1} &= 0 && \text{in } \Omega_1, && (\eta - \Delta)u_2^{n+1} &= 0 && \text{in } \Omega_2, \\
 (\partial_x + S_1)u_1^{n+1} &= (\partial_x + S_1)u_2^n && \text{on } \Gamma_{12}, && (\partial_x + S_2)u_2^{n+1} &= (\partial_x + S_2)u_1^n && \text{on } \Gamma_{21}.
 \end{aligned}$$


We are looking for the best possible forms of in Fourier space

Proceeding as before leads to the solutions:  $(\sigma_r(k) = \mathcal{F}(S_r))$

$$\hat{u}_1^n(x, k) = \frac{\sigma_1(k) - \sqrt{k^2 + \eta}}{\sigma_1(k) + \sqrt{k^2 + \eta}} e^{-\sqrt{k^2 + \eta}(x-L)} \hat{u}_2^{n-1}(L, k), \quad \hat{u}_2^n(x, k) = \frac{\sigma_2(k) + \sqrt{k^2 + \eta}}{\sigma_2(k) - \sqrt{k^2 + \eta}} e^{-\sqrt{k^2 + \eta}x} \hat{u}_1^{n-1}(0, k)$$

New convergence rate:

$$\rho_{opt} = \rho_{opt}(k, \eta, L) = \frac{\sigma_1(k) - \sqrt{k^2 + \eta}}{\sigma_1(k) + \sqrt{k^2 + \eta}} \frac{\sigma_2(k) + \sqrt{k^2 + \eta}}{\sigma_2(k) - \sqrt{k^2 + \eta}} e^{-2\sqrt{k^2 + \eta}L}$$



# Optimized Schwarz: algebraic results

- SGT 2006: show how to modify existing Schwarz algorithm to yield optimized versions
- The augmented or “enhanced” system is rediscovered
- Spectral elements are natural candidates:
  - Overlapping grids are cumbersome to construct
  - Block preconditioning costly: FDM when possible
  - Optimal preconditioner is known (SD Kim 2006)
  - Q1-GLL based problem costly to invert does not scale: use MG or other solver to invert



# Creating the augmented system from a weak form

Consider:

$$\begin{aligned}w_j^{k+1} - \Delta w_j^{k+1} &= G_j(x, y) \\pw_j^{k+1} + \frac{\partial w_j^{k+1}}{\partial \mathbf{n}_{jl}} &= pw_l^k + \frac{\partial w_l^k}{\partial \mathbf{n}_{jl}} \text{ on } \partial\Omega_j \cap \partial\Omega_l \text{ for } l \in \mathcal{N}(\Omega_j) \\w_j^{k+1} &= w_0 \text{ on } \partial\Omega_j \cap \partial\Omega\end{aligned}$$

To be solved for all  $k$  on any  $\Omega_j$ : it converges (Lions 1990).

Weak form:

$$\int_{\Omega_j} \phi_j w_j^{k+1} + \int_{\Omega_j} \nabla \phi_j \cdot \nabla w_j^{k+1} - \int_{\partial\Omega_j} \phi_j \left( \frac{\partial w_j}{\partial \mathbf{n}} \right)^{k+1} = \int_{\Omega_j} \phi_j G_j.$$

Where test functions are in:

$$H^1(\mathcal{Q}_h) = \{v \in L^2(\Omega) | v|_Q \in H^1(Q) \forall Q \in \mathcal{Q}_h\}$$

Decomposition:

$$\mathcal{Q}_h = \cup_j \Omega_j$$



# Creating the augmented system from a weak form

Define:

$$a_j(w_j^{k+1}, \phi_j) \equiv \int_{\Omega_j} \phi_j w_j^{k+1} + \int_{\Omega_j} \nabla \phi_j \cdot \nabla w_j^{k+1}$$

$$f_j(\phi_j) \equiv \int_{\Omega_j} \phi_j G_j$$

$$T_j(w_j^{k+1}, \phi_j) \equiv \sum_{l \in \mathcal{N}(\Omega_j)} \int_{\Gamma_{jl}} \phi_j \left( \frac{\partial w_j}{\partial \mathbf{n}_{jl}} \right)^{k+1}$$

Leads to:

$$a_j(w_j^{k+1}, \phi_j) - T_j(w_j^{k+1}, \phi_j) = f_j(\phi_j)$$



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Leads to:

$$a_j(w_j^{k+1}, \phi_j) - T_j(w_j^{k+1}, \phi_j) = f_j(\phi_j)$$

Remains to introduce the artificial  
transmission condition...



# Creating the augmented system from a weak form

- The normal derivative can be written in terms of the original bilinear operator (Toselli, Widlund 2005)
- Avoids the difficult duality pairing for functions on the edges of the subdomains

$$\begin{aligned} T_j(w_j^{k+1}, \phi_j) &= \int_{\Omega_j} \nabla \phi_j \cdot \nabla w_j^{k+1} + \int_{\Omega_j} \phi_j \Delta w_j^{k+1} \\ &= \int_{\Omega_j} \nabla \phi_j \cdot \nabla w_j^{k+1} + \int_{\Omega_j} \phi_j w_j^{k+1} - f_j(\phi_j) \\ &= a_j(w_j^{k+1}, \phi_j) - f_j(\phi_j) \end{aligned}$$

Where we pick  $\phi_j \in H^1(\partial\Omega_j)$



# Creating the augmented system from a weak form

Boundary condition is:

$$\begin{aligned} T_j(w_j^{k+1}, \phi_j) &= \sum_{l \in \mathcal{N}(\Omega_j)} T_j(w_j^{k+1}, \phi_j|_{\Gamma_{jl}}) \\ &= \sum_{l \in \mathcal{N}(\Omega_j)} \left\{ \int_{\Gamma_{jl}} p\phi_j(w_l^k - w_l^{k+1}) - T_l(w_l^k, \phi_j|_{\Gamma_{jl}}) \right\} \\ &= - \int_{\Omega_j} p\phi_j w_j^{k+1} + \sum_{l \in \mathcal{N}(\Omega_j)} \left\{ \int_{\Gamma_{jl}} p\phi_j w_l^k - T_l(w_l^k, \phi_j|_{\Gamma_{jl}}) \right\} \end{aligned}$$

where a sum on neighbors appears.



# Creating the augmented system from a weak form

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where a sum on neighbors appears.

Leads to the form required by the algorithm

$$\begin{aligned} a_j(w_j^{k+1}, \phi_j) + \int_{\Omega_j} p\phi_j w_j^{k+1} &= f_j(\phi_j) + \sum_{l \in \mathcal{N}(\Omega_j)} f_l(\phi_l|_{\Gamma_{jl}}) \\ &\quad - \sum_{l \in \mathcal{N}(\Omega_j)} a_l(w_l^k, \phi_l|_{\Gamma_{jl}}) + \sum_{l \in \mathcal{N}(\Omega_j)} \int_{\Gamma_{jl}} p\phi_l w_l^k \end{aligned}$$



# Creating the augmented system from a weak form

$$a_j(w_j^{k+1}, \phi_j) + \int_{\Omega_j} p \phi_j w_j^{k+1} = f_j(\phi_j) + \sum_{l \in \mathcal{N}(\Omega_j)} f_l(\phi_l|_{\Gamma_{jl}}) \\ - \sum_{l \in \mathcal{N}(\Omega_j)} a_l(w_l^k, \phi_l|_{\Gamma_{jl}}) + \sum_{l \in \mathcal{N}(\Omega_j)} \int_{\Gamma_{jl}} p \phi_l w_l^k$$

After (any)

$$\tilde{A}_j \mathbf{u}_j^{n+1} = \mathbf{f}_j + \sum_{k=1}^J \tilde{B}_{jk} \mathbf{u}_k^n, \quad j = 1, \dots, J$$



# Creating the augmented system from a weak form

$$\boxed{a_j(w_j^{k+1}, \phi_j) + \int_{\Omega_j} p\phi_j w_j^{k+1}} = f_j(\phi_j) + \sum_{l \in \mathcal{N}(\Omega_j)} f_l(\phi_l|_{\Gamma_{jl}}) \\
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Possible to create augmented system!



# Creating the augmented system from a weak form

$$a_j(w_j^{k+1}, \phi_j) + \int_{\Omega_j} p\phi_j w_j^{k+1} = f_j(\phi_j) + \sum_{l \in \mathcal{N}(\Omega_j)} f_l(\phi_l|_{\Gamma_{jl}}) \\ - \sum_{l \in \mathcal{N}(\Omega_j)} a_l(w_l^k, \phi_l|_{\Gamma_{jl}}) + \sum_{l \in \mathcal{N}(\Omega_j)} \int_{\Gamma_{jl}} p\phi_l w_l^k$$

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Not mentioned: difficulties at corners



# Creating the augmented system from a weak form

$$a_j(w_j^{k+1}, \phi_j) + \int_{\Omega_j} p\phi_j w_j^{k+1} = f_j(\phi_j) + \sum_{l \in \mathcal{N}(\Omega_j)} f_l(\phi_l|_{\Gamma_{jl}}) \\ - \sum_{l \in \mathcal{N}(\Omega_j)} a_l(w_l^k, \phi_l|_{\Gamma_{jl}}) + \sum_{l \in \mathcal{N}(\Omega_j)} \int_{\Gamma_{jl}} p\phi_l w_l^k$$

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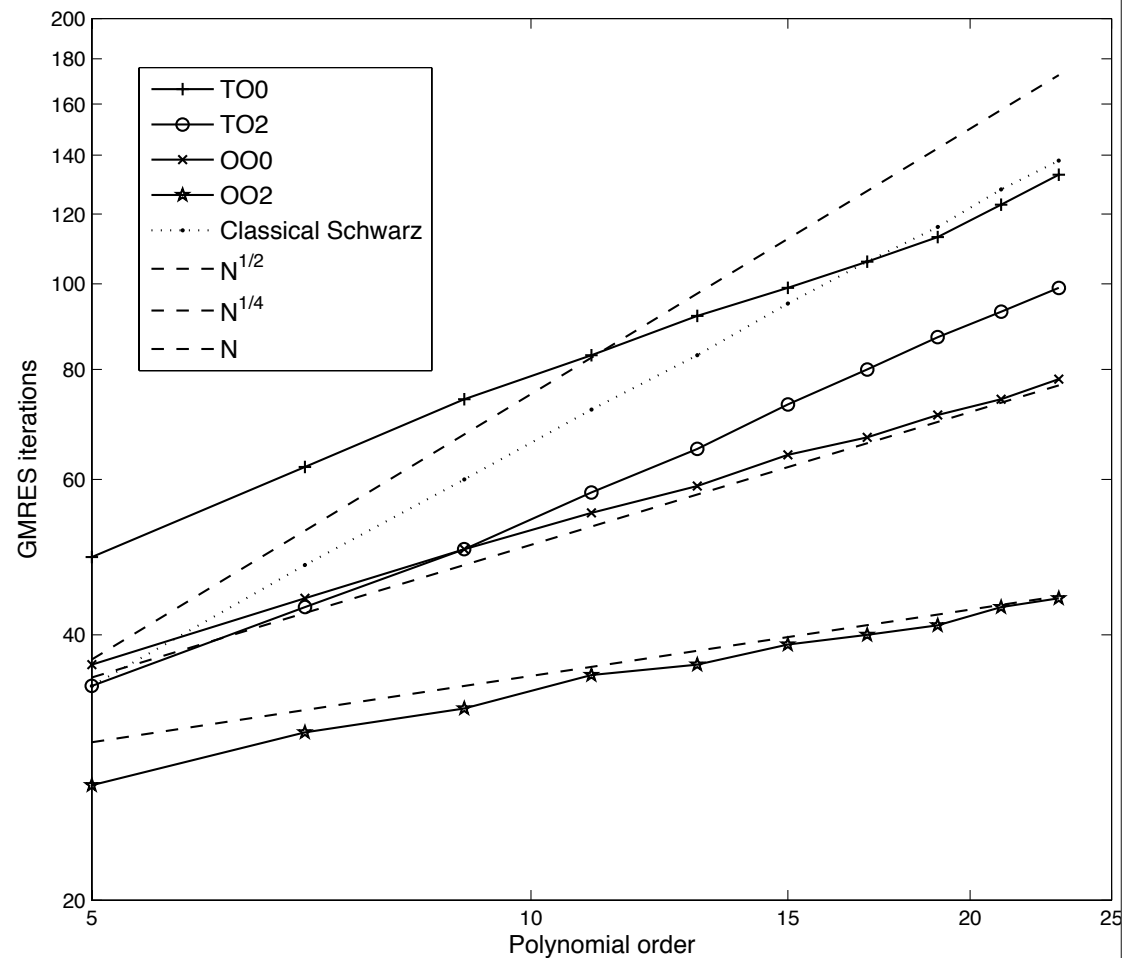
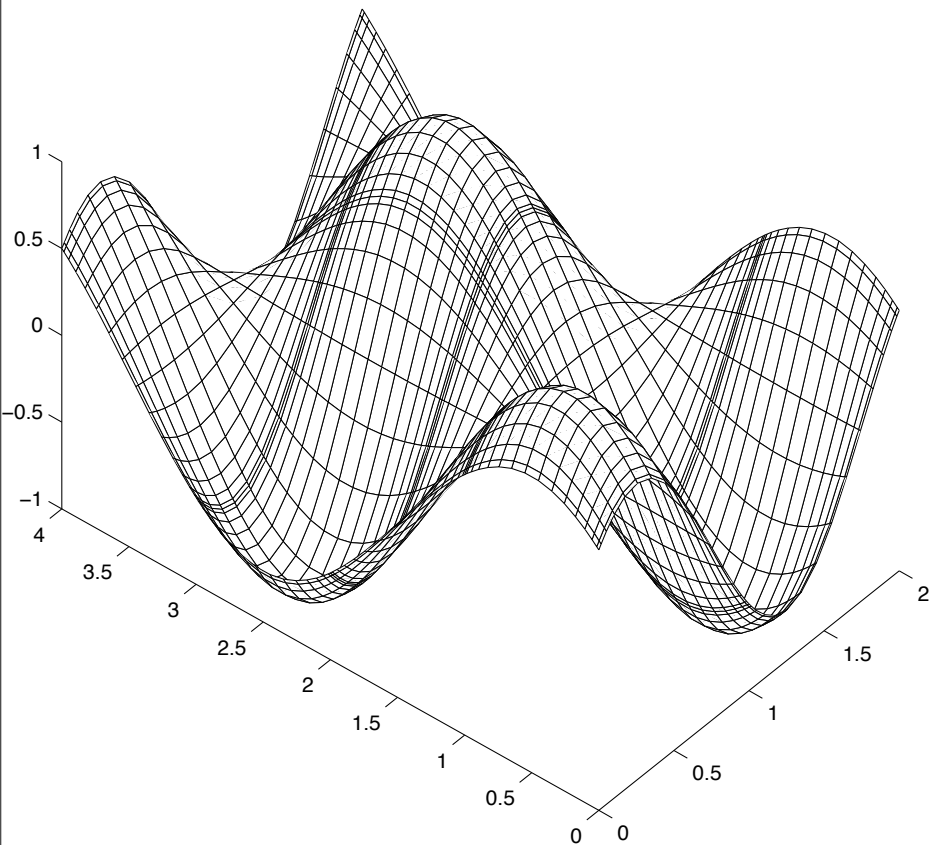
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Not mentioned: “under” integration for SEM

# SEM simple problem

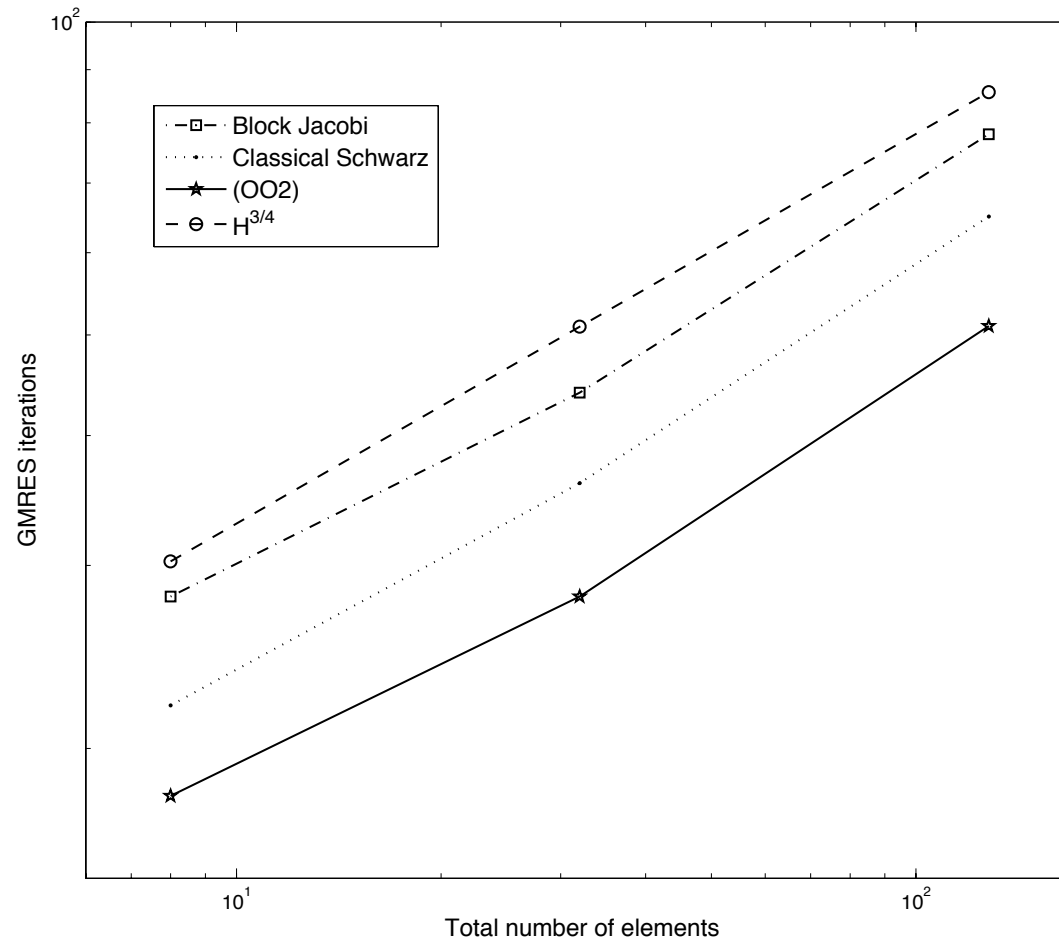
$$\mathcal{L}u = (\eta - \Delta)u = f, \quad \text{in } \Omega,$$

Gander 2006

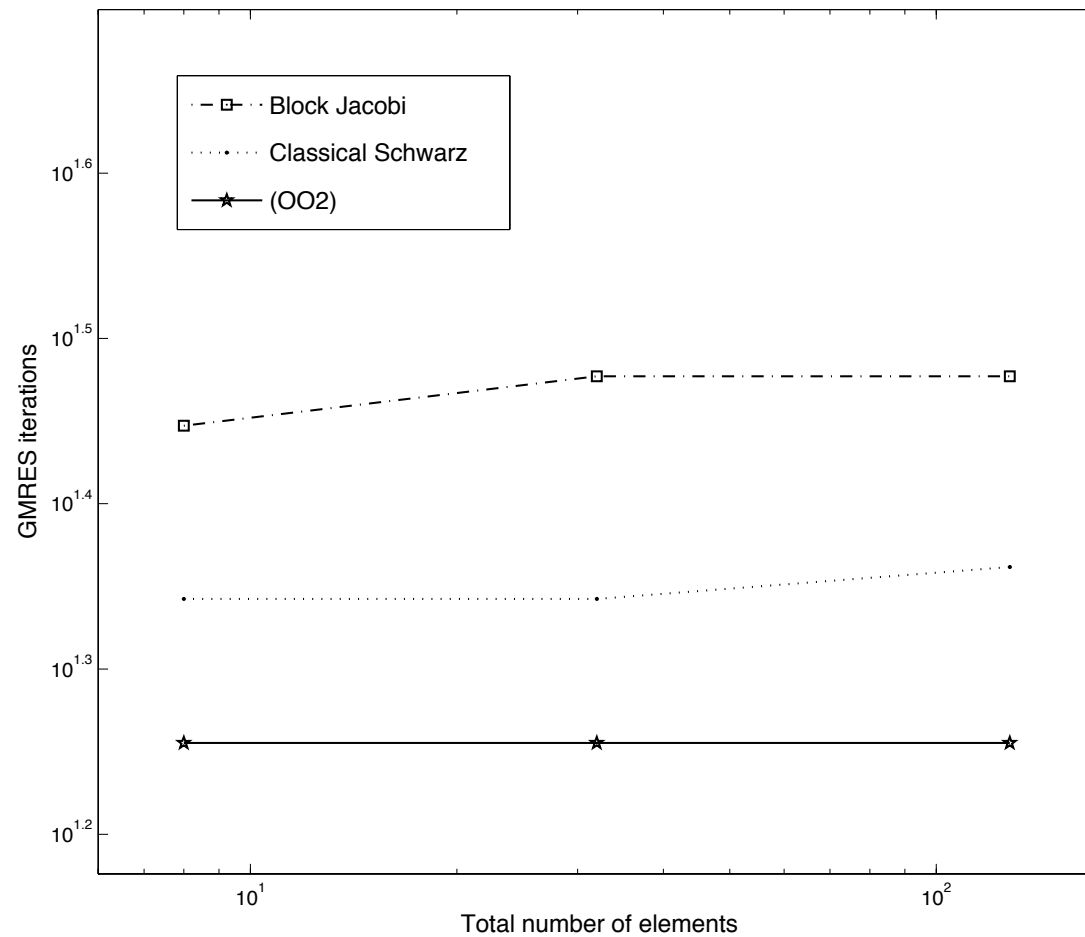




# SEM simple problem



# SEM simple problem





# Primitive equations

Momentum: 
$$\frac{d\mathbf{v}}{dt} + f \mathbf{k} \times \mathbf{v} + \nabla\Phi + RT \nabla \ln p = 0$$

Thermodynamic: 
$$\frac{dT}{dt} - \frac{\kappa T \omega}{p} = 0$$

Continuity: 
$$\frac{\partial}{\partial t} \left( \frac{\partial p}{\partial \eta} \right) + \nabla \cdot \left( \mathbf{v} \frac{\partial p}{\partial \eta} \right) + \frac{\partial}{\partial \eta} \left( \dot{\eta} \frac{\partial p}{\partial \eta} \right) = 0$$

HOMME: high order multiscale modeling environment

# Primitive equations: SI

Hydrostatic assumption:  $\frac{\partial \Phi}{\partial \eta} = -\frac{RT}{p} \frac{\partial p}{\partial \eta}$ .

Linearization (barotropic state):  $T^r = 300K$ ,  $p_s^r = 1000hPa$

Semi-Implicit:

$$\frac{dX}{dt} = \mathcal{M}(X)$$

Add zero:  $\frac{dX}{dt} = \mathcal{M}(X) + \mathcal{L}X - \mathcal{L}X = \mathcal{N}(X) - \mathcal{L}X$

$$\frac{X^{n+1} - X^{n-1}}{2\Delta t} = \mathcal{N}(X^n) - \frac{1}{2}\mathcal{L}(X^{n+1} + X^{n-1}) = \mathcal{M}(X^n) + \mathcal{L}X^n - \frac{1}{2}\mathcal{L}(X^{n+1} + X^{n-1})$$

$$\frac{X^{n+1} - X^{n-1}}{2\Delta t} = \mathcal{M}(X^n) - \frac{1}{2}\Delta_{tt}\mathcal{L}X$$

“Time diffusion”



# PE: vertical structure matrix


Results of hydrostatic assumption

and vertical coordinate choice:  $p(\eta, p_s) = A(\eta)p_0 + B(\eta)p_s$

$$\mathbf{A} = R\mathbf{H}^r\mathbf{T} + RT^r P,$$

$$G^r - \Delta t^2 \mathbf{A} \nabla^2 G^r = B - \Delta t \mathbf{A} \nabla \cdot \mathcal{V}$$

Solve for each k:

$$\left( \nabla^2 - \frac{1}{\Delta t^2 \lambda_k} \right) \Gamma_k^r = C_k$$


Series of 2D Helmholtz

Barotropic eigenmodes of atmosphere

Backsub:

$$D = \Delta t^{-1} \mathbf{A}^{-1} (B - G^r)$$

$$\ln p_s = \mathcal{P} - \Delta t P \cdot D$$

$$T = \mathcal{T} - \Delta t \mathbf{T} D$$

$$\mathbf{v} = \mathcal{V} - \Delta t \nabla G^r$$

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$$\mathbf{A} = R\mathbf{H}^r\mathbf{T} + RT^rP, \leftarrow \text{Diagonalize}$$

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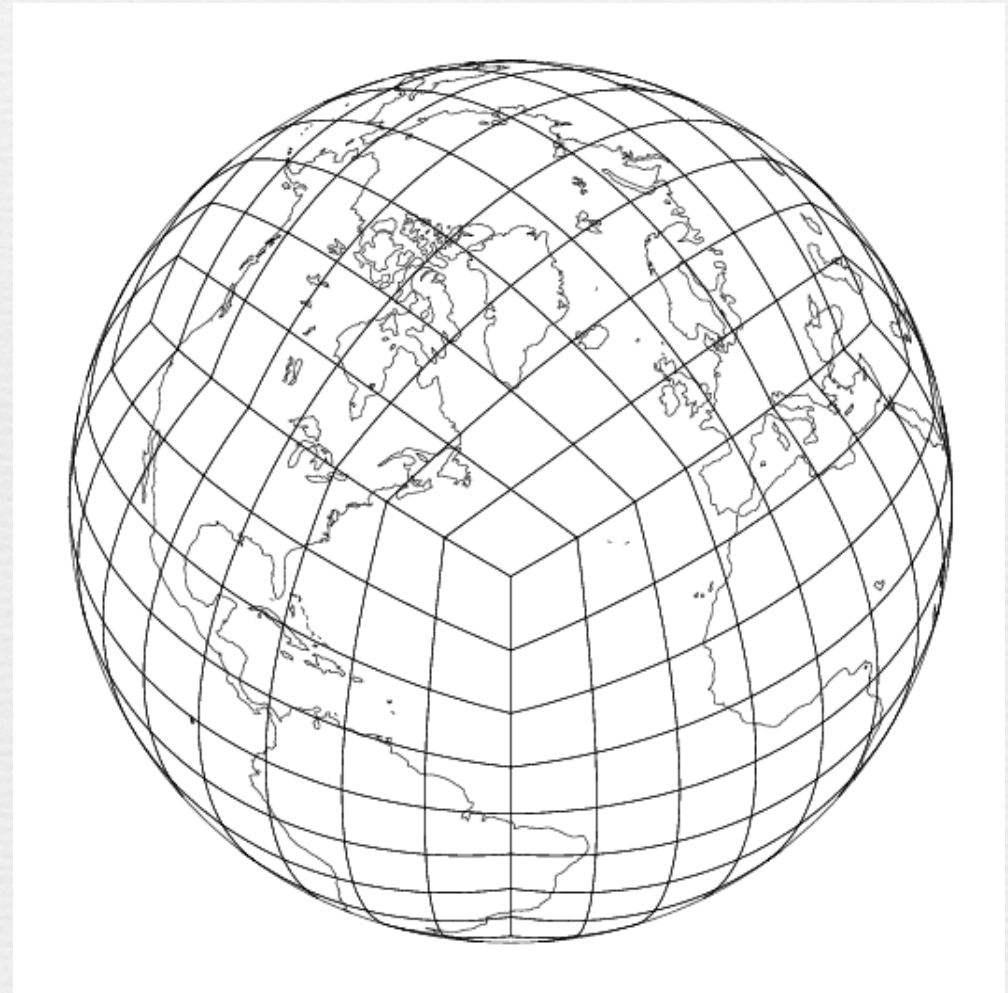
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# Cubed sphere

- Equiangular projection
- Sadourny (72), Rancic (96), Ronchi (96)
- Most models moving towards this approach
- SFC: Dennis 2003



## Metric tensor

$$g_{ij} = \frac{1}{r^4 \cos^2 x_1 \cos^2 x_2} \begin{bmatrix} 1 + \tan^2 x_1 & -\tan x_1 \tan x_2 \\ -\tan x_1 \tan x_2 & 1 + \tan^2 x_2 \end{bmatrix}.$$

## Rewrite div and vorticity

$$g \nabla \cdot \mathbf{v} = \frac{\partial}{\partial x^j} (g u^j), \quad g \zeta = \epsilon_{ij} \frac{\partial u_j}{\partial x^i}.$$

# Cubed sphere

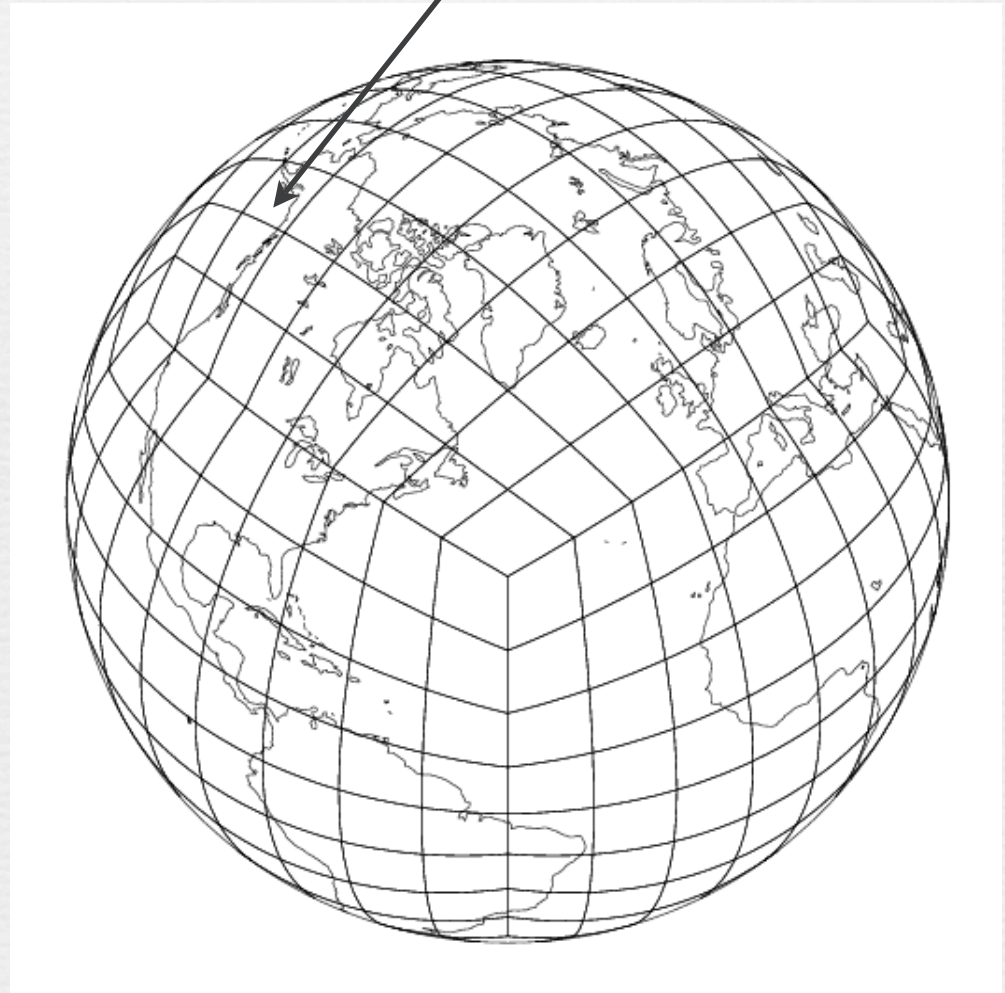
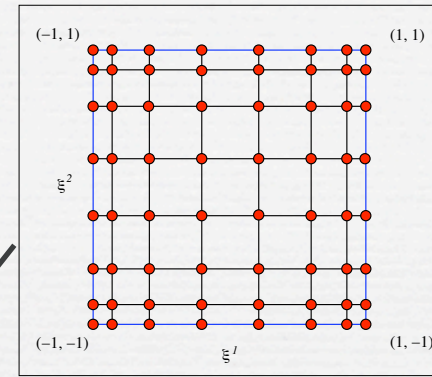
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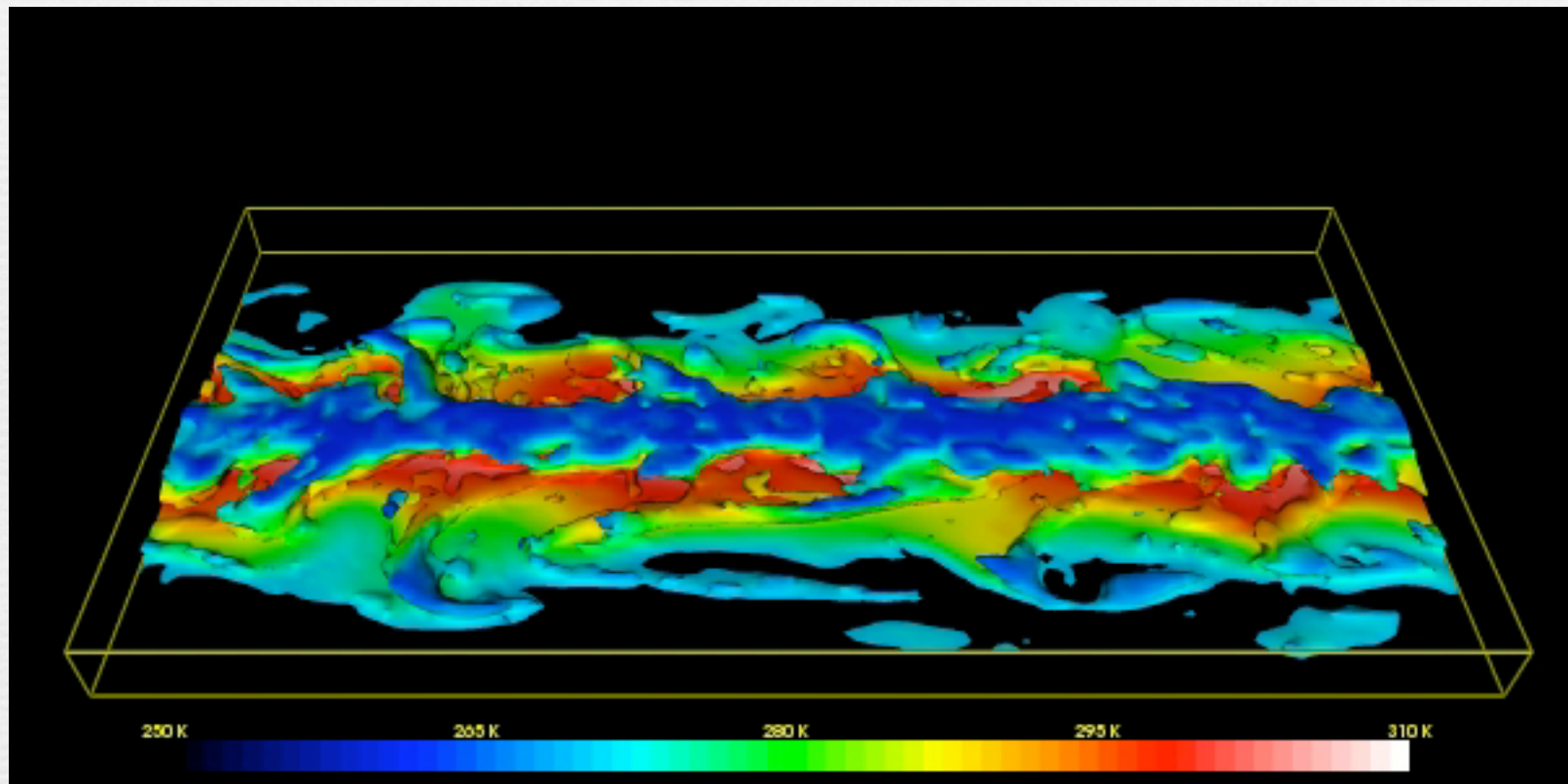
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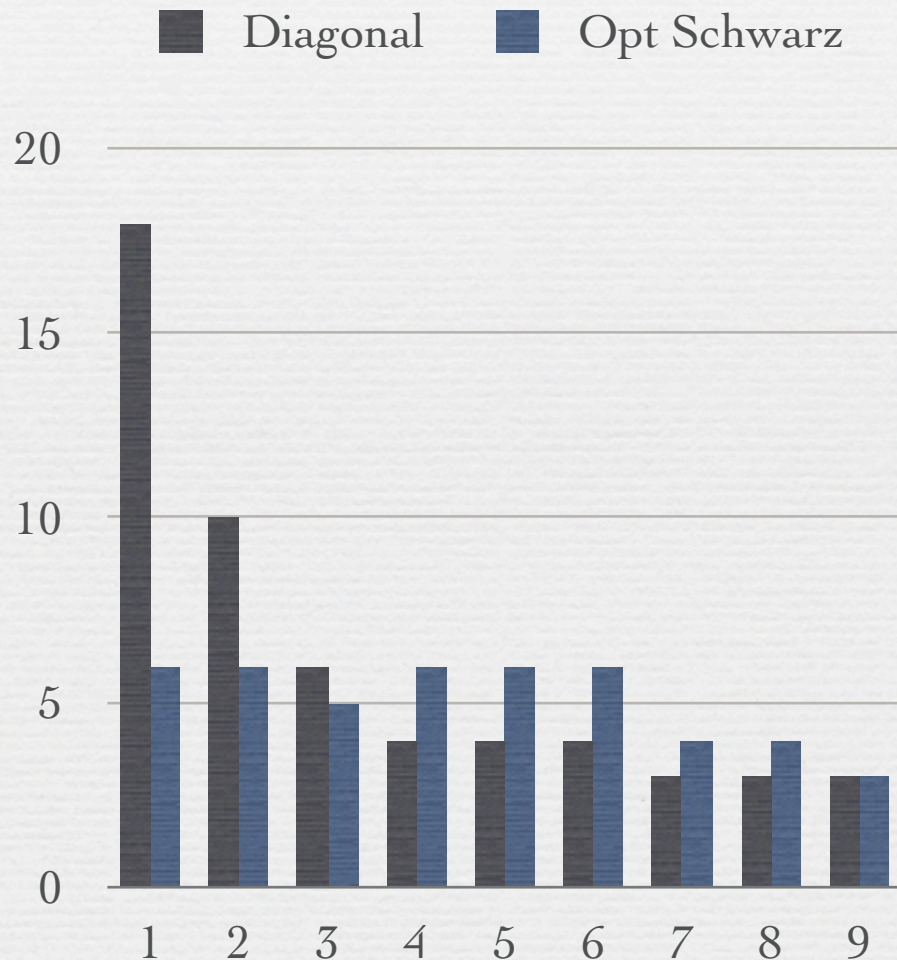


# Held-Suarez numerical experiment: with moisture



Galewski, Sobel and Held 2004

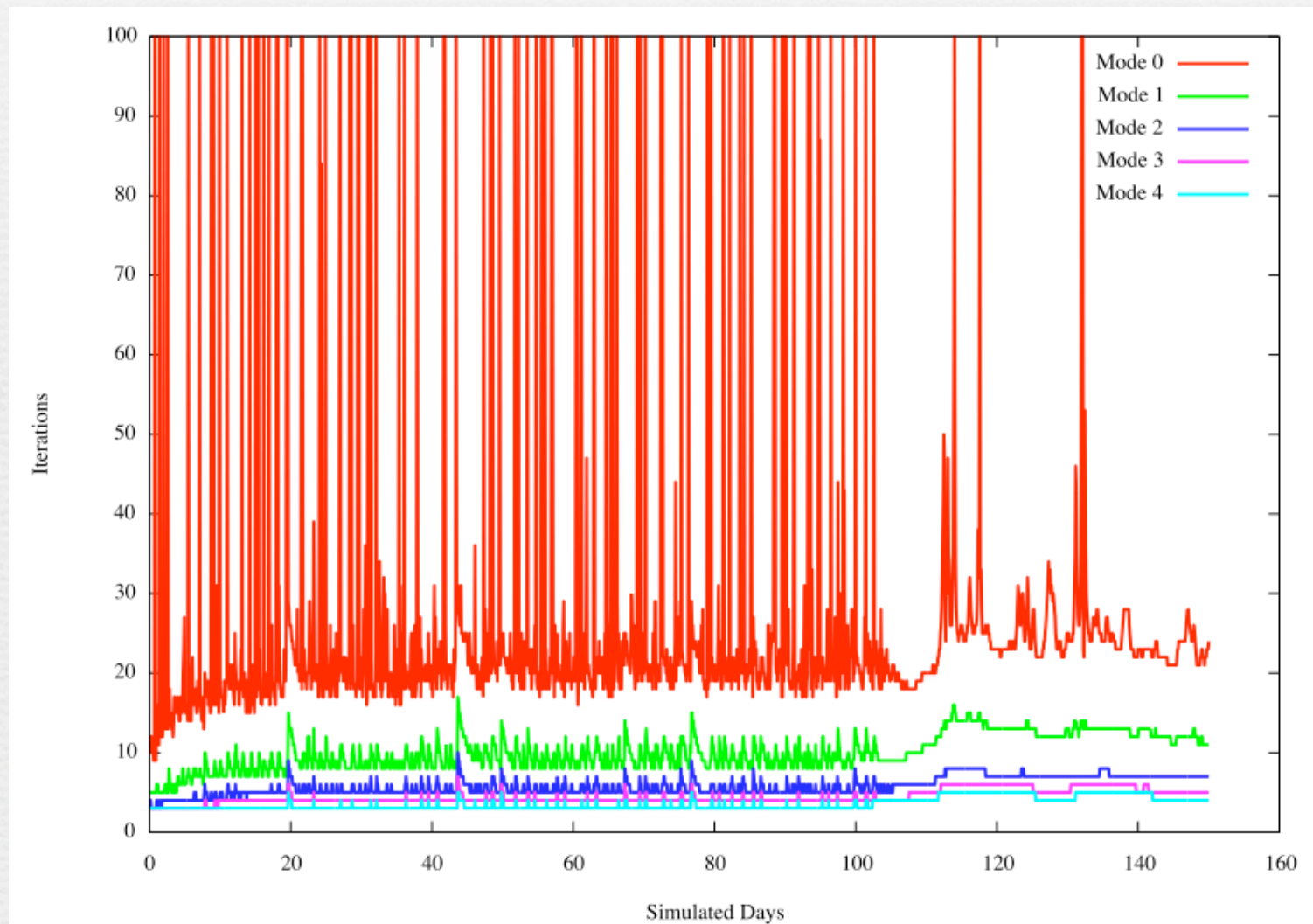
# Convergence per mode



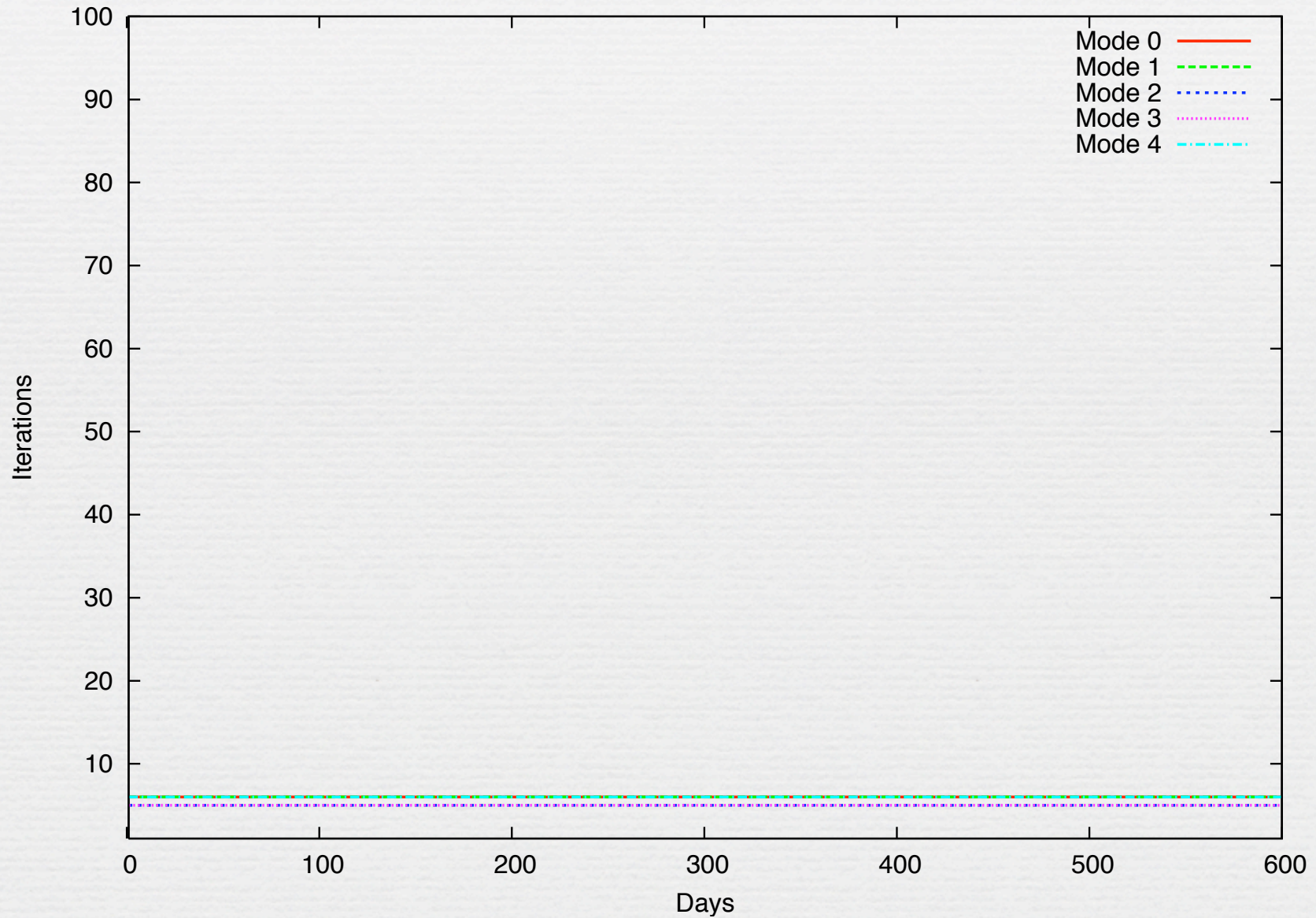
- Optimized algorithm: no maxing out
- Communication cost identical
- Twice the cost of CG per iteration
- Diagonal  $O(N)$  while OS is  $O(N^3)$
- Best strategy: use OS on first few barotropic modes and diagonal elsewhere
- No coarse solver needed: because of time dependence



# Diagonal preconditioning

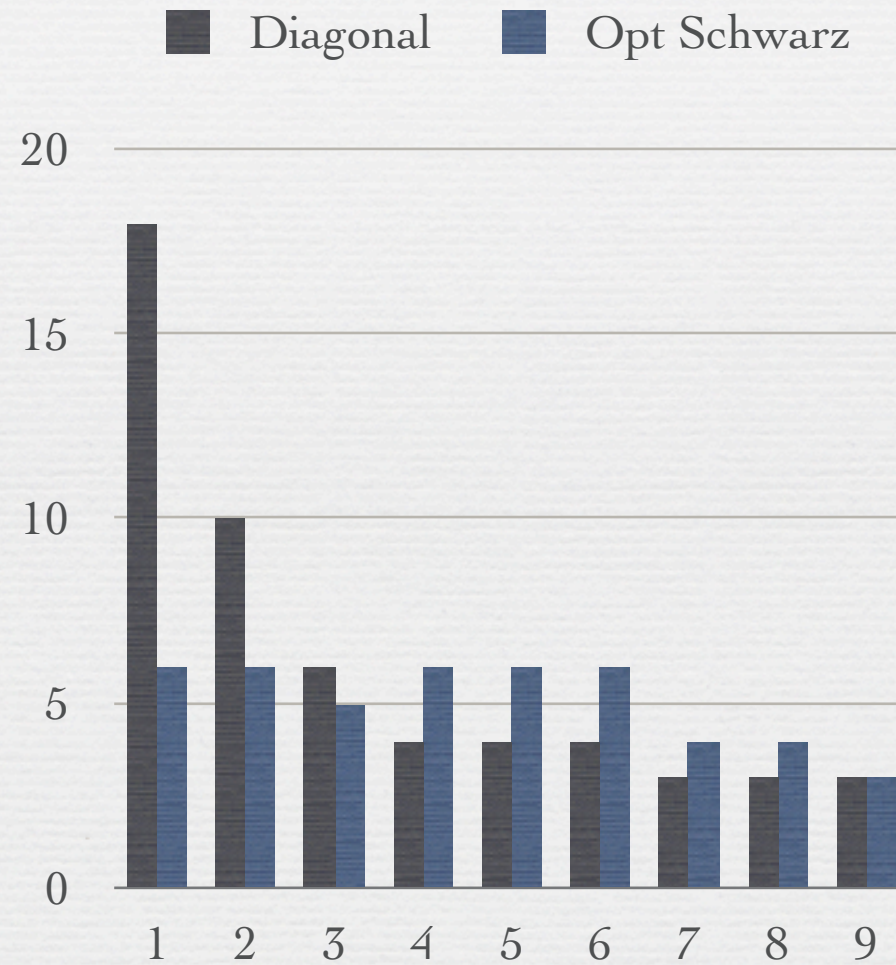


# Optimized Schwarz

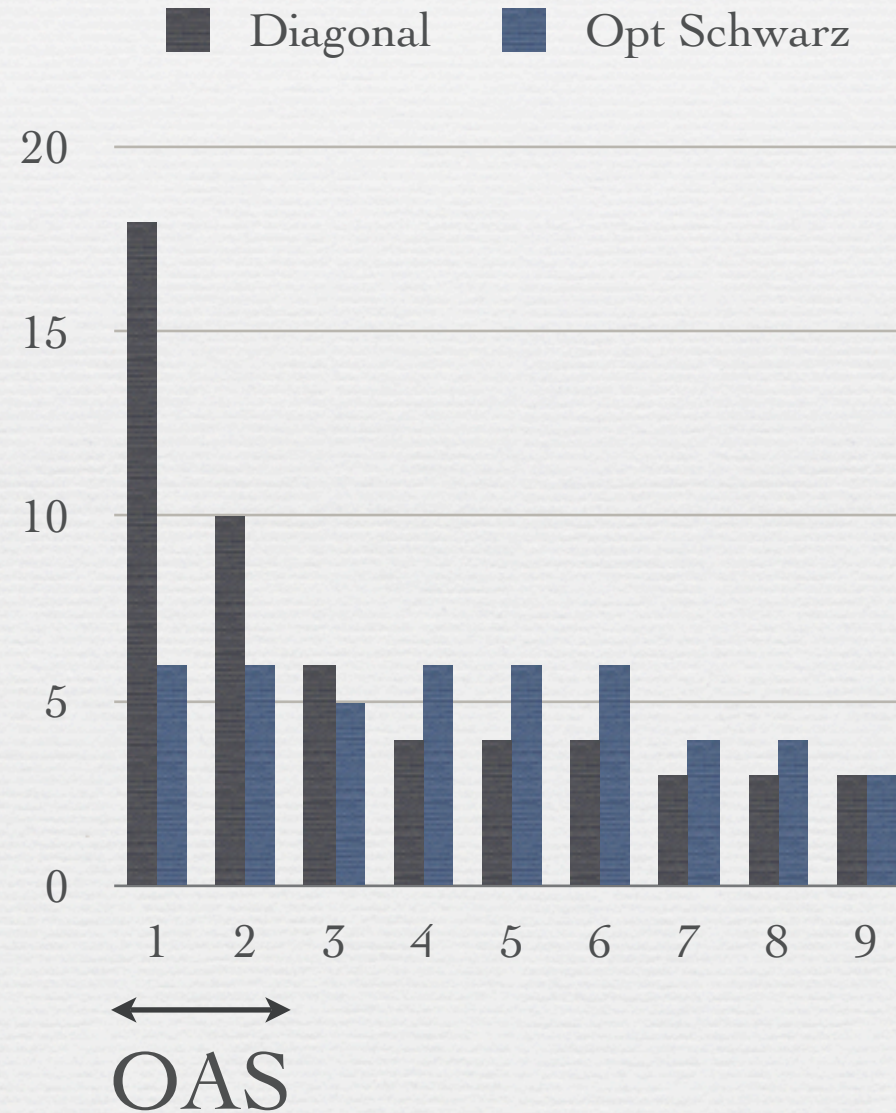




# New approach

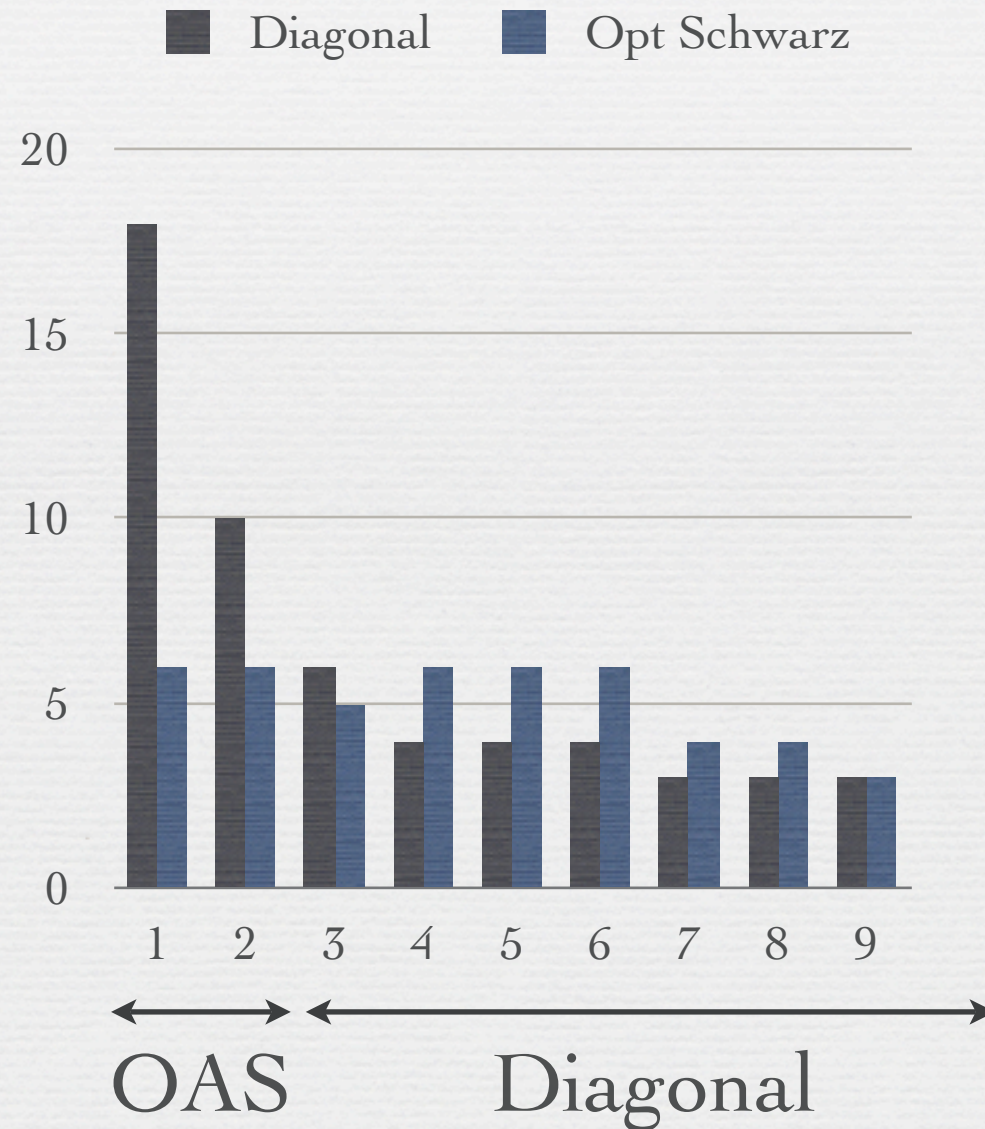


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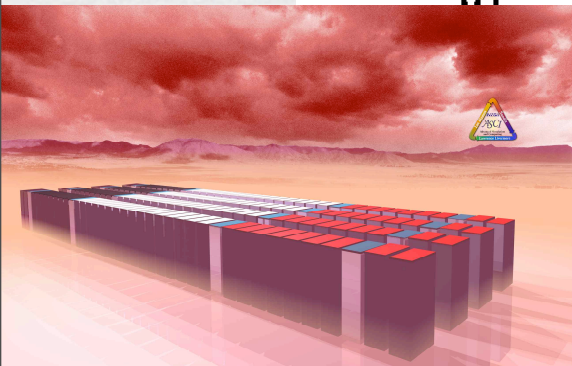
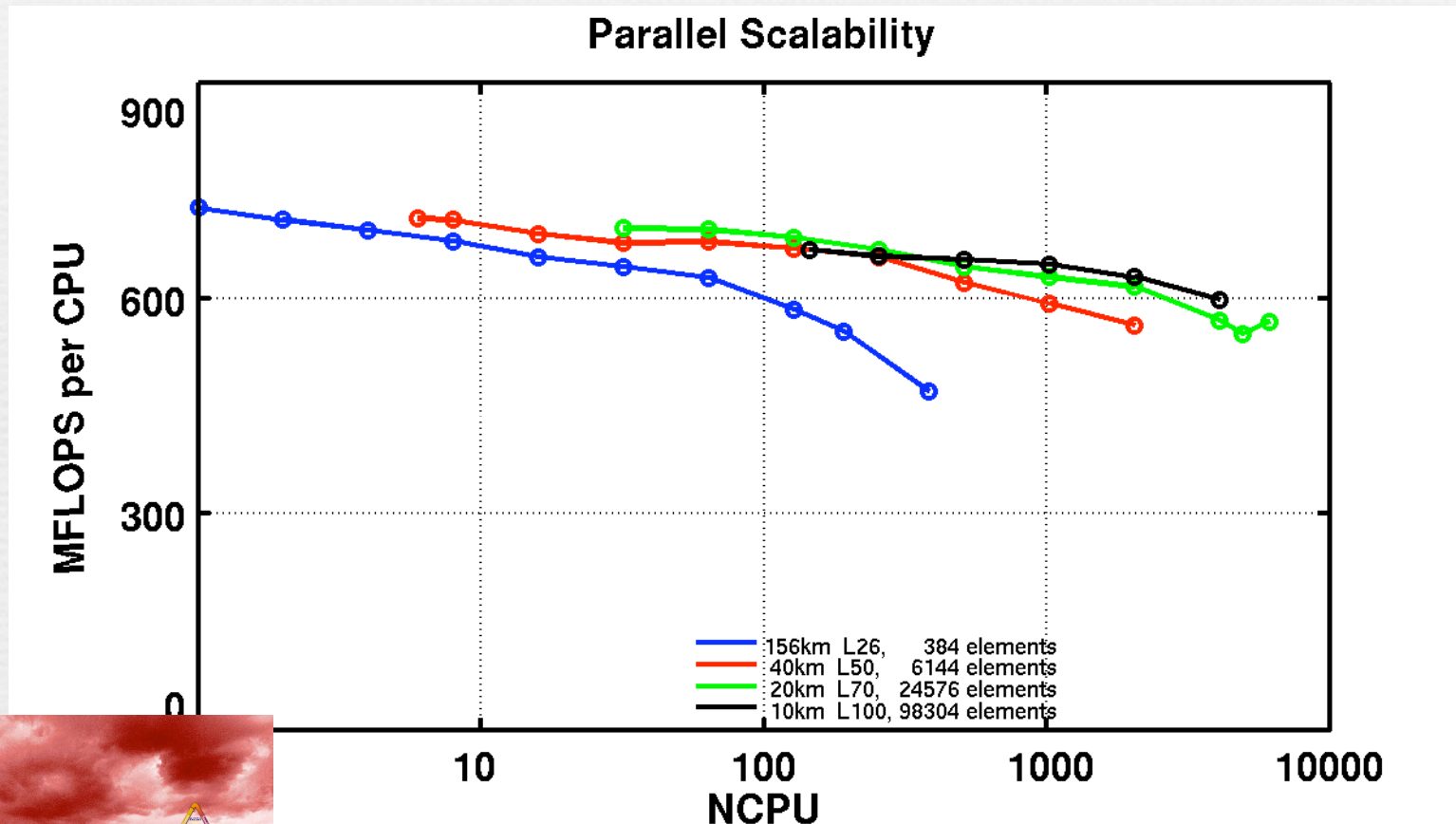




# New approach



# Large scale runs

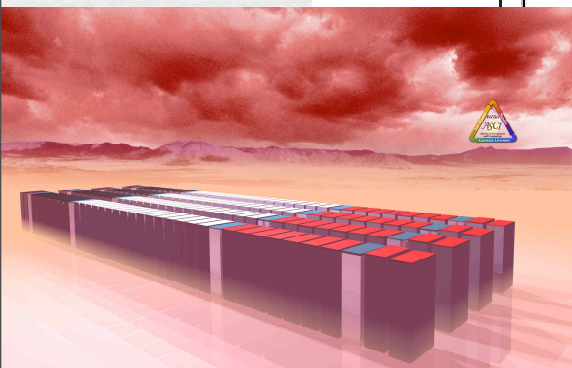
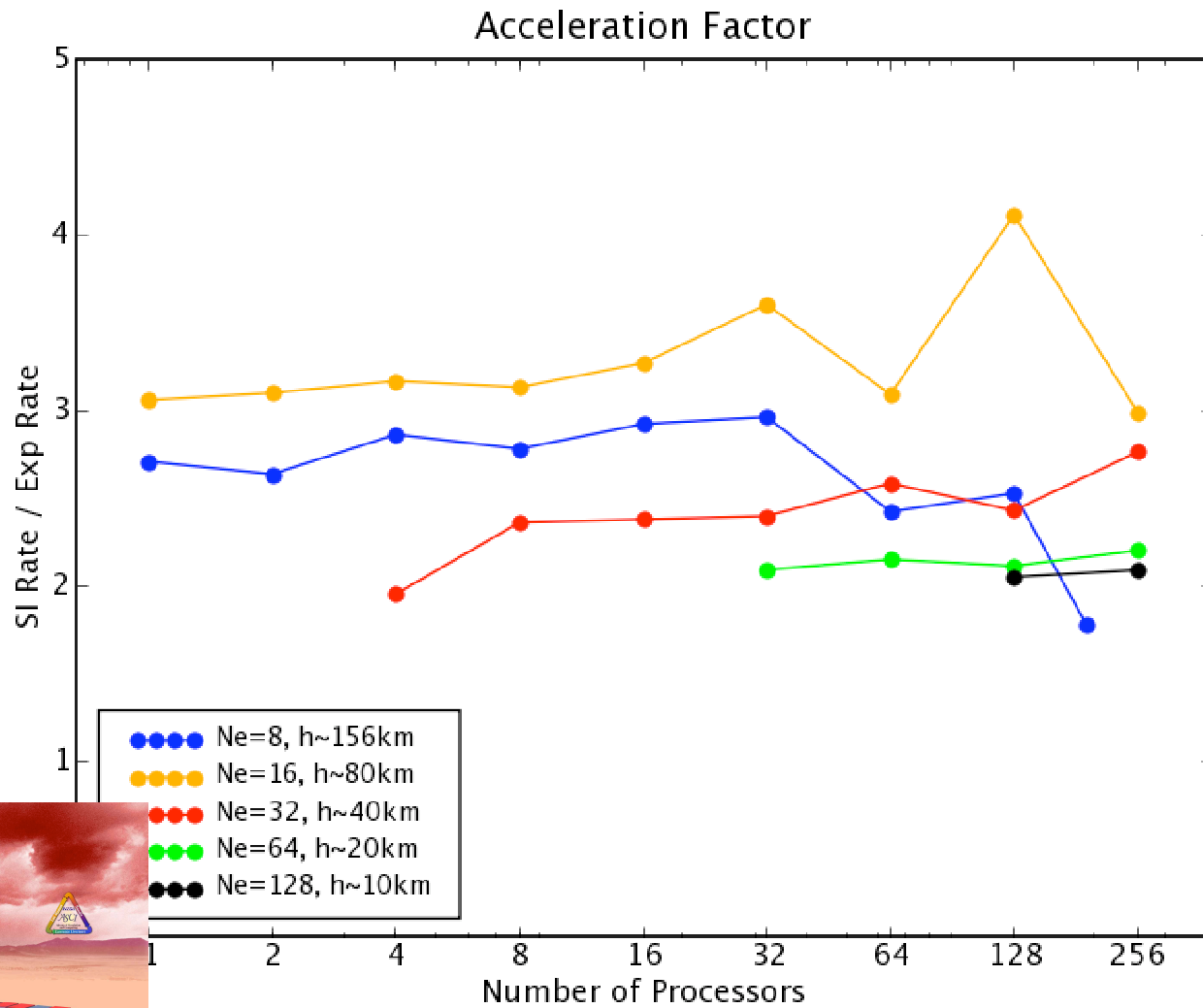


Max 5TF

W. Spotz and M. Taylor: Sandia National Labs



# Si vs Exp: Red Storm



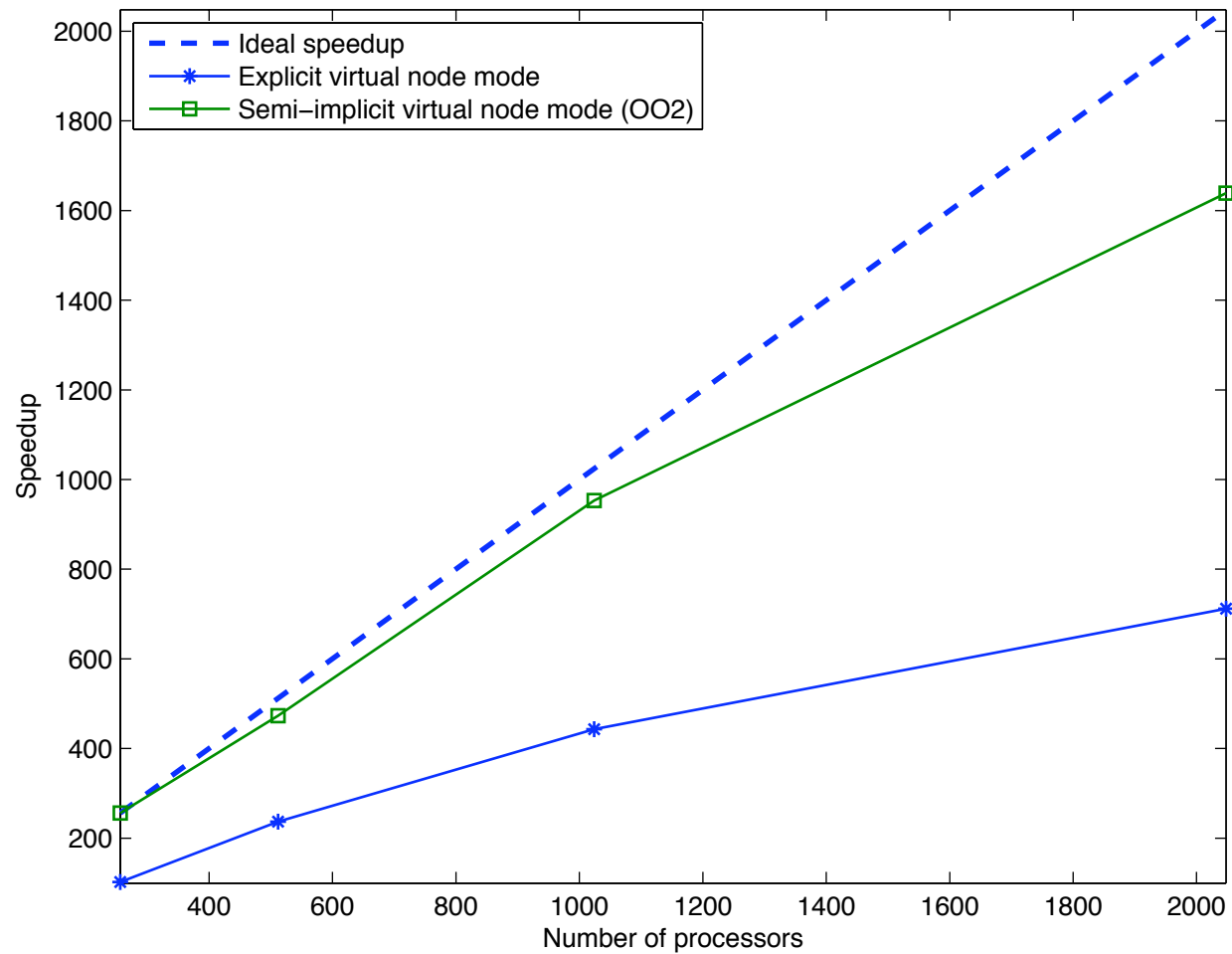
W. Spetz : Sandia National Labs

# Si vs Exp: Blue gene

ne=32, 40km



# Si vs Exp: Blue gene

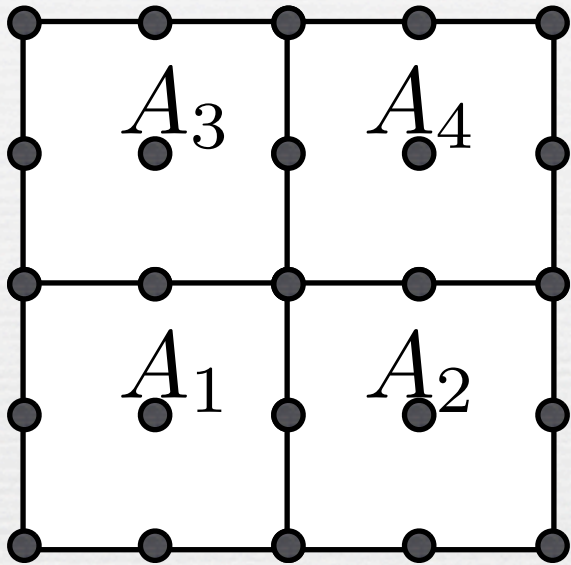


ne=32, 40km

# Adaptive Mesh Refinements



# Conforming SEM

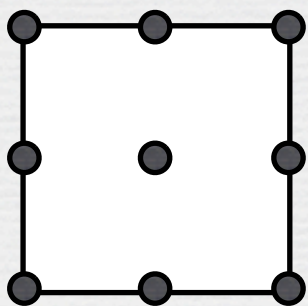


Linear problem associated with elliptic problem discretized with SEM

$$Au = f$$

$$A_L = \text{block}\{A_1, A_2, A_3, A_4\}$$

$$v^T Au = v^T Q^T A_L Qu = v^T Q^T M_L Q f = v^T f$$

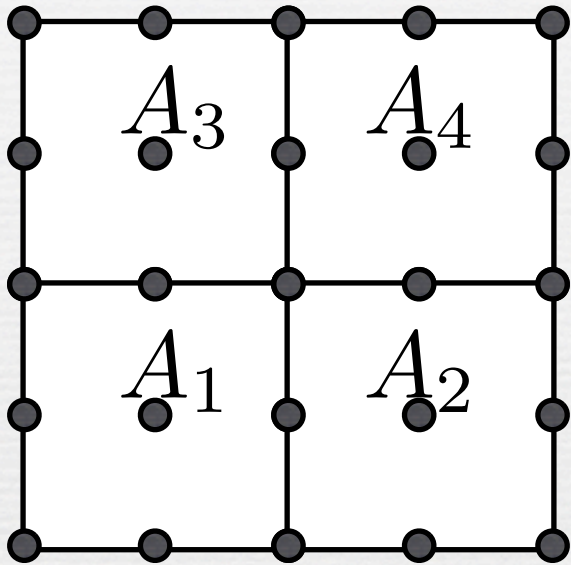


$A_k$   
 $f_k$   
 $u_k$

$$v^T Q^T A_L u_L = v^T Q^T M_L f_L$$

$$QQ^T A_L u_L = QQ^T M_L f_L$$

# Conforming SEM

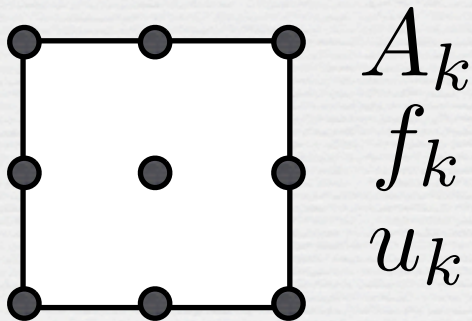


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$$Au = f$$

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$$v^T Au = v^T Q^T A_L Qu = v^T Q^T M_L Q f = v^T f$$



$$v^T Q^T A_L u_L = v^T Q^T M_L f_L$$

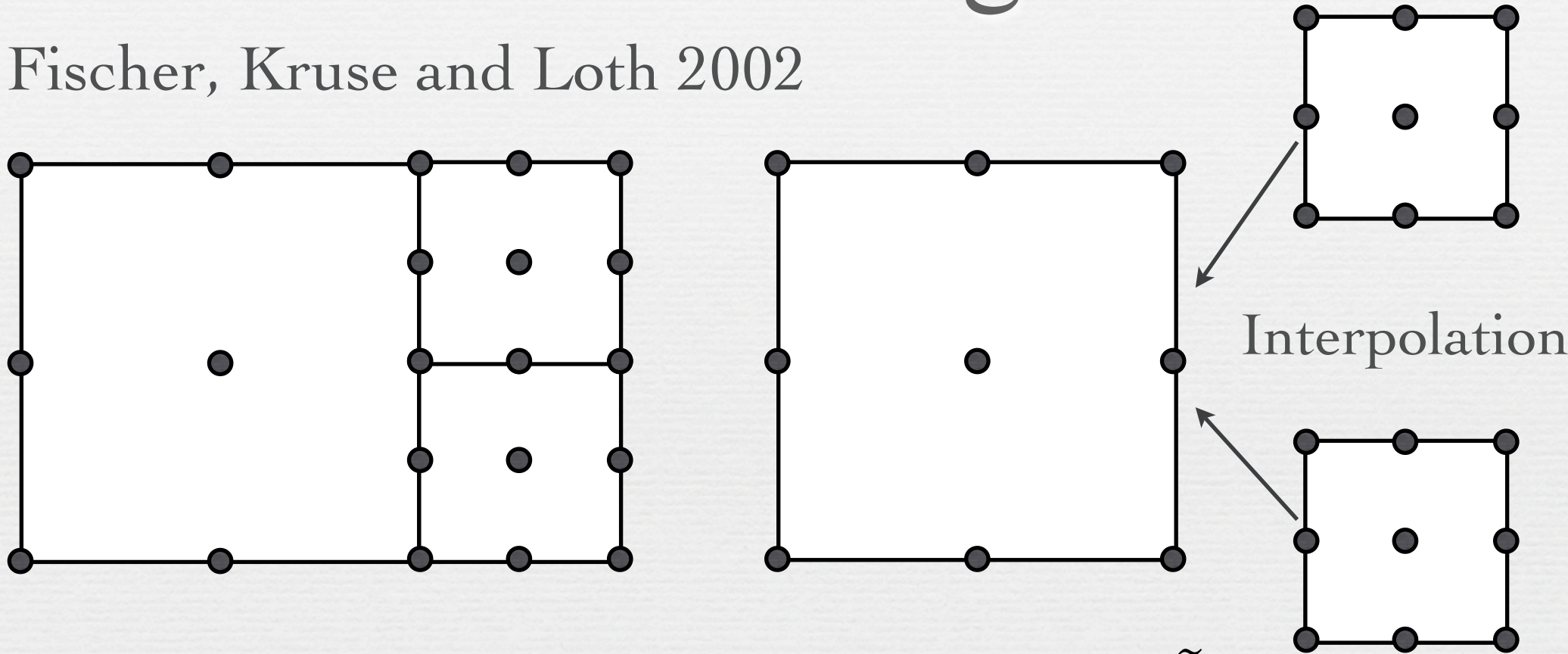
$$\boxed{QQ^T} A_L u_L = QQ^T M_L f_L$$

Direct stiffness summation: represents boolean operations



# Nonconforming SEM

Fischer, Kruse and Loth 2002



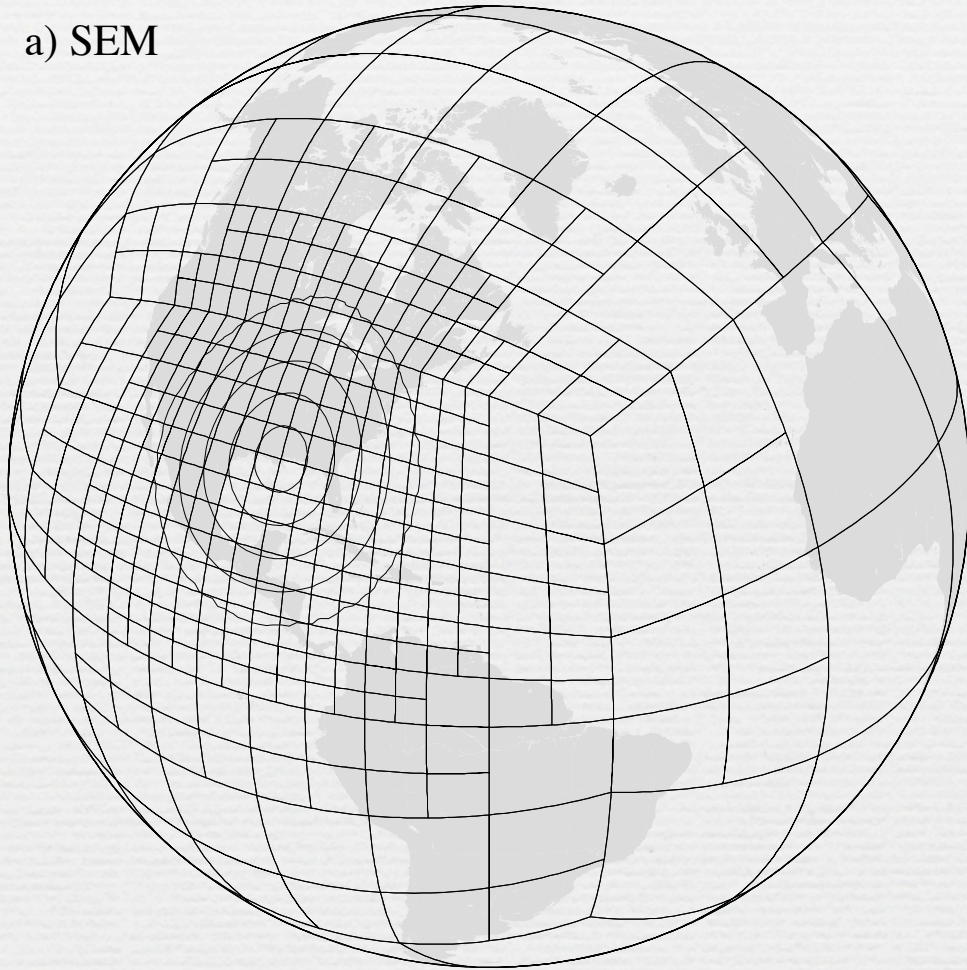
Boolean matrix  $Q$  is redefined as  $Q = J_L \tilde{Q}$

DSS is conceptually the same:

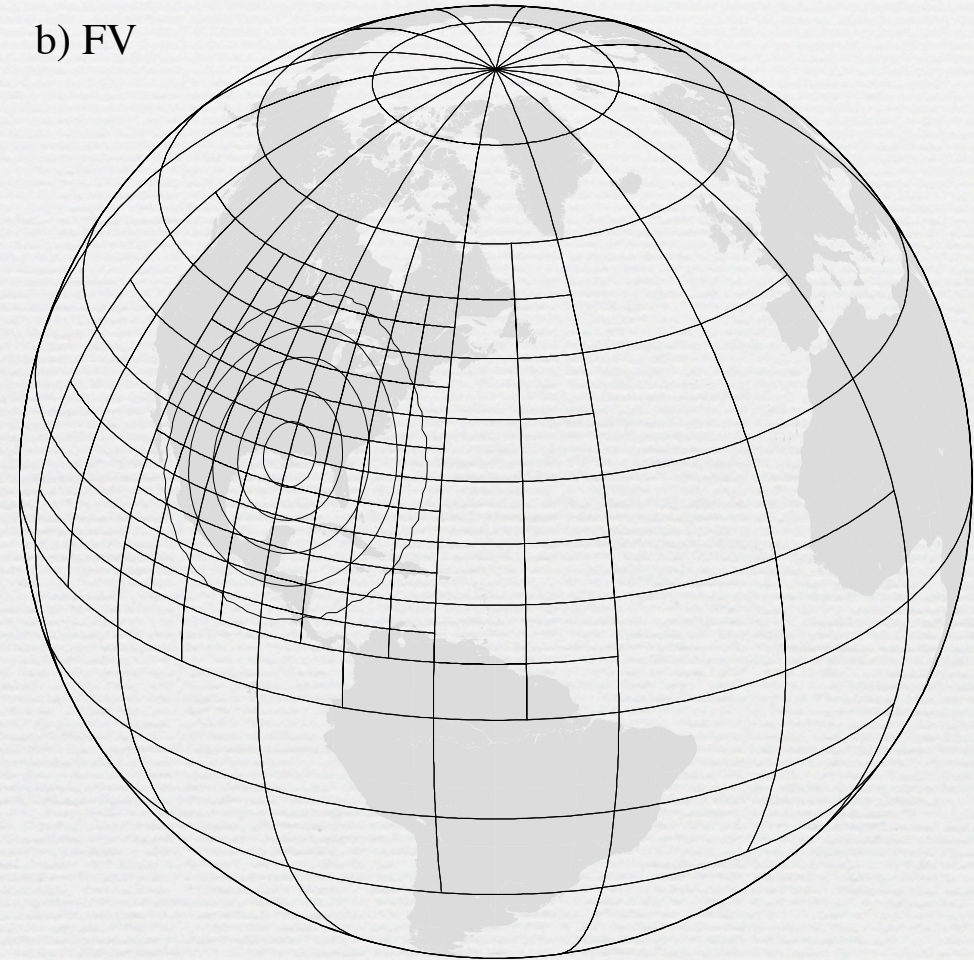
$$v^T A u = v^T (\tilde{Q}^T J_L^T) A_L (J_L \tilde{Q}) u = v^T Q^T A_L Q u.$$

# SEM vs FVM

a) SEM



b) FV



Standard test suite is employed



# Cosine bell advection

Alpha = 0

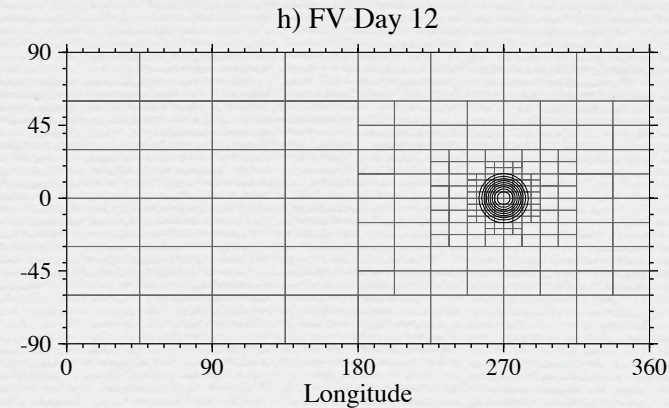
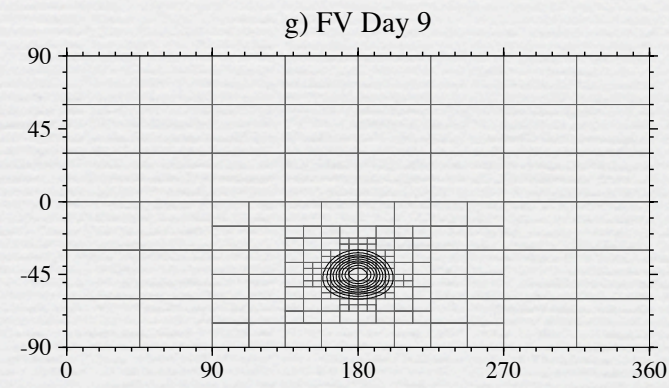
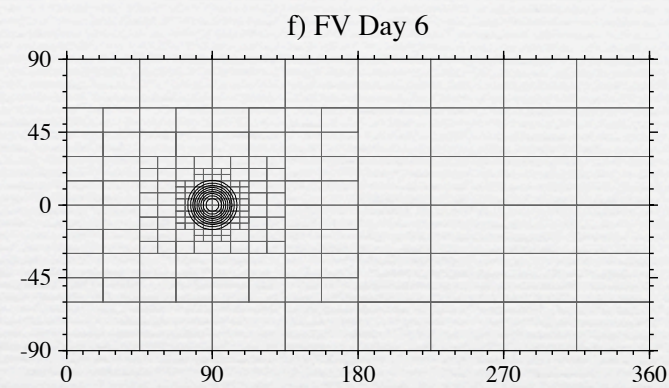
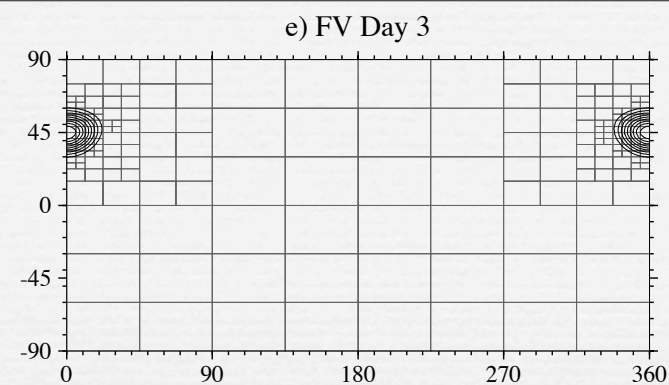
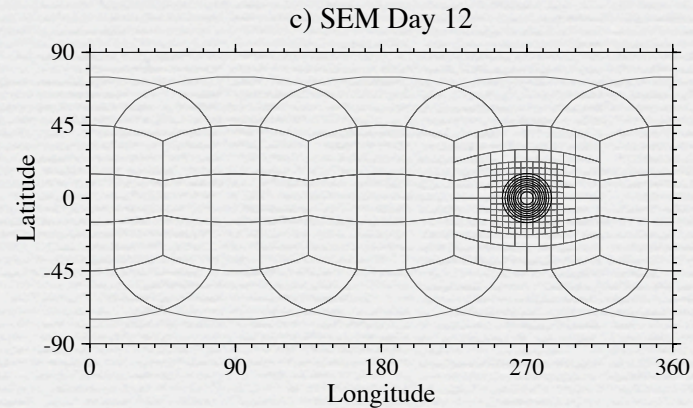
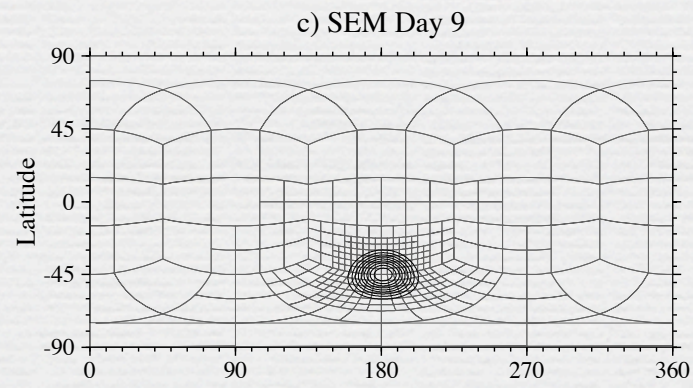
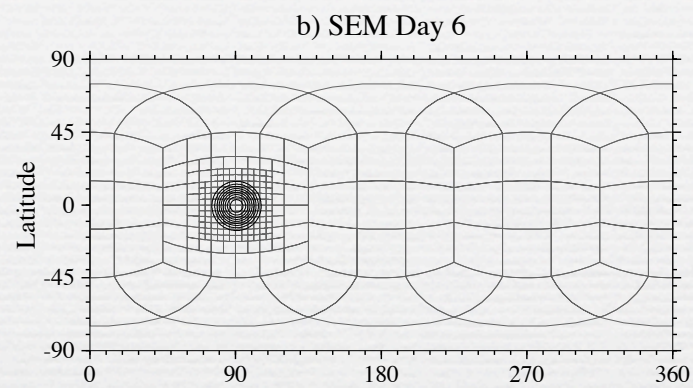
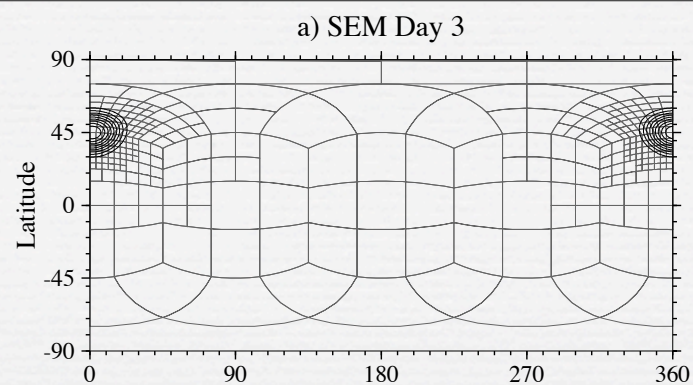
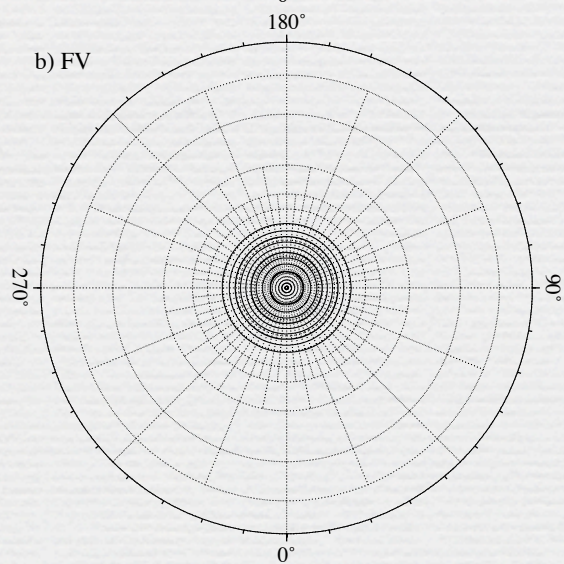
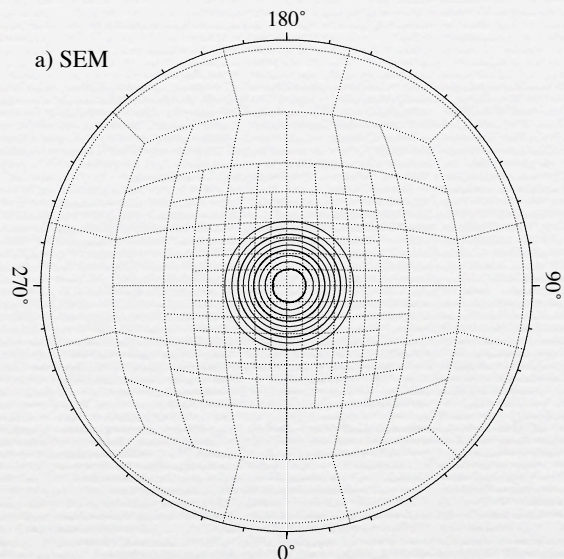
FV

SEM

Resolution	$l_1$	$l_2$	$l_\infty$	$h(m)$ max/min	Resolution	$l_1$	$l_2$	$l_\infty$	$h(m)$ max/min
2.5	0.0341	0.0301	0.0317	949.1/0	2.5	0.0503	0.0269	0.0195	991.6/-15.1
1.25	0.0097	0.0103	0.0150	984.2/0	1.25	0.0085	0.0056	0.0057	997.5/-4.2
0.625	0.0016	0.0021	0.0044	995.0/0	0.625	0.0019	0.0014	0.0019	999.1/-1.1
0.3125	0.0003	0.0005	0.0014	998.4/0	0.3125	0.0008	0.0006	0.0015	999.7/-0.9

- For alpha different than 0 : FV has undershoots
- Conservation of mass breaks monotonicity

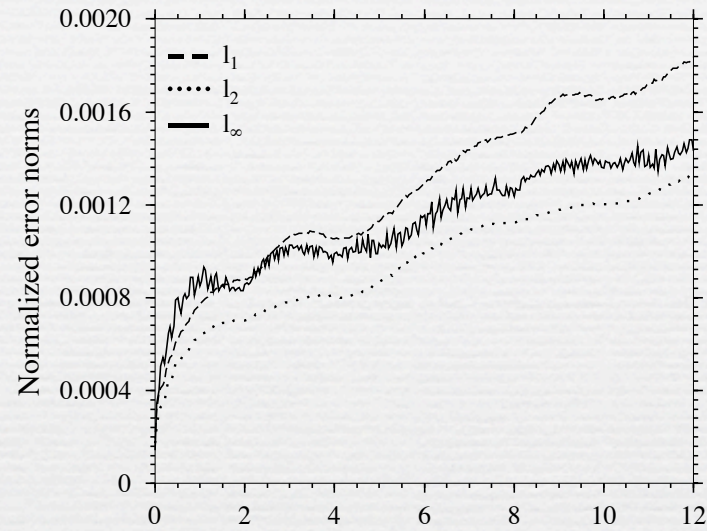




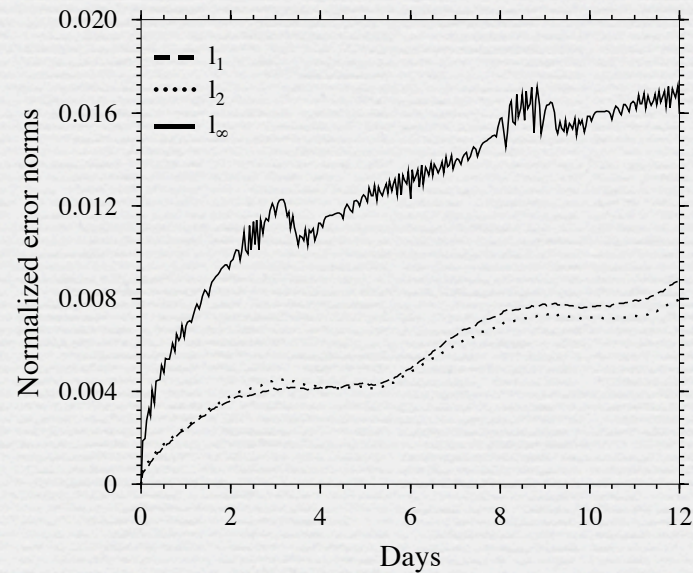


# SWTC1 45 degrees

a) SEM

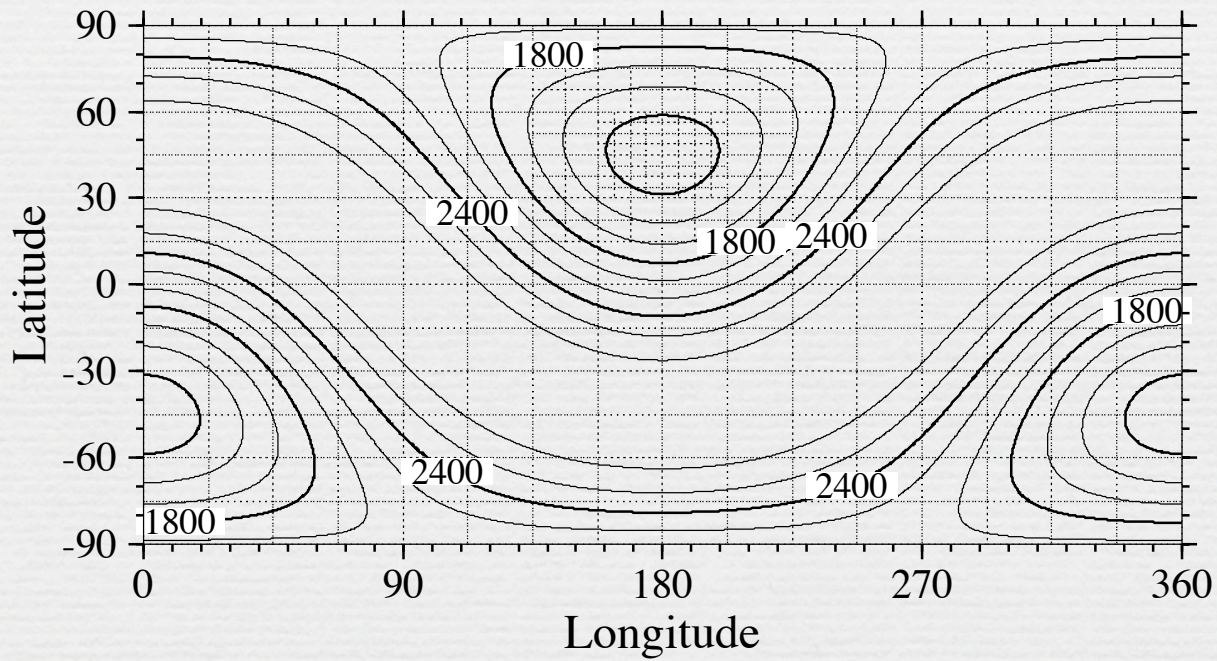


b) FV

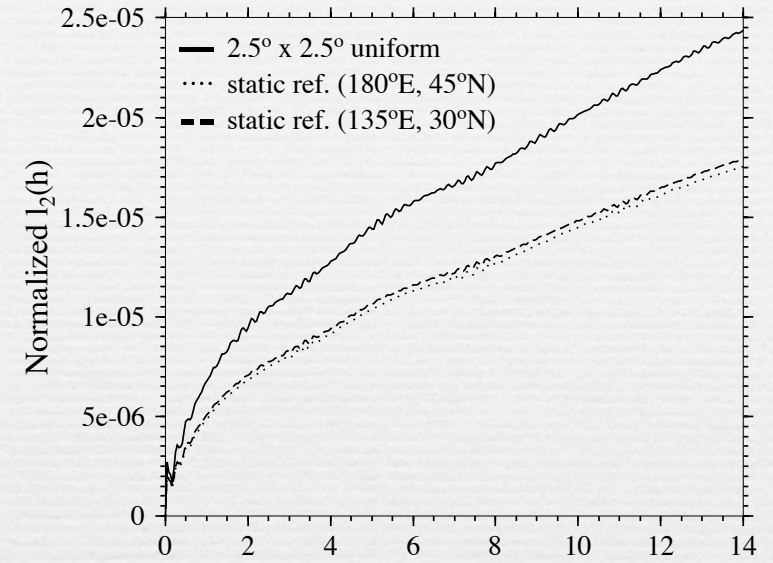




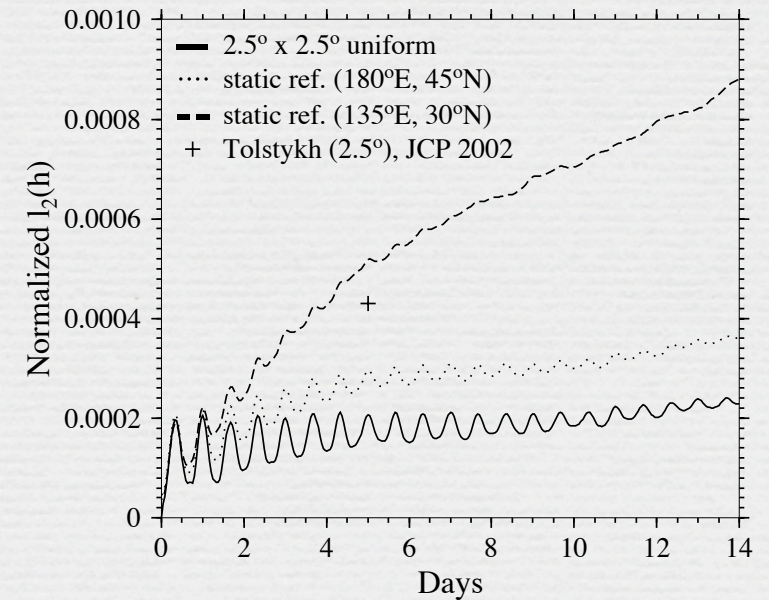
# SWTC2



a) SEM

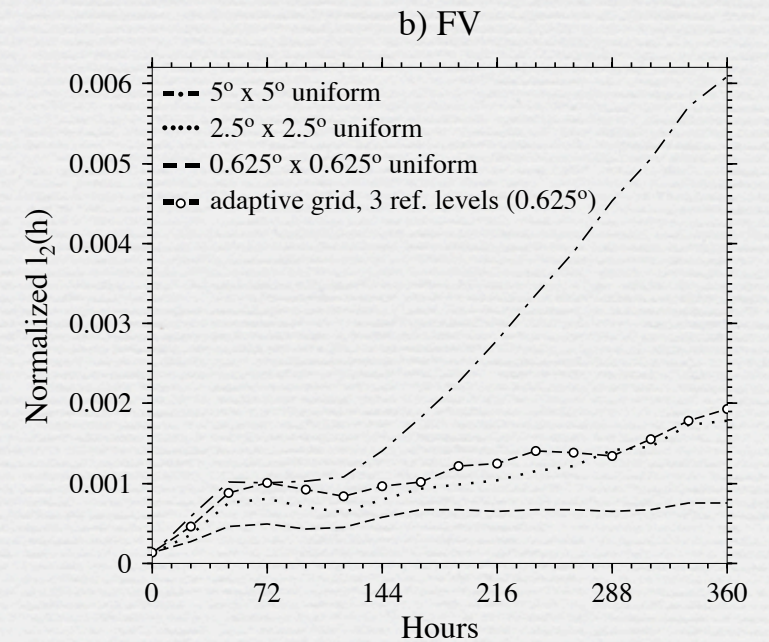
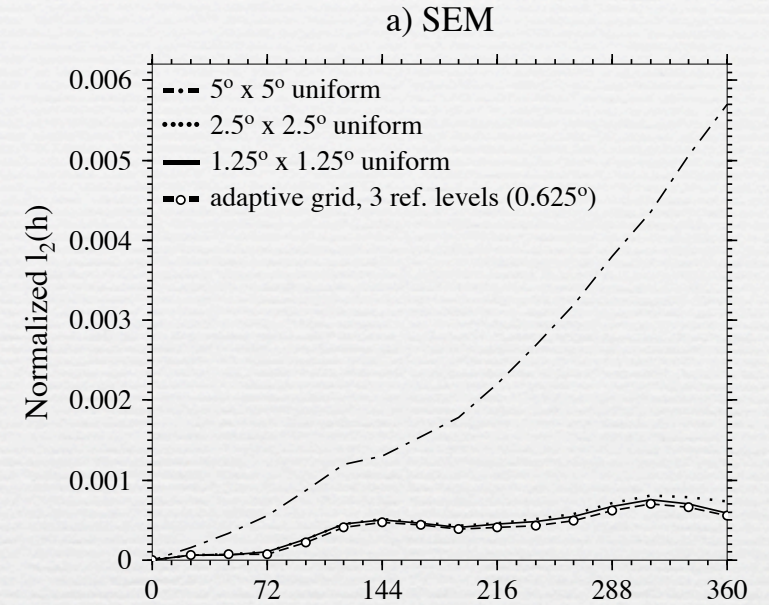
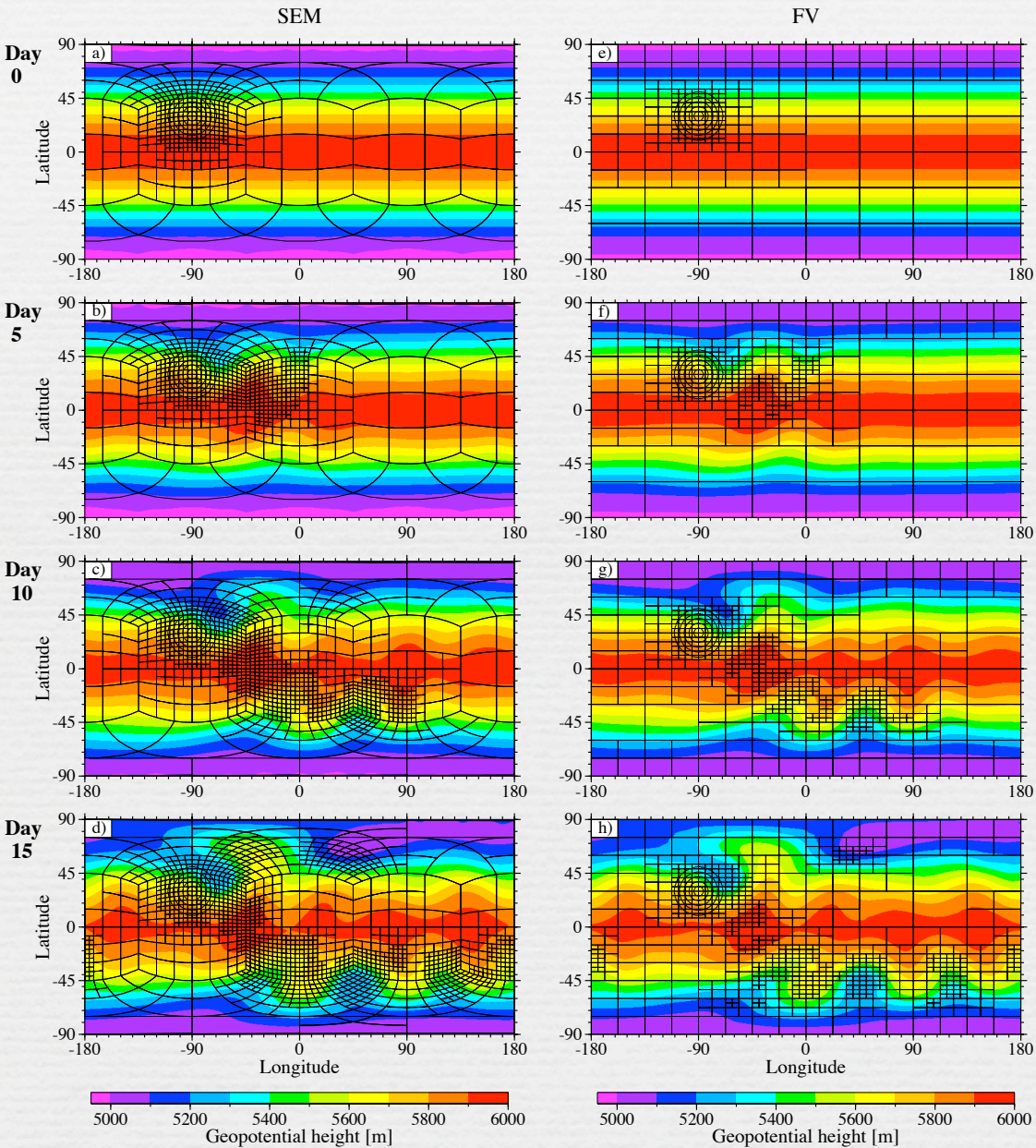


b) FV





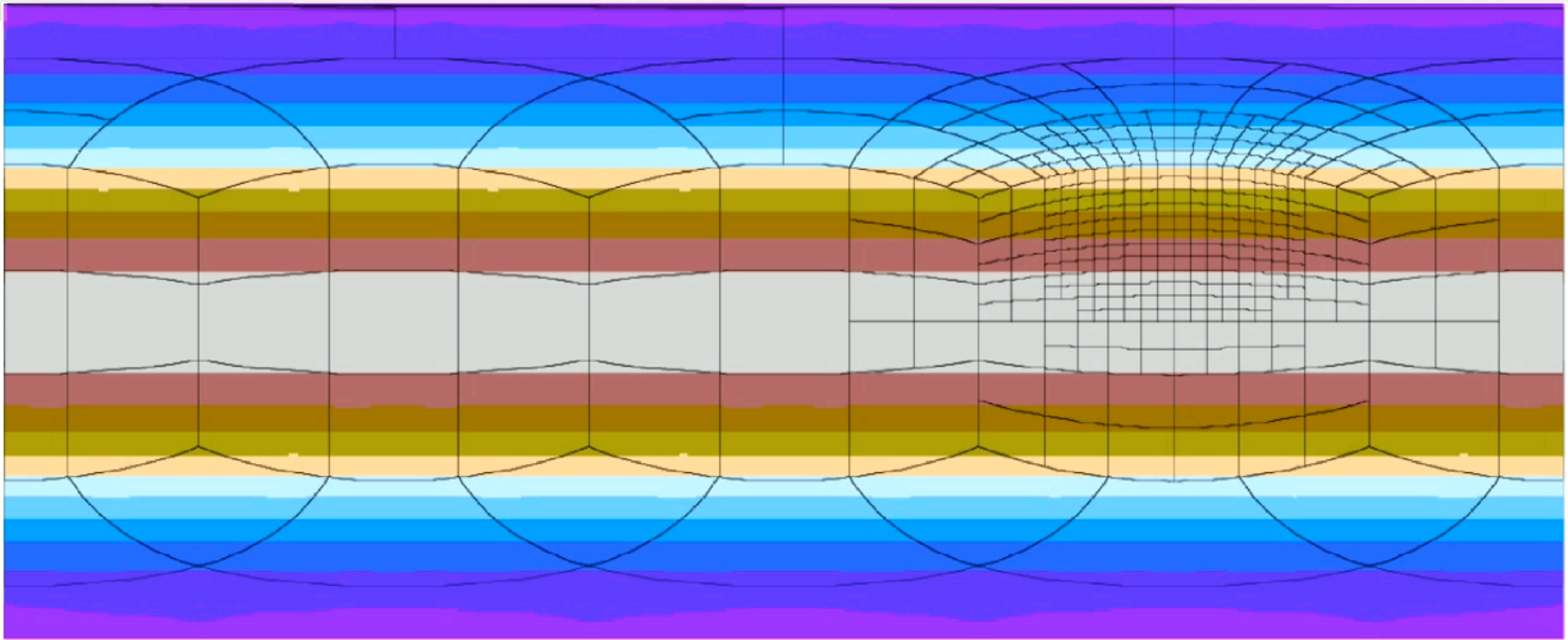
# SWTC5



# SWTC5

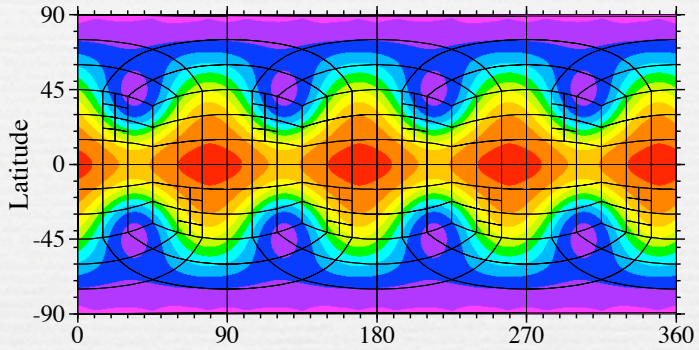


# SWTC5

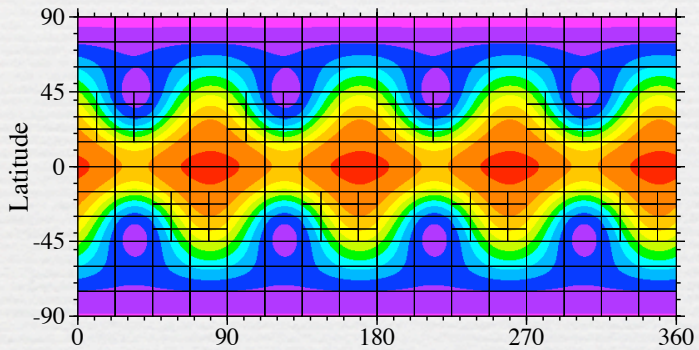


# SWTC6

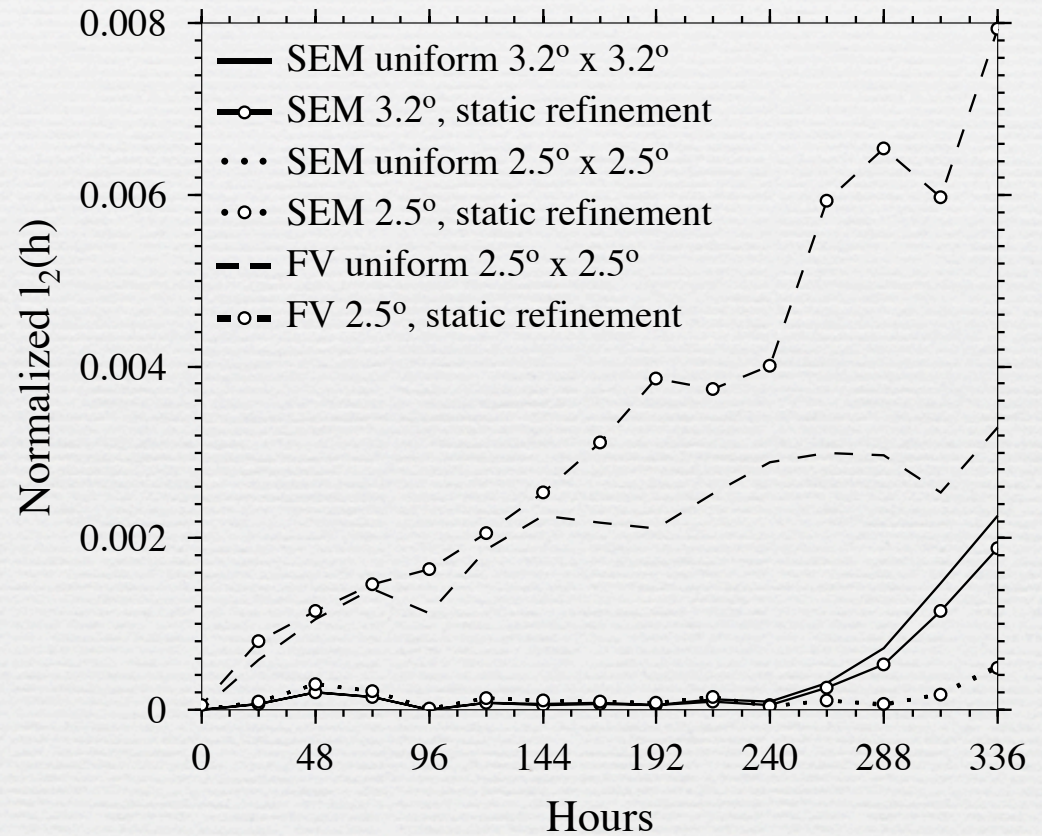
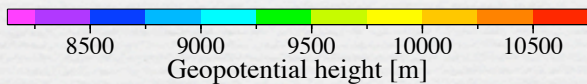
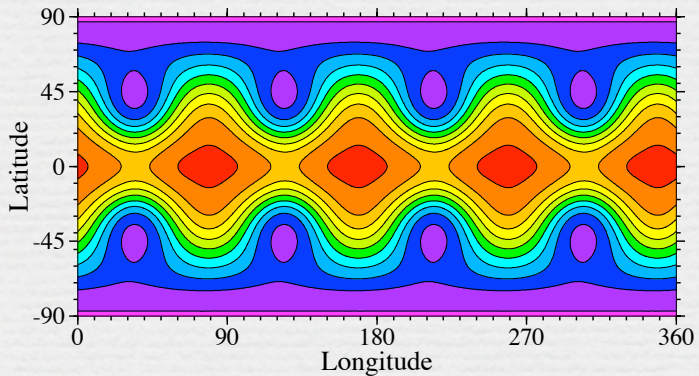
a) SEM



b) FV



c) NCAR reference





# Time-stepping

# OIFS+AMR

- Goal: SEM based AMR for primitive equations
- Oliger and Sundstrom show ill posedness for any kind of boundary conditions
- Cannot use local time stepping: Berger Oliger (84)
- Semi-implicit semi-Lagrangian approach? (Robert 81)



# OIFS+AMR

- Goal: SEM based AMR for primitive equations
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- Cannot use local time stepping: Berger Oliger (84)
- Semi-implicit semi-Lagrangian approach? (Robert 81)
- SISL is rather inefficient on modern computers
- Attempts were made by Berhens: shmem only (96)

# SISL

$$\frac{d\phi(X, t)}{dt} = \frac{\partial\phi}{\partial t} + \mathbf{u} \cdot \nabla\phi = f(\phi(X, t))$$

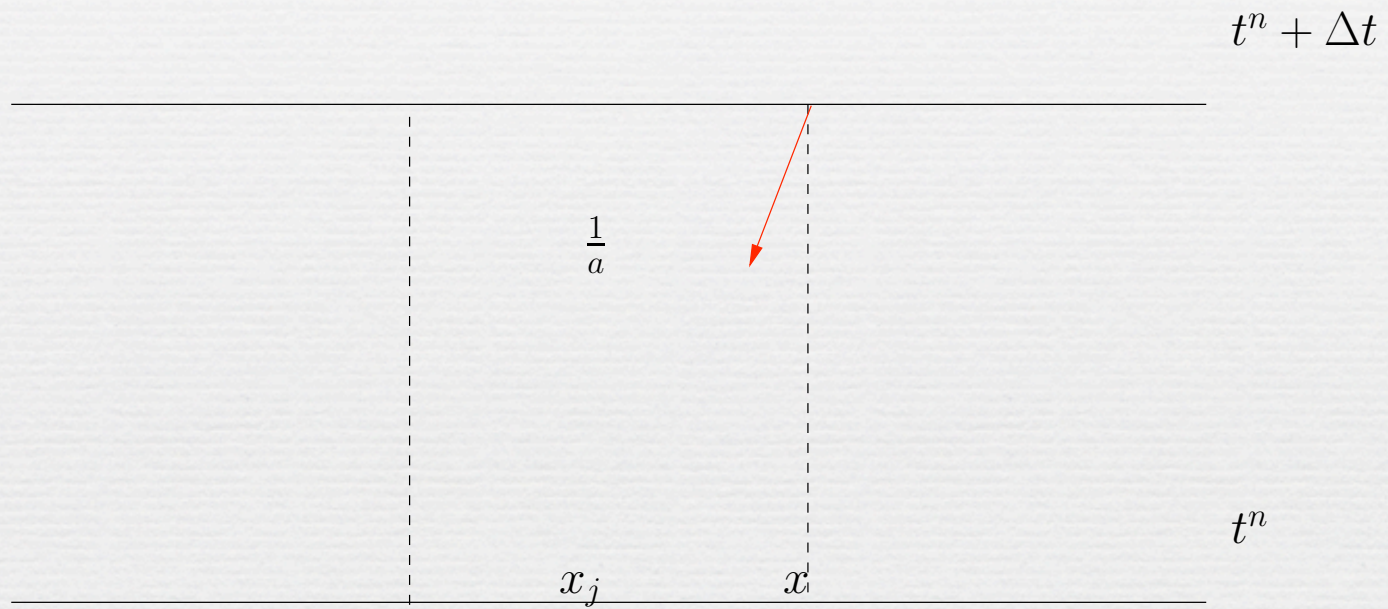
- Material derivative (hide advective term)
- Spatial position is now a function of time in the Lagrangian frame

Characteristic equation:  $\frac{dX}{dt} = u(X, t)$

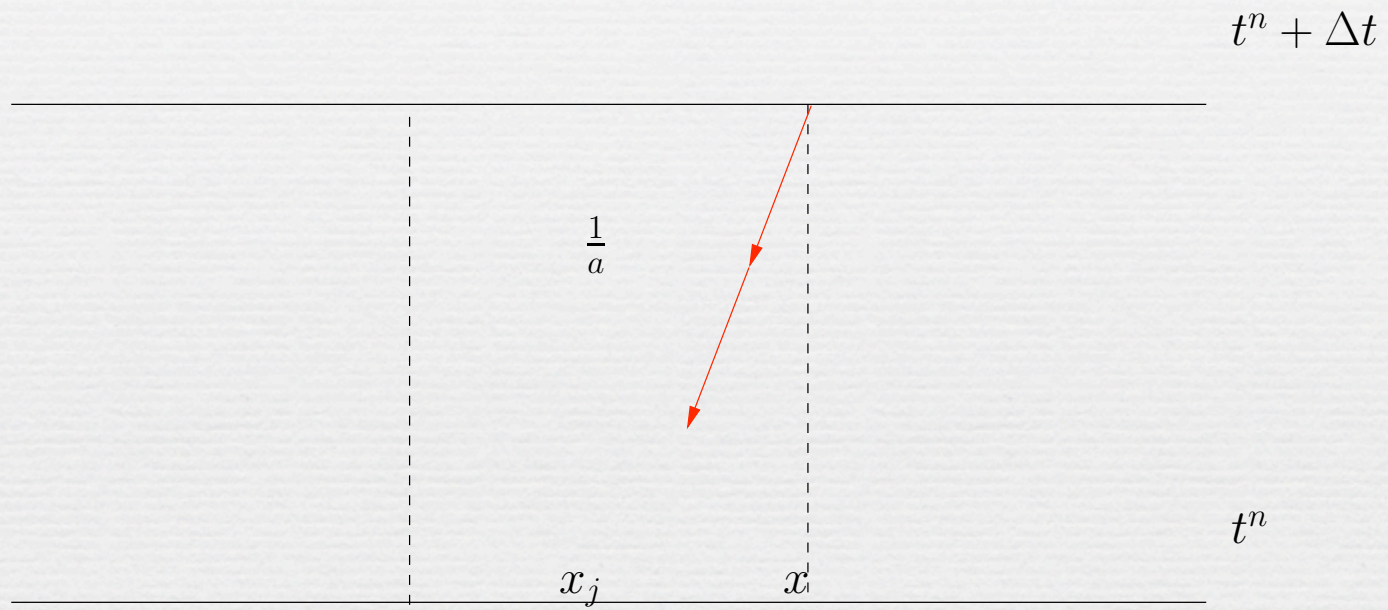
$$X^n = X^{n+1} - \frac{\Delta t}{2} (\mathbf{u}(X^n, t^n) + \mathbf{u}(X^{n+1}, t^{n+1})), \text{ with } X(t^{n+1}) = x$$



# SISL

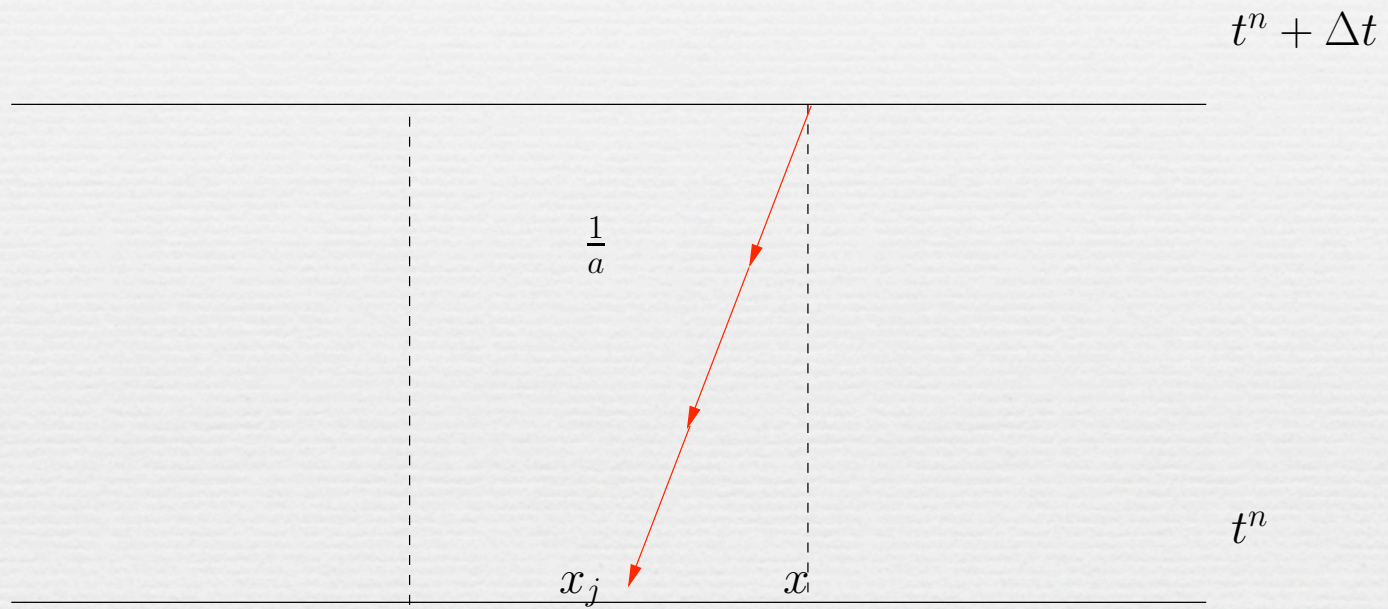


# SISL





# SISL



# Operator integrating factor splitting

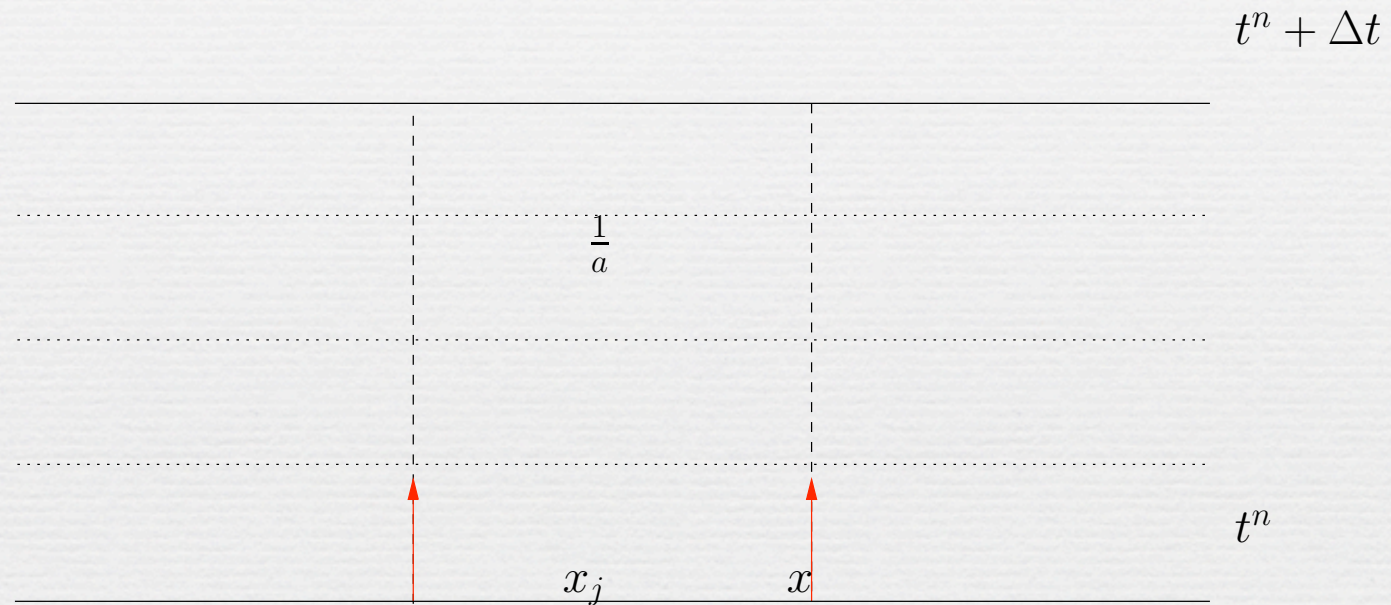
- Maday, Patera, Ronquist (90): OIFS.
- $K$  elements of order  $N$ ,  $K N^d$  grid points
- Interpolation  $K N^{2d}$
- Scalar advection requires  $d K N^{d+1}$
- OIFS more efficient if sub-step  $< N^{d-1}$  "times"
- Purely Eulerian: regular communication patterns
- Nonlinear OIFS: St-Cyr and Thomas (05)
- Euler (MC2): Girard, Thomas and St-Cyr (07)



# Operator integrating factor splitting

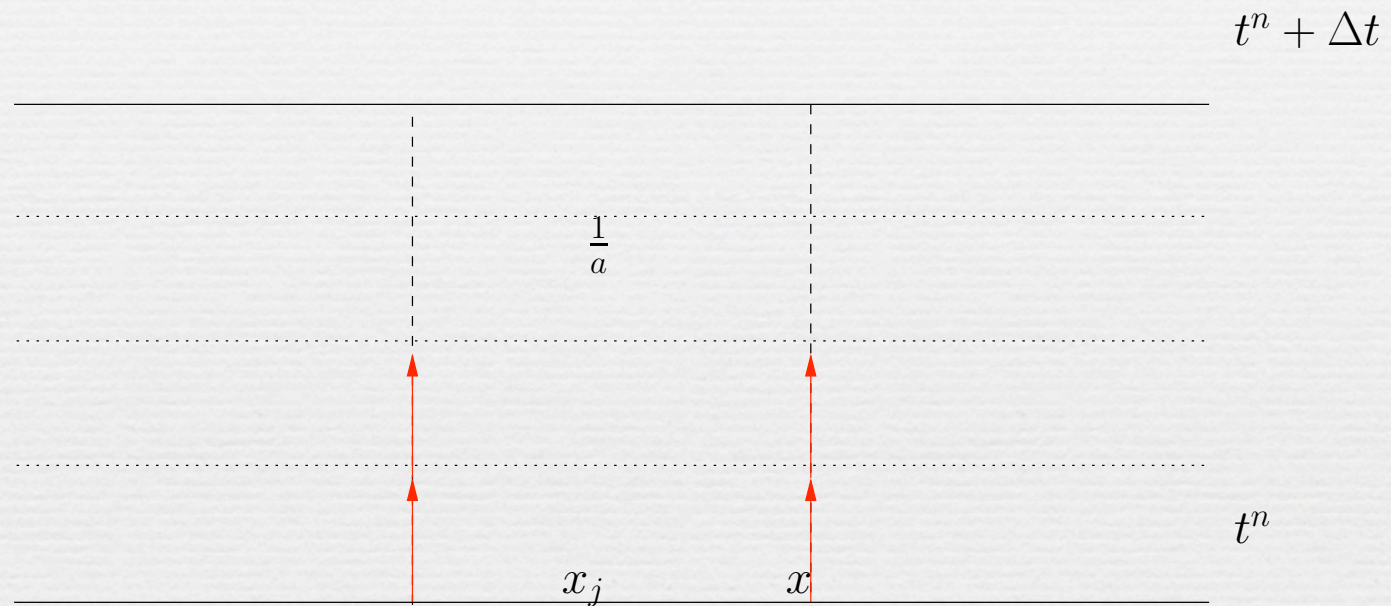
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# Operator integrating factor splitting

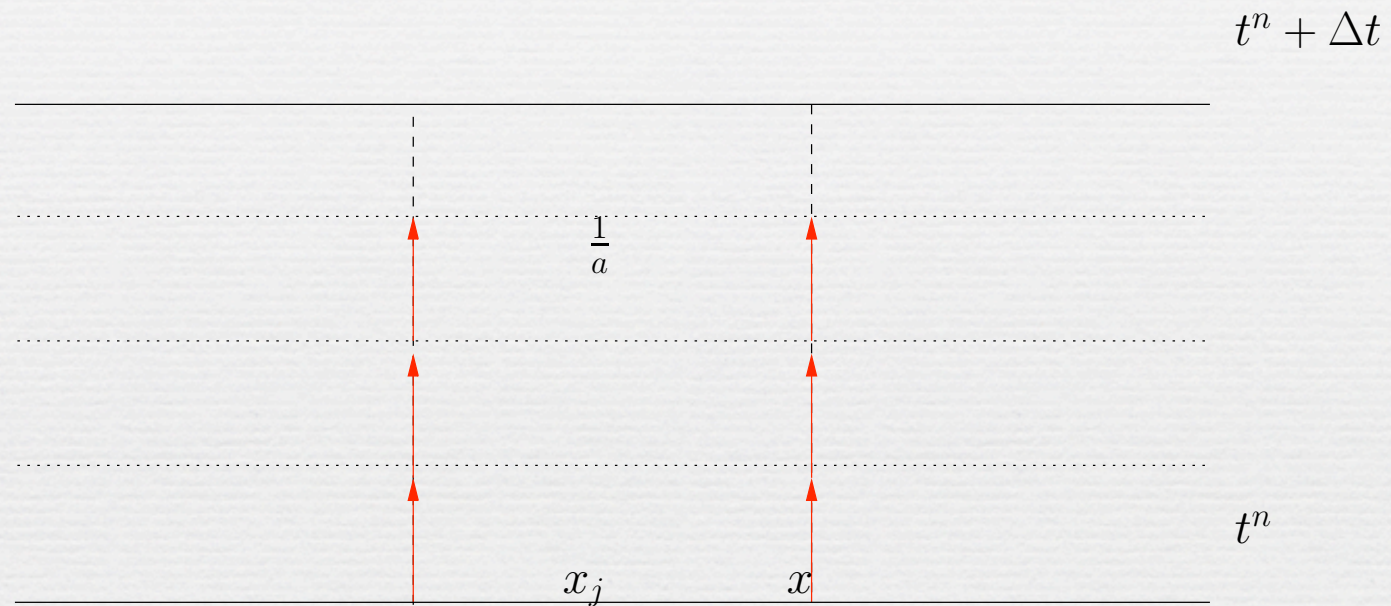




# Operator integrating factor splitting

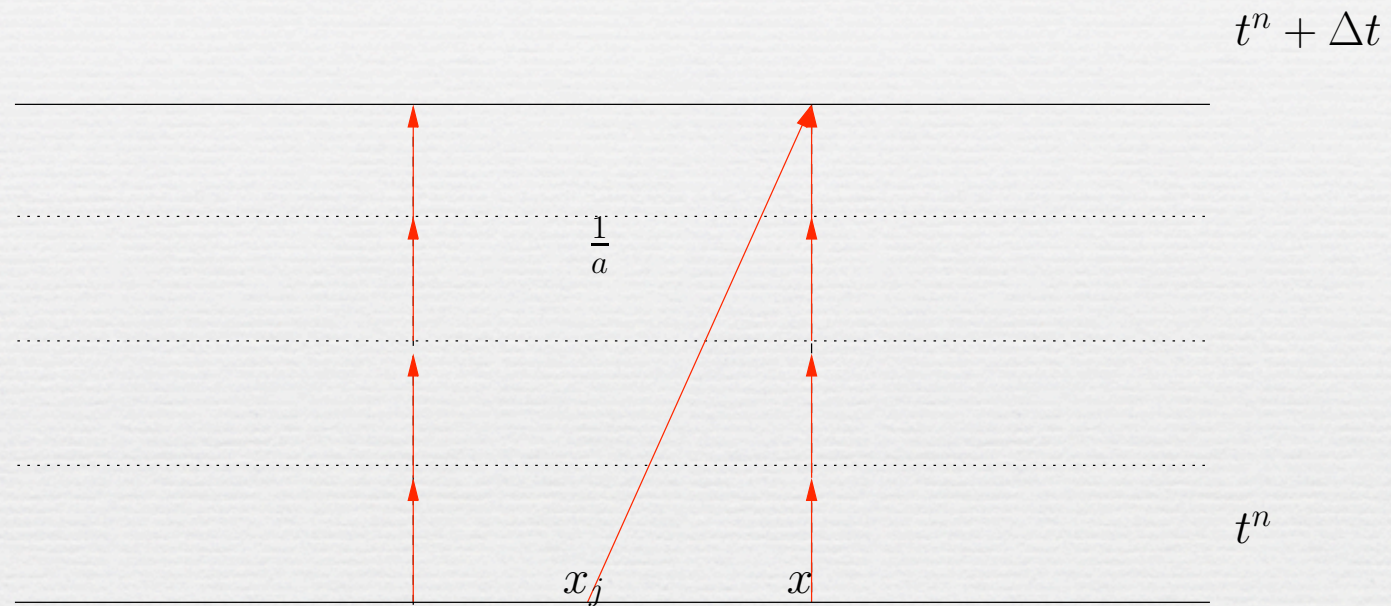


# Operator integrating factor splitting





# Operator integrating factor splitting



# Operator integrating factor splitting

ODE resulting from SEM discretization (MOL)

$$\frac{du(t)}{dt} = S(u(t)) + F(u(t)), \quad t \in [0, T]$$

with initial condition  $u(0) = u_0$

**Problem**: find integrating factor,  $Q_S^{t^*}(t)$  such that  $Q_S^{t^*}(t^*) = I$ ,

$$\frac{d}{dt} Q_S^{t^*}(t) \cdot u = Q_S^{t^*}(t) \cdot F(u).$$

To find the action of  $Q_S^{t^*}(t)$  solve:

$$\frac{dv^{(t^*,t)}(s)}{ds} = S(v^{(t^*,t)}), \quad 0 \leq s \leq t - t^*$$

with initial condition  $v^{(t^*,t)}(0) = u(t)$



# Nonlinear OIFS

St-Cyr and Thomas (2005) sub-step

$$\frac{\partial \tilde{\mathbf{v}}}{\partial s} + \tilde{\zeta} \mathbf{k} \times \tilde{\mathbf{v}} + \frac{1}{2} \nabla (\tilde{\mathbf{v}} \cdot \tilde{\mathbf{v}}) = 0$$

$$\frac{\partial \tilde{\Phi}}{\partial s} + \nabla \cdot (\tilde{\Phi} \tilde{\mathbf{v}}) = 0$$

with initial conditions  $\tilde{\mathbf{v}}(\mathbf{x}, t^{n-q}) = \mathbf{v}(\mathbf{x}, t^{n-q})$ ,  
 $\tilde{\Phi}(\mathbf{x}, t^{n-q}) = \Phi(\mathbf{x}, t^{n-q})$ .

# Nonlinear OIFS

Integration factor applied to the SWE's

$$\frac{d}{dt} Q_S^{t^*}(t) \begin{bmatrix} \mathbf{v} \\ \Phi \end{bmatrix} = -Q_S^{t^*}(t) \begin{bmatrix} f \mathbf{k} \times \mathbf{v} + \nabla \Phi \\ \Phi_0 \nabla \cdot \mathbf{v} \end{bmatrix}$$

Backward Differentiation Formula (BDF-2):

$$\frac{3\mathbf{v}^n - 4\tilde{\mathbf{v}}^{n-1} + \tilde{\mathbf{v}}^{n-2}}{2\Delta t} = -\mathbf{M} f \mathbf{v}^n - \nabla \Phi^n$$

$$\frac{3\Phi^n - 4\tilde{\Phi}^{n-1} + \tilde{\Phi}^{n-2}}{2\Delta t} = -\Phi_0 \nabla \cdot \mathbf{v}^n$$

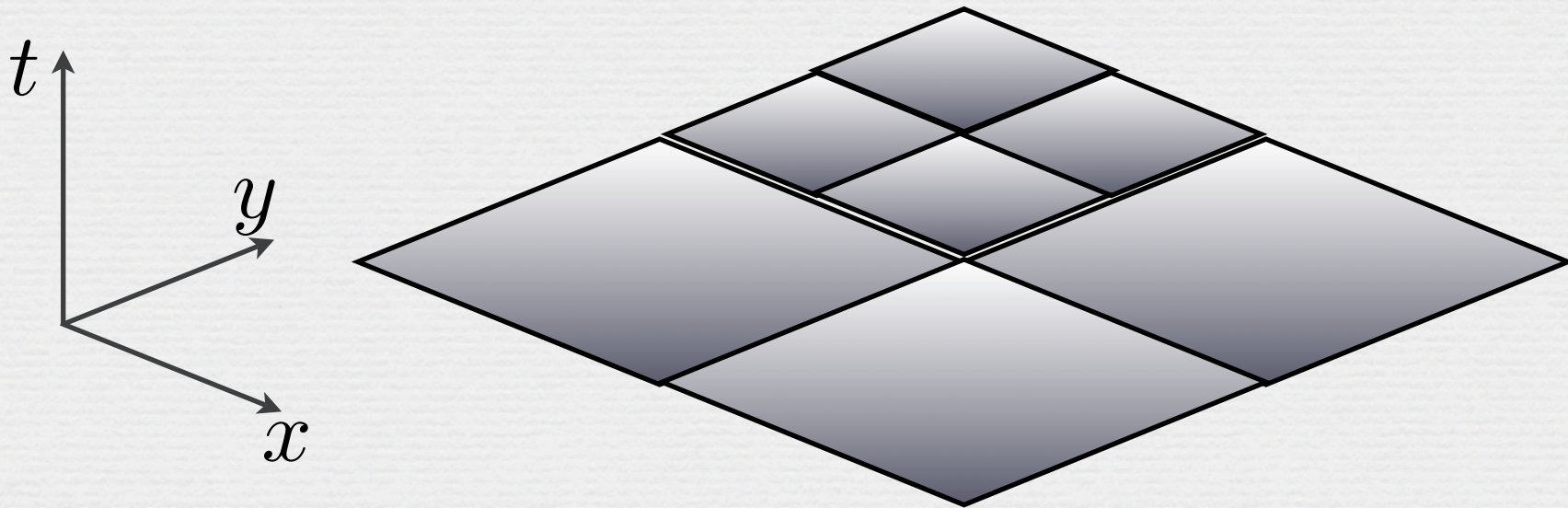
Terms responsible for

Coriolis inverted

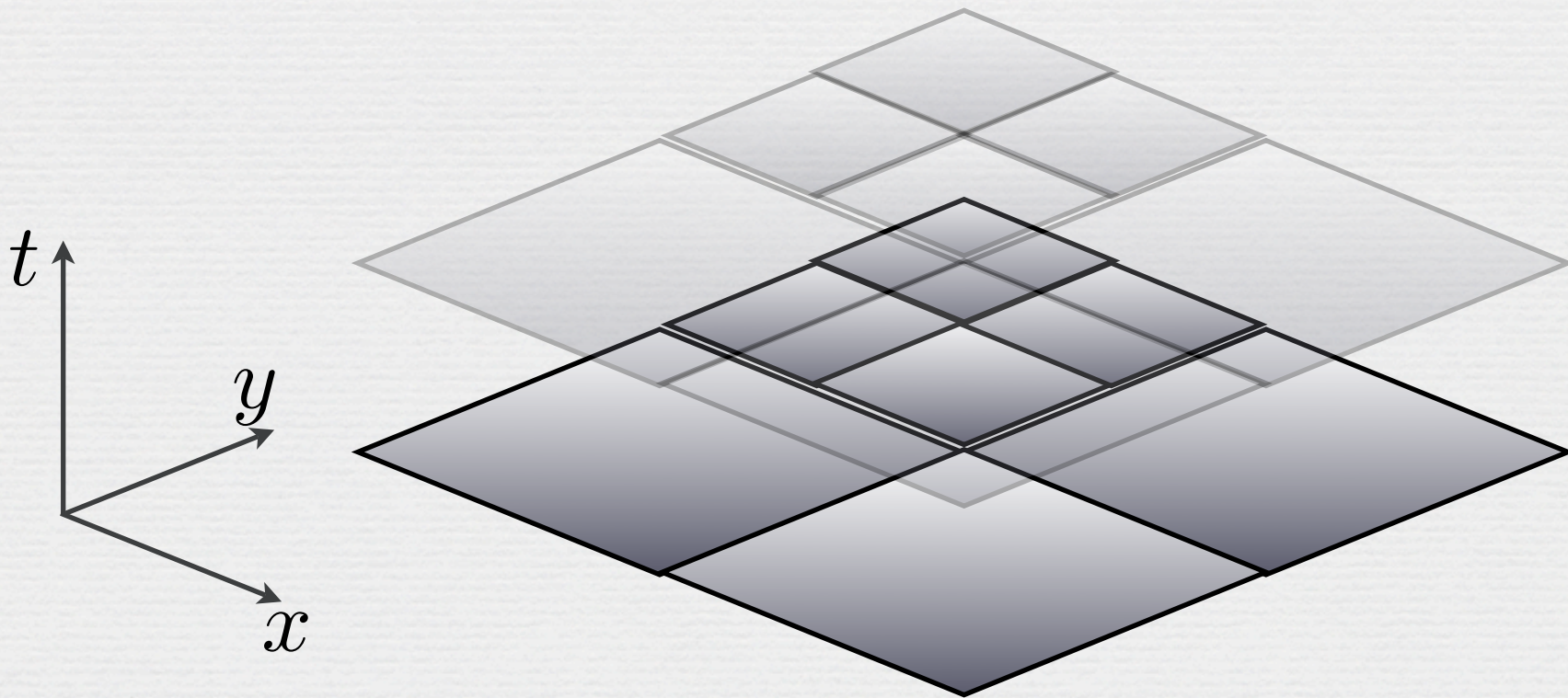
Non-symmetric due to implicit Coriolis: CGS.



# Implicit/Explicit

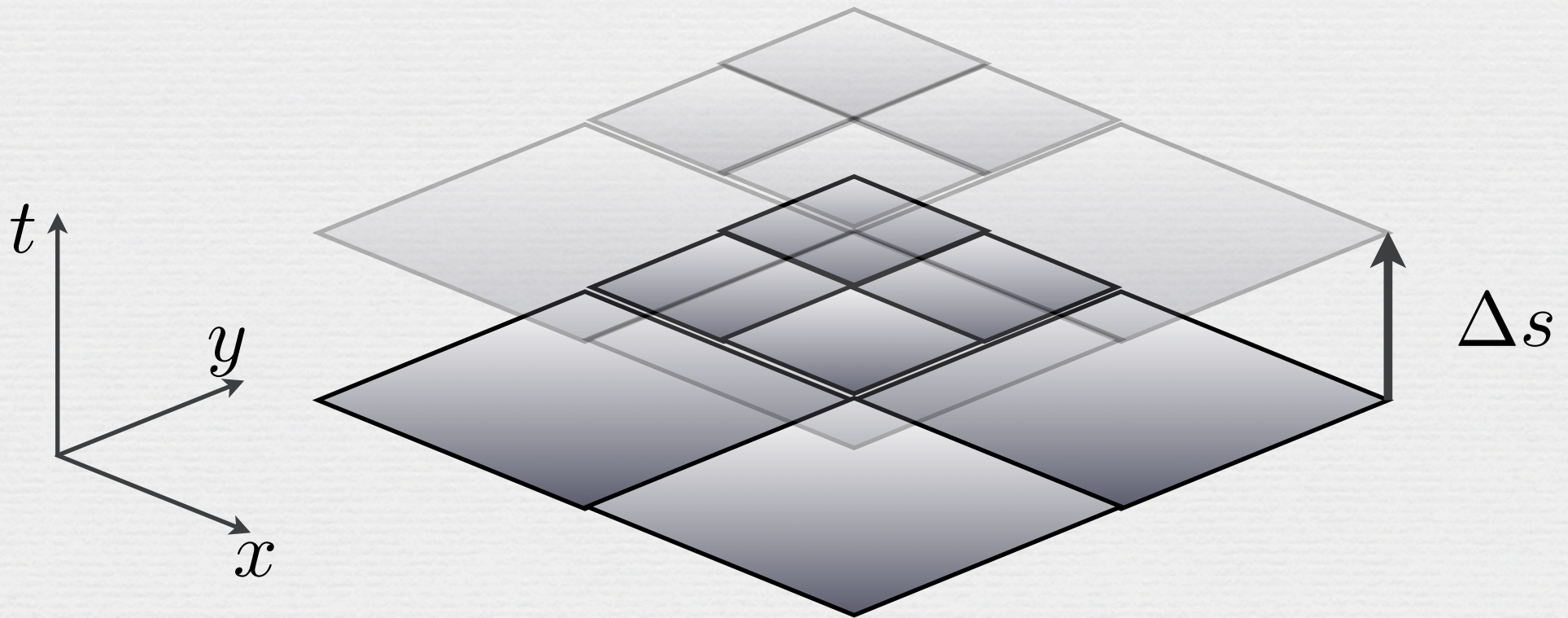


# Implicit/Explicit

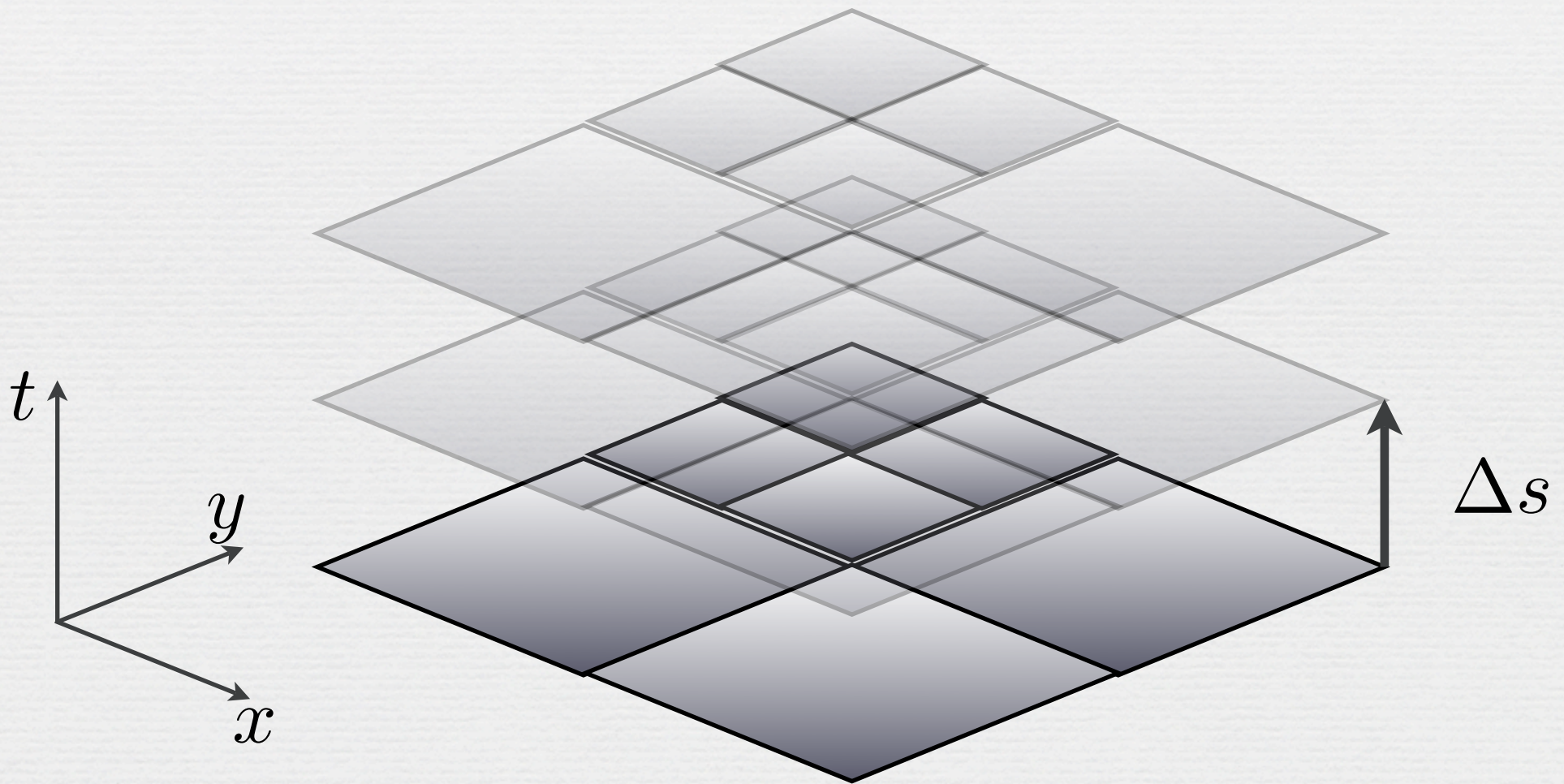




# Implicit/Explicit

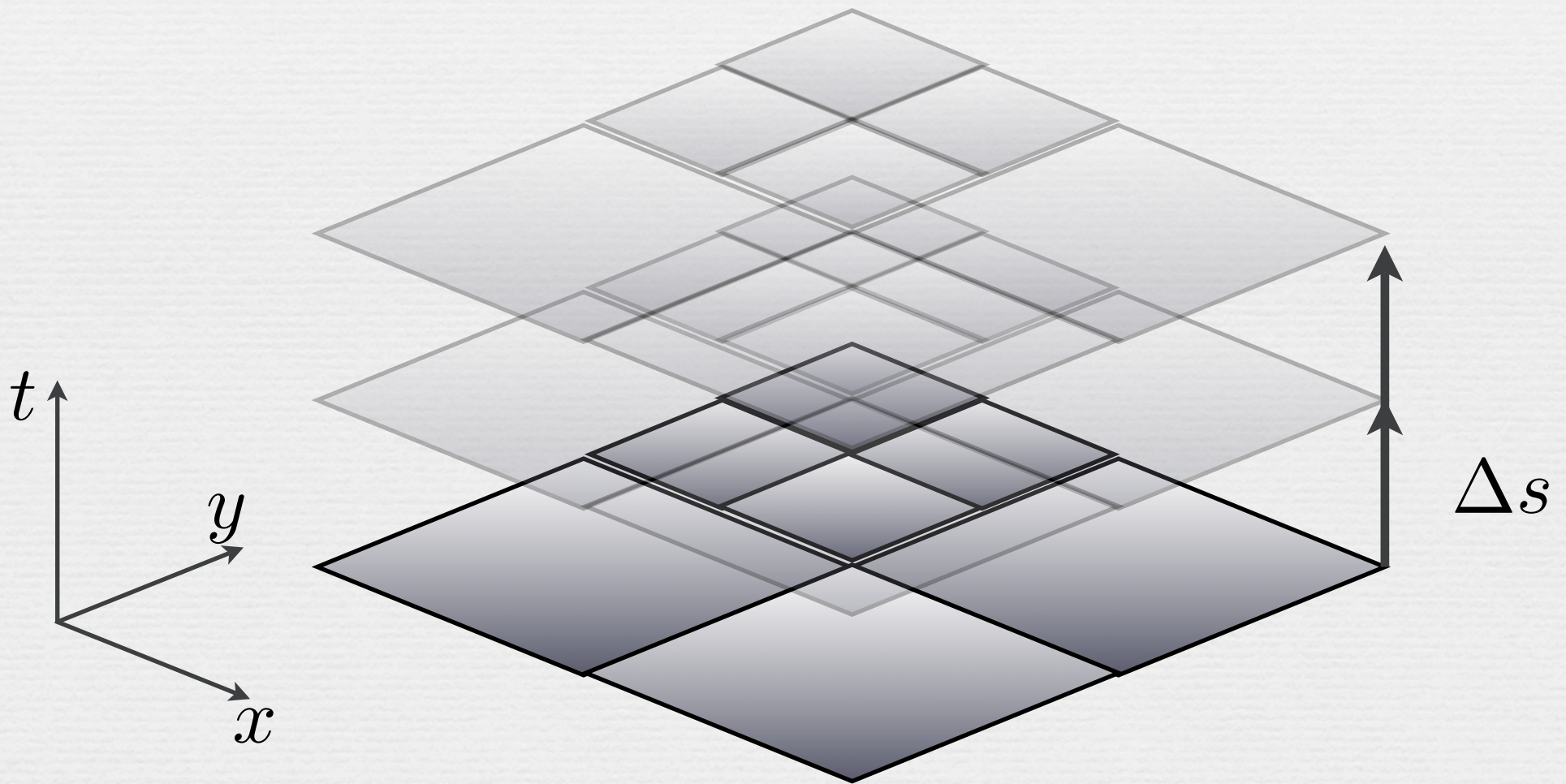


# Implicit/Explicit

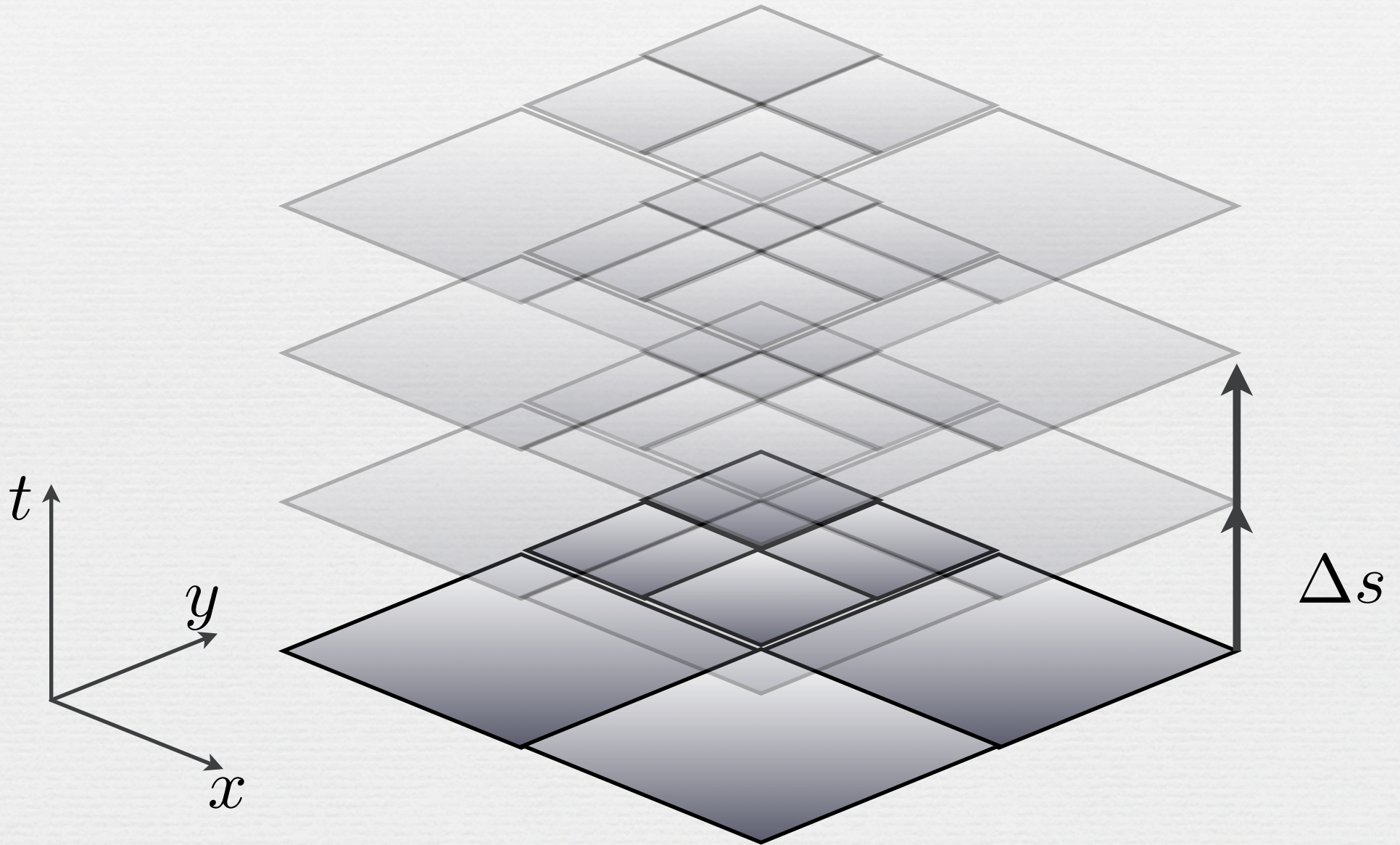




# Implicit/Explicit

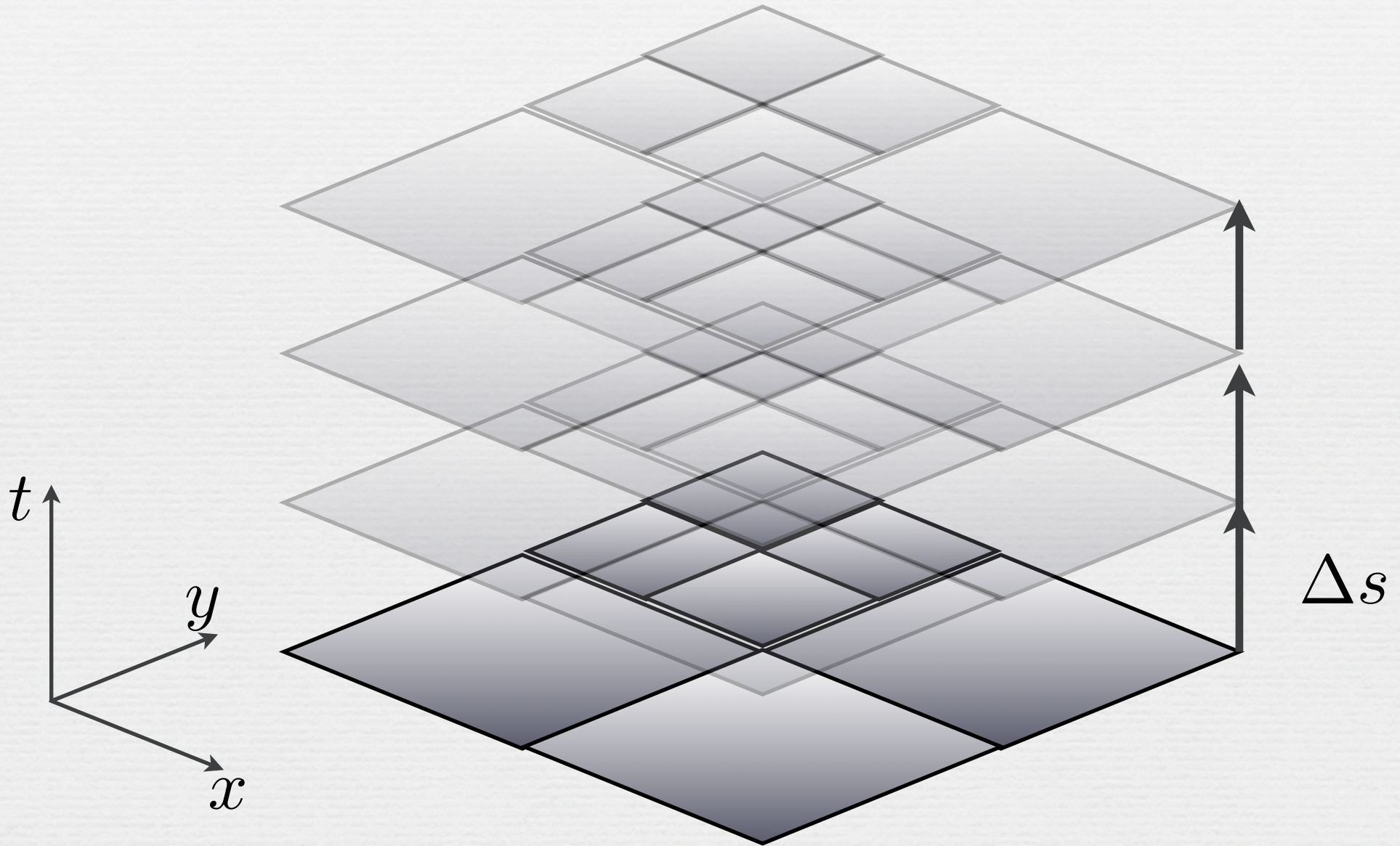


# Implicit/Explicit





# Implicit/Explicit



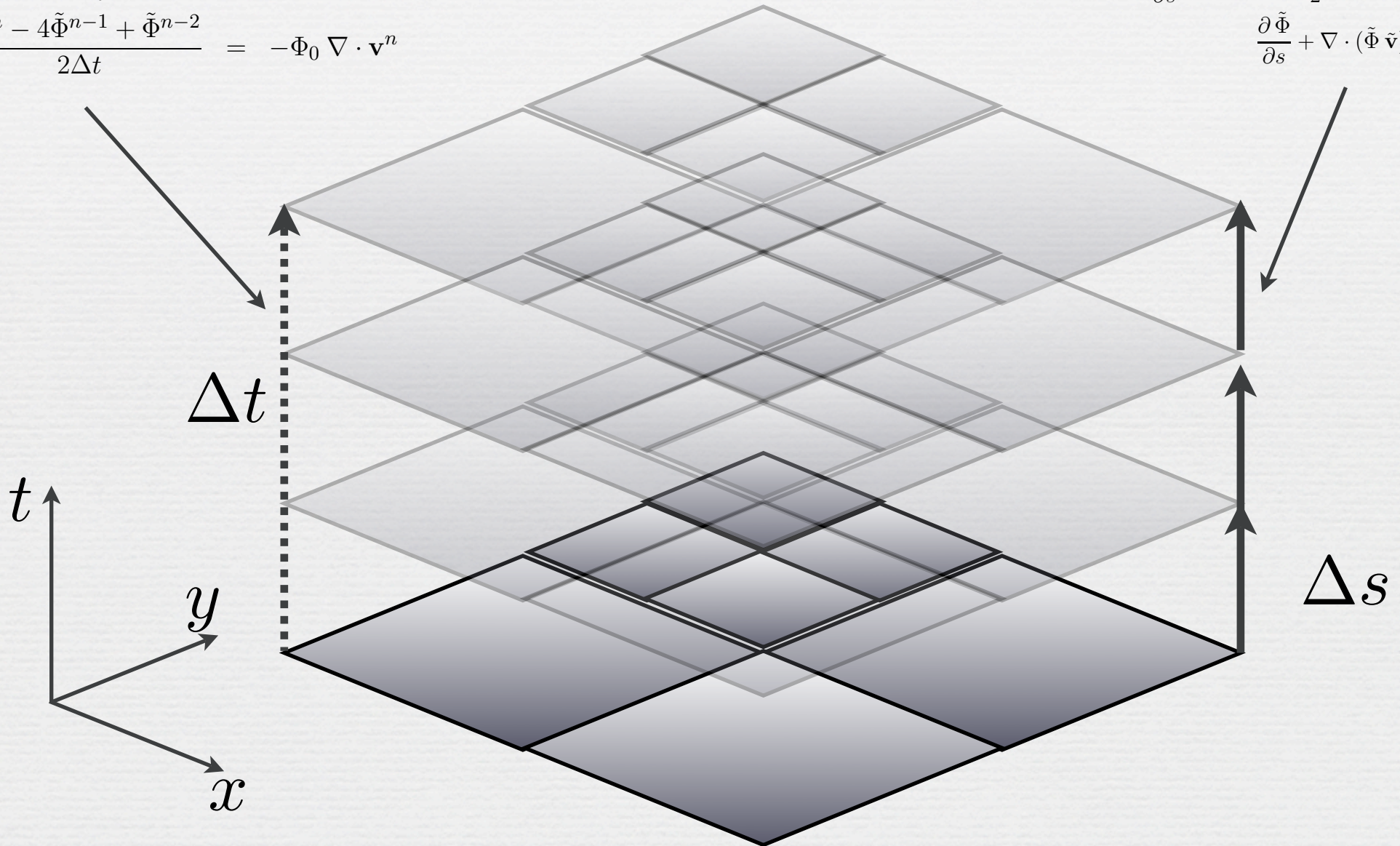
# Implicit/Explicit

$$\frac{3\mathbf{v}^n - 4\tilde{\mathbf{v}}^{n-1} + \tilde{\mathbf{v}}^{n-2}}{2\Delta t} = -Mf\mathbf{v}^n - \nabla\Phi^n$$

$$\frac{3\Phi^n - 4\tilde{\Phi}^{n-1} + \tilde{\Phi}^{n-2}}{2\Delta t} = -\Phi_0 \nabla \cdot \mathbf{v}^n$$

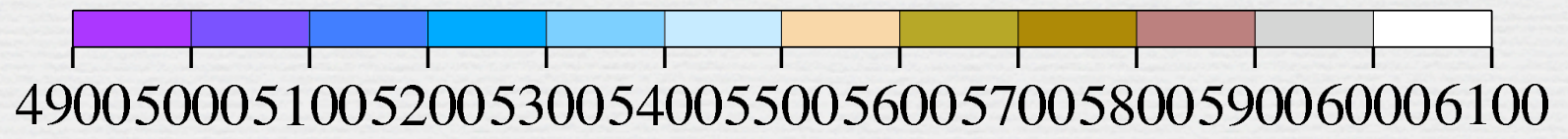
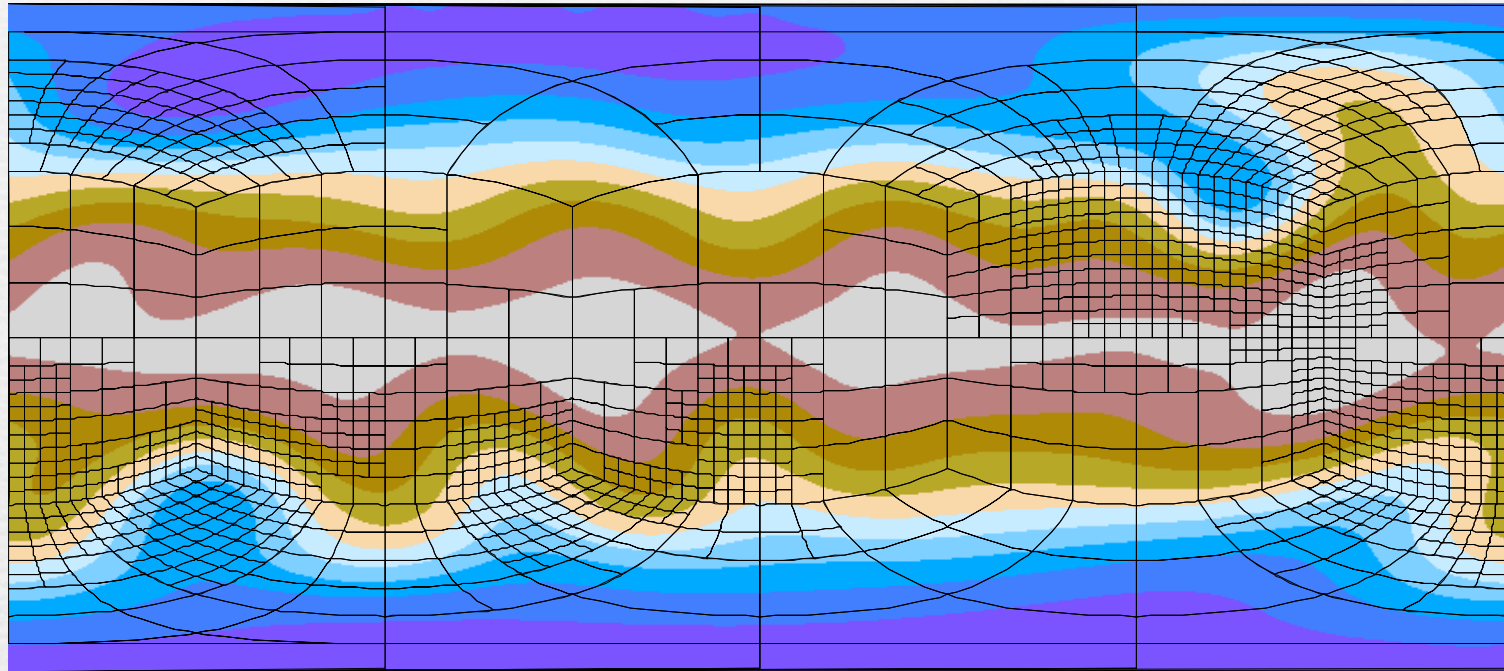
$$\frac{\partial \tilde{\mathbf{v}}}{\partial s} + \tilde{\zeta} \mathbf{k} \times \tilde{\mathbf{v}} + \frac{1}{2} \nabla (\tilde{\mathbf{v}} \cdot \tilde{\mathbf{v}}) = 0$$

$$\frac{\partial \tilde{\Phi}}{\partial s} + \nabla \cdot (\tilde{\Phi} \tilde{\mathbf{v}}) = 0$$

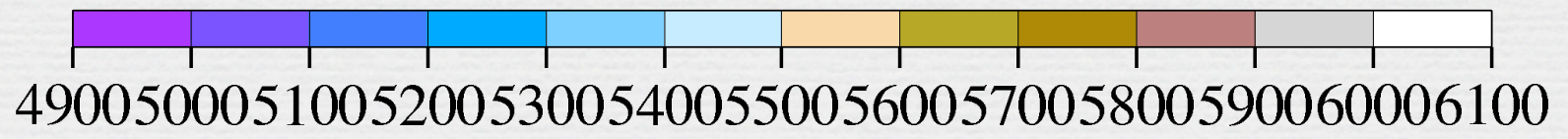
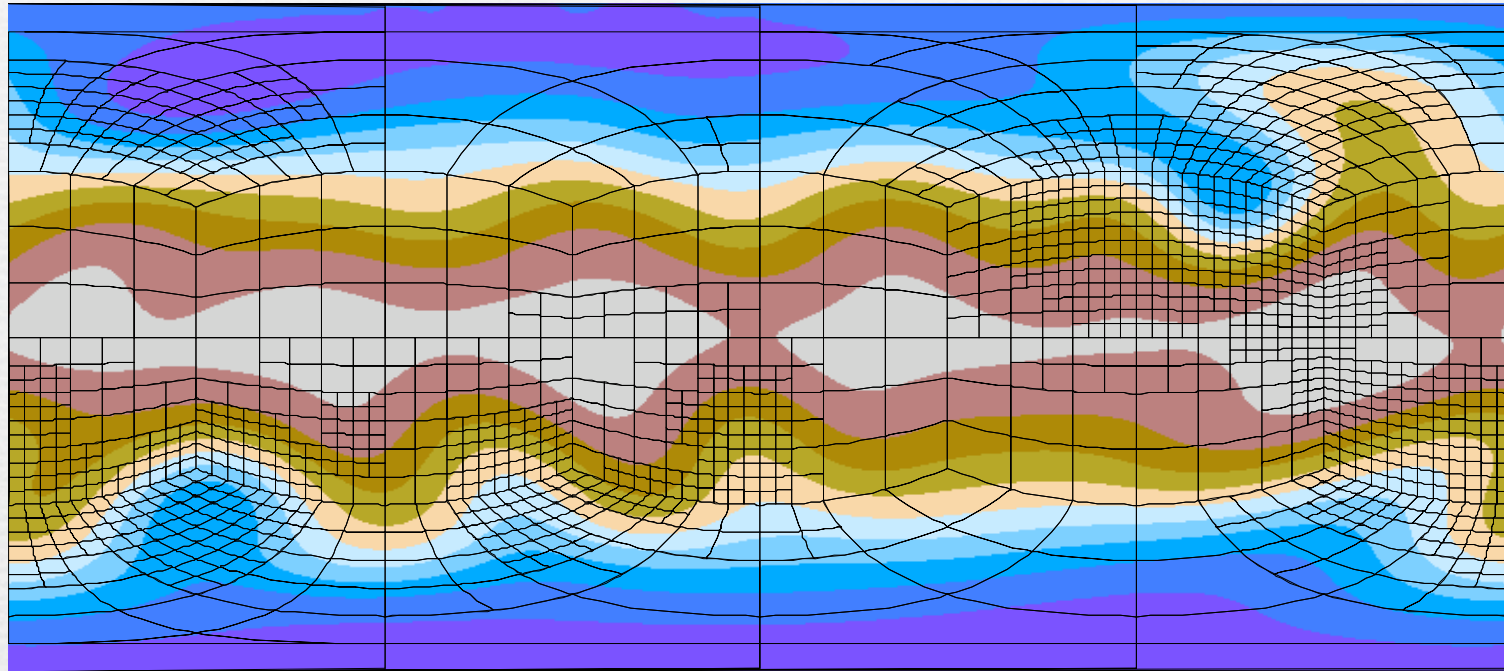




$dt=120s$

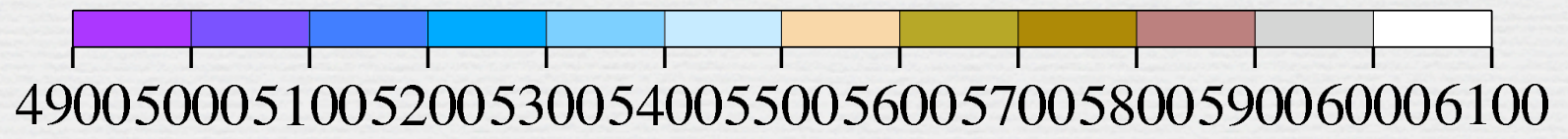
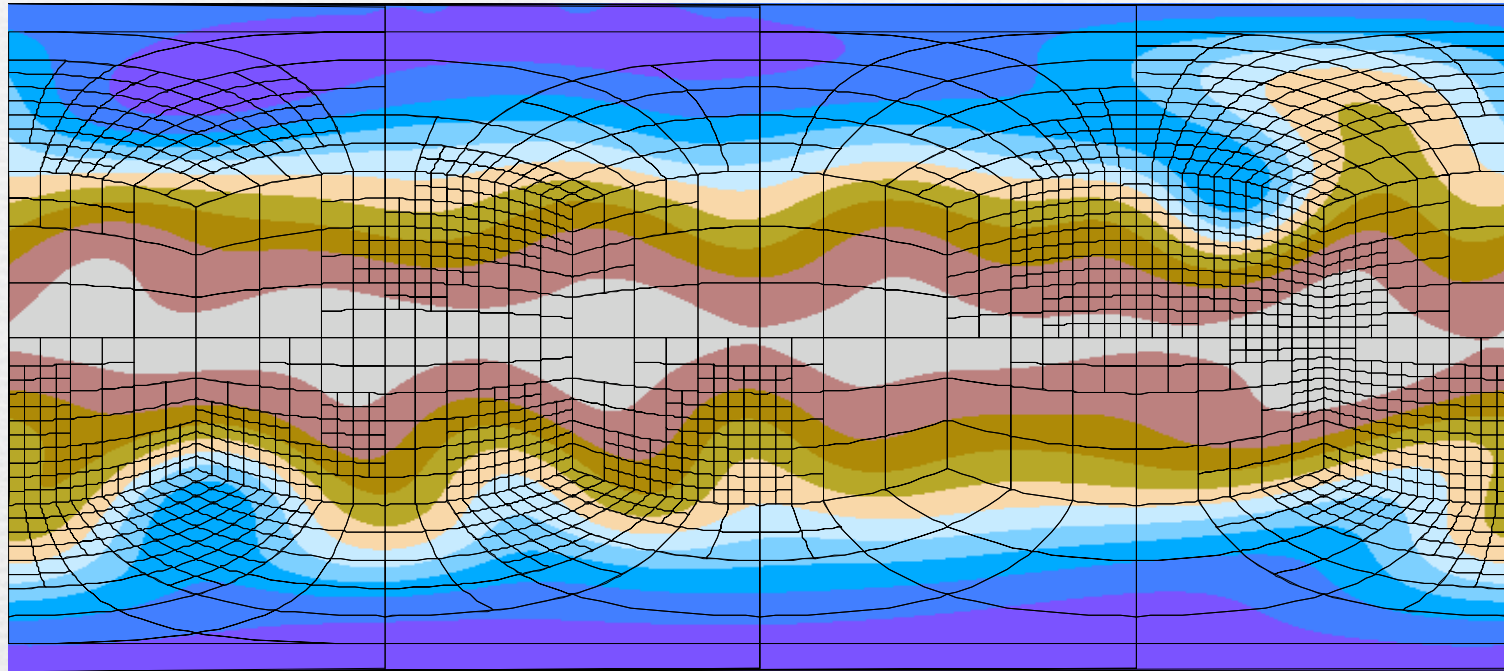


$dt=360s$

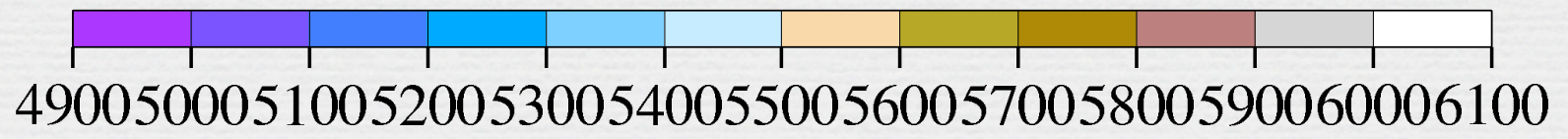
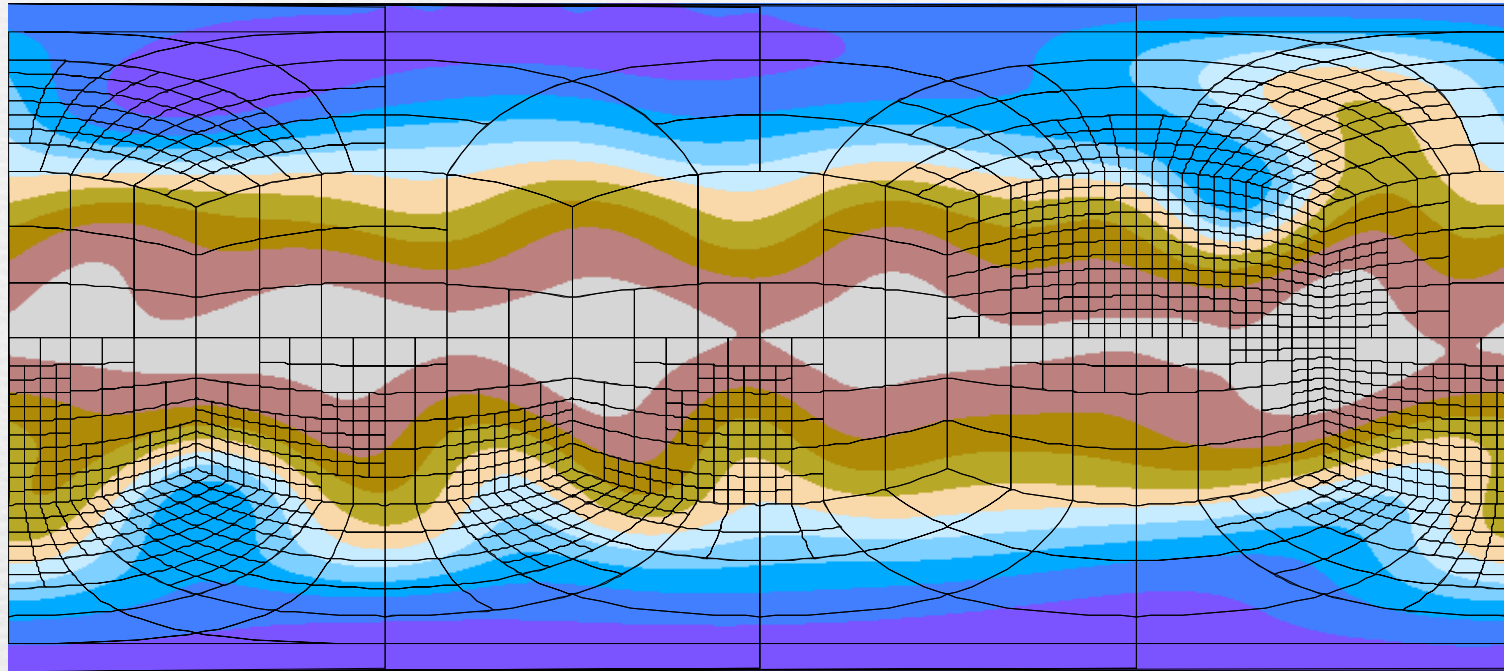




$dt=720s$

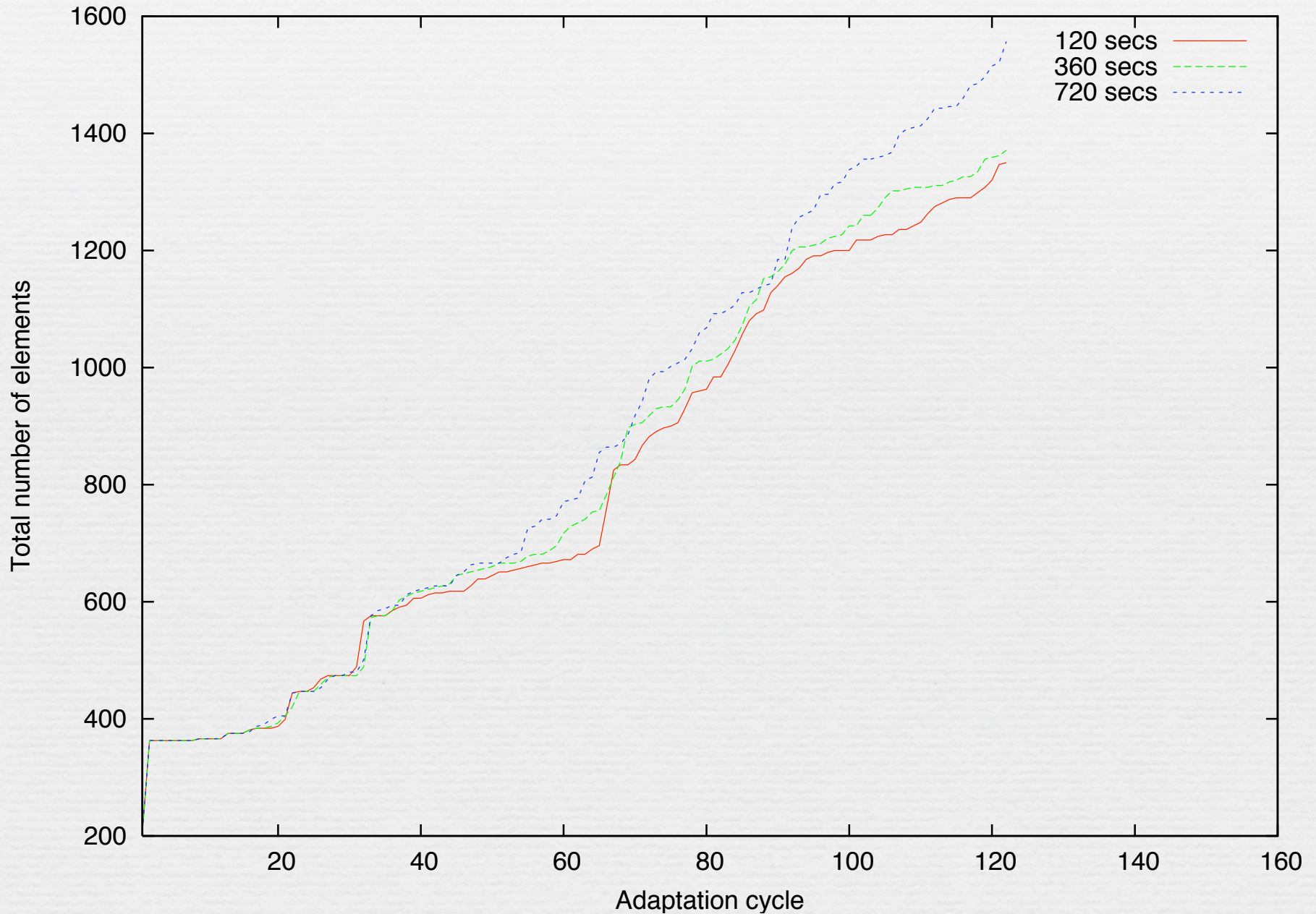


$dt=120s$

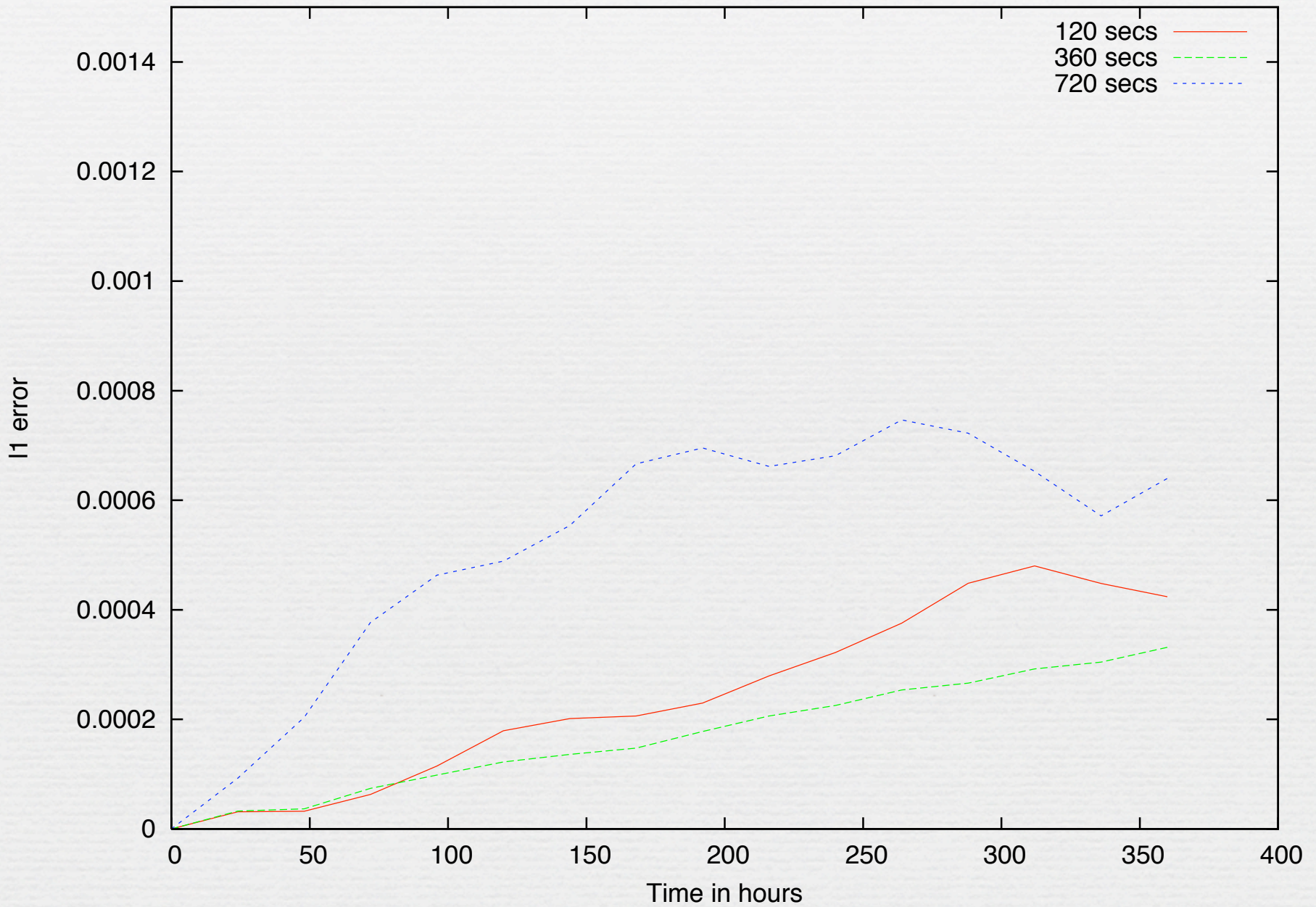




# Total number of elements

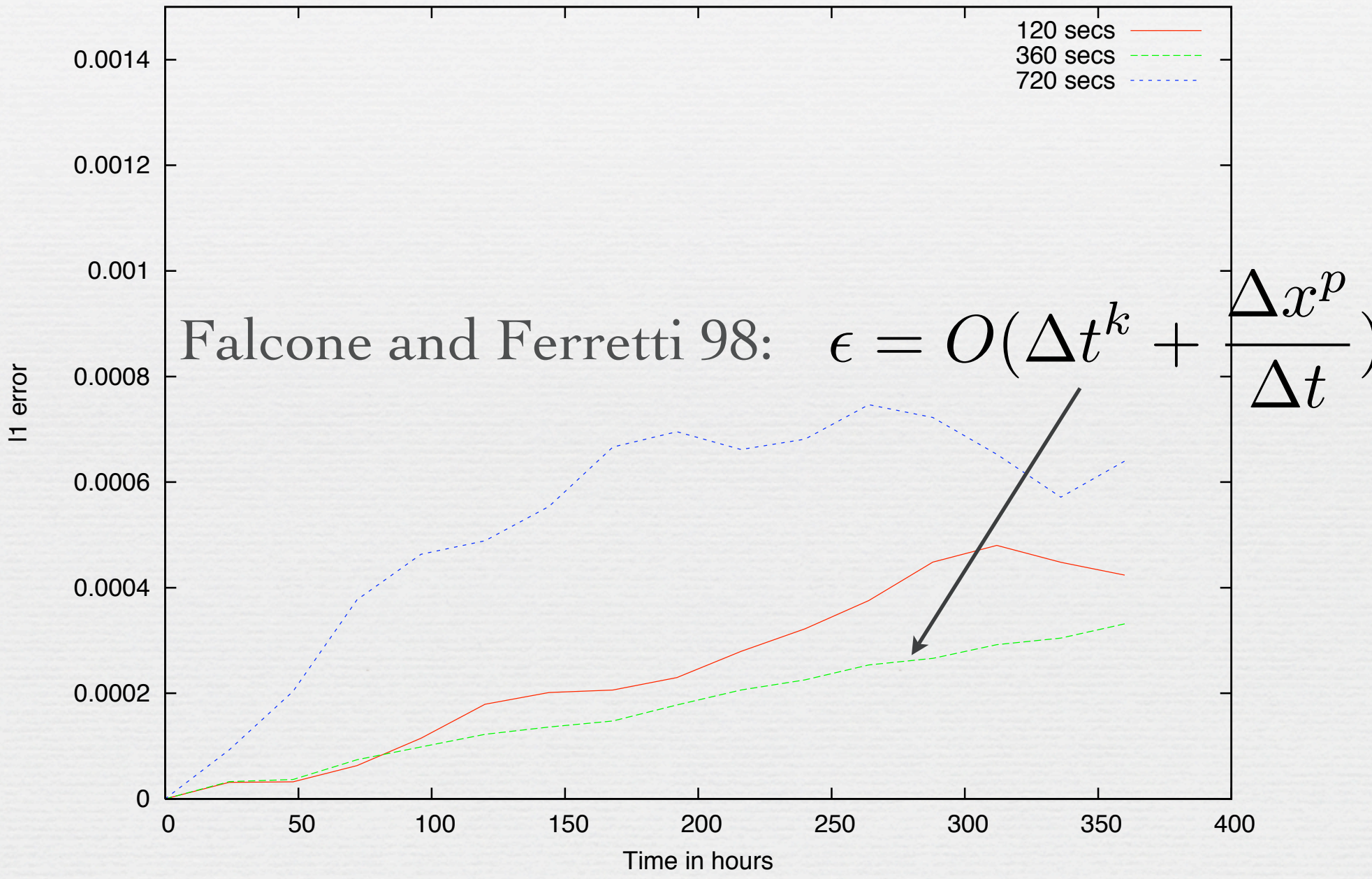


# Comparison with reference solution from NCAR pseudo spectral





# Comparison with reference solution from NCAR pseudo spectral



# Discontinuous Galerkin

Conservation law:

$$u_t + \nabla \cdot \mathcal{F}(u) = S(u)$$

Weak form:

$$\frac{d}{dt} \int_{\Omega_k} \varphi_h u_h d\Omega = \int_{\Omega_k} \varphi_h S(u_h) d\Omega + \int_{\Omega_k} \mathcal{F}(u_h) \cdot \nabla \varphi_h d\Omega - \int_{\partial\Omega_k} \varphi_h \mathcal{F} \cdot \hat{n} ds$$

Numerical flux:

$$\hat{\mathcal{F}}(u_h^+, u_h^-) = \frac{1}{2} [(\mathcal{F}(u_h^+) + \mathcal{F}(u_h^-)) \cdot \hat{n} - \alpha(u_h^+ - u_h^-)]$$



# SSP Runge-Kutta with extended linear stability region

$$\frac{d\mathbf{U}_h}{dt} = \mathbf{L}_h(\mathbf{U}_h).$$

$$u^{(0)} = u^n$$

$$u^{(i)} = \sum_{k=0}^{i-1} \alpha_{ik} u^{(k)} + \Delta t \beta_{ik} L(u^{(k)}), \quad i = 1, \dots, m,$$

$$u^{n+1} = u^{(m)}.$$

Higuera 2004, JSC

# Compressible Euler:

$$\underline{U} \equiv (\rho, \rho u, \rho w, \Theta)^T = (\rho, U, W, \Theta)^T$$

$$\mathbf{F}(\underline{U}) \equiv (F, G)$$

$$F = \left( U, \frac{UU}{\rho} + p, \frac{WU}{\rho}, \frac{U\Theta}{\rho} \right)^T$$

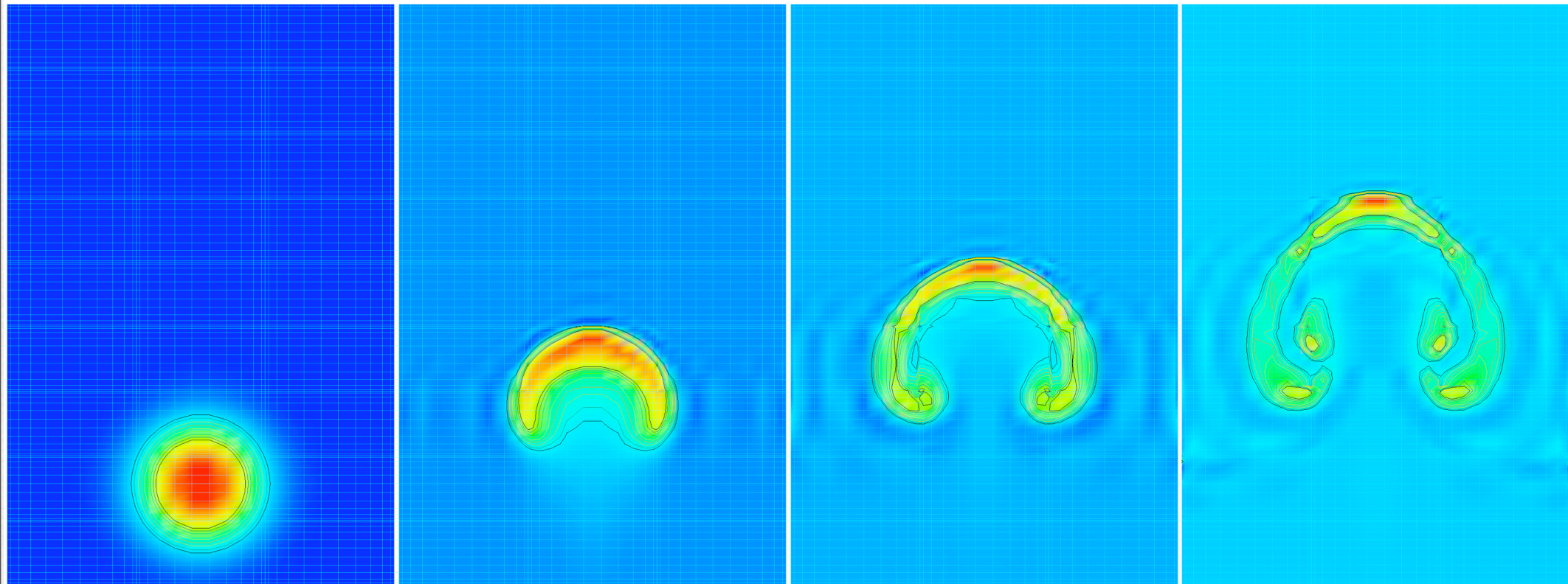
$$G = \left( W, \frac{UW}{\rho}, \frac{WW}{\rho} + p, \frac{W\Theta}{\rho} \right)^T$$

$$S(\underline{U}) = (0, 0, -g\rho, 0)^T$$

$$p = p_0 \left( \frac{R\Theta}{p_0} \right)^\gamma$$



# Warm bubble (Robert 93)





# To use or not to use HOMs?

- Low order: 2nd or 3rd
- Very dissipative
- Large dispersion error
- Oscillation control: grid point level
- Limiters - not - cache efficient
- CFL:  $dt = O(dx)$
- Costly halos...
- Spectrally accurate
- No dissipation
- No dispersion error: with filtering
- Oscillation control: questionable
- Matrix-Matrix tensor operations: cache friendly
- Halos are minimal



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- ❧ DOE Climate Change Prediction Program CCPP.

Email: [amik@ucar.edu](mailto:amik@ucar.edu)

Phone: 303-497-1287