

Multivariate spatial models and the multiKrig class

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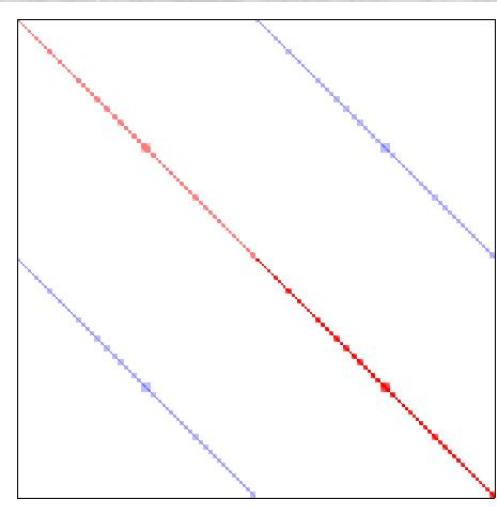
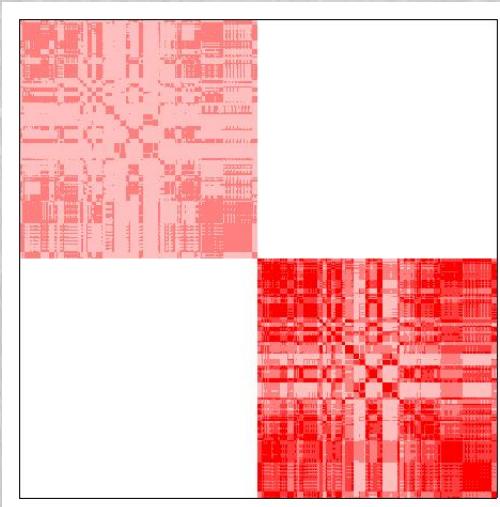
SAMSI Summer School on Spatial Statistics

July 28–August 1, 2009



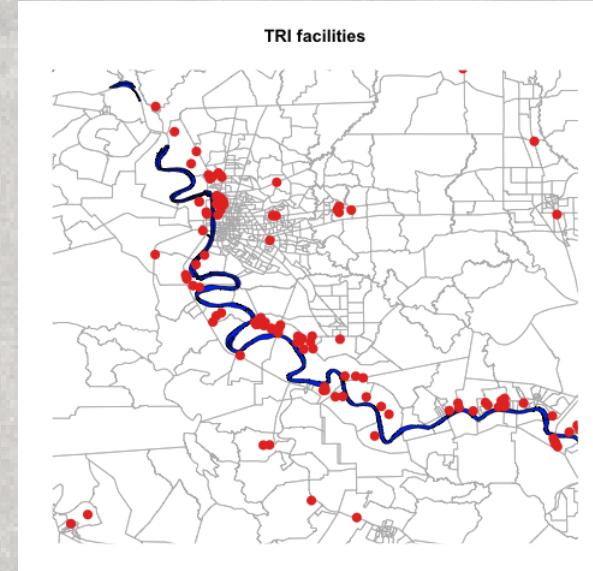
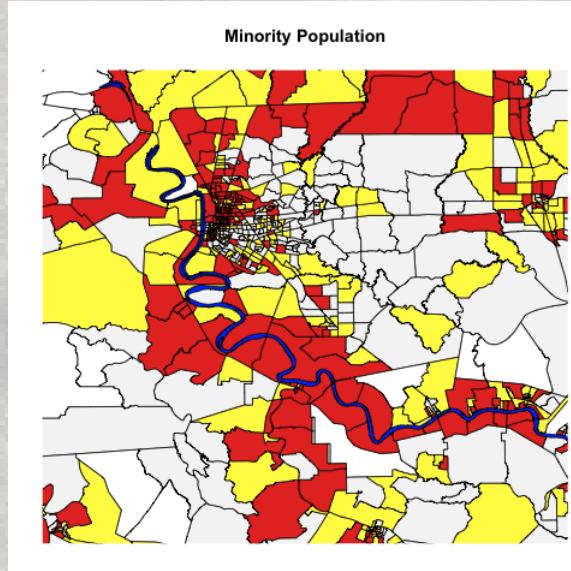
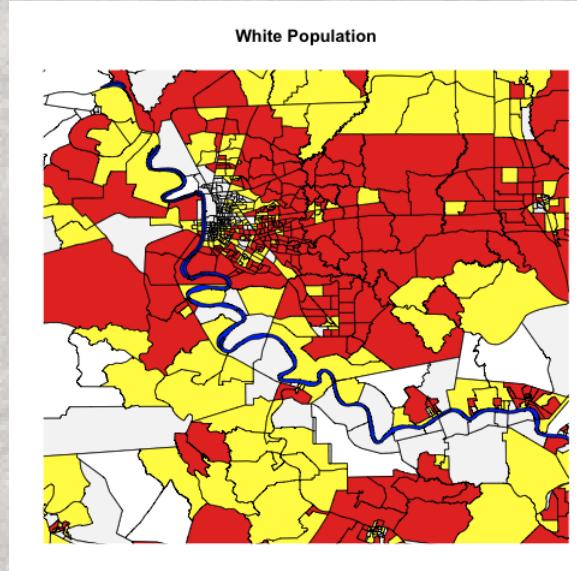
Outline

- Overview of multivariate spatial regression models.
- The `multiKrig` class
 - Case study: NC temperature and precipitation.
- Some future directions and issues.



Multivariate Spatial Regression

- Motivation: increased interest in scientific problems with many different spatial layers.
 - Geographic information systems (GIS).
- Examples: disease mapping, remote sensing, climate and weather, . . .



A Spatial Regression Model

- A spatial regression model:

$$\begin{array}{ccccccccc} \mathbf{Y} & = & \mathbf{X}\boldsymbol{\beta} & + & \mathbf{h} & + & \boldsymbol{\epsilon} \\ (n \times 1) & & (n \times q)(q \times 1) & & (n \times 1) & & (n \times 1) \end{array}$$

where

- $E[\mathbf{h}] = 0$, $\text{Var}[\mathbf{h}] = \Sigma_{\mathbf{h}}$
- $E[\boldsymbol{\epsilon}] = 0$, $\text{Var}[\boldsymbol{\epsilon}] = \sigma^2 \mathbf{I}$.
- \mathbf{h} and $\boldsymbol{\epsilon}$ are independent.
- $\mathbf{Y} \sim \mathcal{N}(\mathbf{X}\boldsymbol{\beta}, \mathbf{V})$, $\mathbf{V} = \Sigma_{\mathbf{h}} + \sigma^2 \mathbf{I}$
- $\hat{\boldsymbol{\beta}} = (\mathbf{X}'\mathbf{V}^{-1}\mathbf{X})^{-1}\mathbf{X}'\mathbf{V}^{-1}\mathbf{Y}$, $\hat{\mathbf{h}} = \Sigma_{\mathbf{h}}\mathbf{V}^{-1}(\mathbf{Y} - \mathbf{X}\hat{\boldsymbol{\beta}})$

Multivariate Regression

- A multivariate, multiple regression model:

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon}$$

$(n \times p) \quad (n \times q)(q \times p) \quad (n \times p)$

where

- Each of the n rows of \mathbf{Y} represents a p -vector observation.
- Each of the p columns of $\boldsymbol{\beta}$ represent regression coefficients for each variable.
- The rows of $\boldsymbol{\epsilon}$ represents a collection of iid error vectors with zero mean and common covariance matrix, Σ .

Multivariate Regression

- MLEs are straightforward to obtain:

$$\begin{aligned}\hat{\beta} &= (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{Y} \\ (q \times p) \quad & \\ \hat{\Sigma} &= \frac{1}{n}\mathbf{Y}'\mathbf{P}\mathbf{Y} \\ (p \times p) \quad &\end{aligned}$$

where $\mathbf{P} = \mathbf{I} - \mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'$.

- Note that the columns of $\hat{\beta}$ can be obtained through p univariate regressions.

Vec and Kronecker

- The Kronecker product of an $m \times n$ matrix \mathbf{A} and an $r \times q$ matrix \mathbf{B} is an $mr \times nq$ matrix:

$$\mathbf{A} \otimes \mathbf{B} = \begin{bmatrix} a_{11}\mathbf{B} & a_{12}\mathbf{B} & \cdots & a_{1n}\mathbf{B} \\ a_{21}\mathbf{B} & a_{22}\mathbf{B} & \cdots & a_{2n}\mathbf{B} \\ \vdots & & \ddots & \vdots \\ a_{m1}\mathbf{B} & a_{m2}\mathbf{B} & \cdots & a_{mn}\mathbf{B} \end{bmatrix}$$

- Some properties:

$$\begin{aligned}\mathbf{A} \otimes (\mathbf{B} + \mathbf{C}) &= \mathbf{A} \otimes \mathbf{B} + \mathbf{A} \otimes \mathbf{C} \\ \mathbf{A} \otimes (\mathbf{B} \otimes \mathbf{C}) &= (\mathbf{A} \otimes \mathbf{B}) \otimes \mathbf{C} \\ (\mathbf{A} \otimes \mathbf{B})(\mathbf{C} \otimes \mathbf{D}) &= \mathbf{AC} \otimes \mathbf{BD} \\ (\mathbf{A} \otimes \mathbf{B})' &= \mathbf{A}' \otimes \mathbf{B}' \\ (\mathbf{A} \otimes \mathbf{B})^{-1} &= \mathbf{A}^{-1} \otimes \mathbf{B}^{-1} \\ |\mathbf{A} \otimes \mathbf{B}| &= |\mathbf{A}|^m |\mathbf{B}|^n\end{aligned}$$

Vec and Kronecker

- The vec-operator stacks the columns of a matrix:

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \quad \text{vec}(\mathbf{A}) = \begin{bmatrix} a_{11} \\ a_{21} \\ a_{12} \\ a_{22} \end{bmatrix}$$

- Some properties:

$$\text{vec}(\mathbf{AXB}) = (\mathbf{B}' \otimes \mathbf{A}) \text{vec } \mathbf{X}$$

$$\text{tr}(\mathbf{A}'\mathbf{B}) = \text{vec}(\mathbf{A})' \text{vec}(\mathbf{B})$$

$$\text{vec}(\mathbf{A} + \mathbf{B}) = \text{vec}(\mathbf{A}) + \text{vec}(\mathbf{B})$$

$$\text{vec}(\alpha \mathbf{A}) = \alpha \text{vec}(\mathbf{A})$$

Multivariate Regression Revisited

- Rewrite the multivariate, multiple regression model:

$$\begin{array}{cccccc}\text{vec}(\mathbf{Y}) & = & (\mathbf{I}_p \otimes \mathbf{X}) \text{vec}(\boldsymbol{\beta}) & + & \text{vec}(\boldsymbol{\epsilon}) \\ (np \times 1) & & (np \times qp)(qp \times 1) & & (np \times 1).\end{array}$$

- What is $\text{Var}[\text{vec } \boldsymbol{\epsilon}]$?
- What is the GLS estimator for $\text{vec}(\boldsymbol{\beta})$?

A Multivariate Spatial Model

- Extend the multivariate, multiple regression model:

$$\begin{array}{cccccc}\text{vec}(\mathbf{Y}) & = & (\mathbf{I}_p \otimes \mathbf{X}) \text{vec}(\boldsymbol{\beta}) & + & \text{vec}(\mathbf{h}) & + & \text{vec}(\boldsymbol{\epsilon}) \\ (np \times 1) & & (np \times qp)(qp \times 1) & & (np \times 1) & & (np \times 1),\end{array}$$

where

$$\begin{aligned}\text{Var}[\text{vec}(\mathbf{h})] &= \boldsymbol{\Sigma}_{\mathbf{h}} = \begin{bmatrix} \boldsymbol{\Sigma}_{11} & \boldsymbol{\Sigma}_{12} & \cdots & \boldsymbol{\Sigma}_{1p} \\ \boldsymbol{\Sigma}'_{12} & \boldsymbol{\Sigma}_{22} & \cdots & \boldsymbol{\Sigma}_{2p} \\ \vdots & & \ddots & \vdots \\ \boldsymbol{\Sigma}'_{1p} & \boldsymbol{\Sigma}'_{2p} & \cdots & \boldsymbol{\Sigma}_{pp} \end{bmatrix} \\ \text{Var}[\text{vec}(\boldsymbol{\epsilon})] &= \boldsymbol{\Sigma} \otimes \mathbf{I}_n\end{aligned}$$

A Multivariate Spatial Model

- One simplification to the spatial covariance matrix is to use a Kronecker form:

$$\begin{aligned}\Sigma_h &= \rho \otimes K \\ &= \begin{bmatrix} \rho_{11}K & \rho_{12}K & \cdots & \rho_{1p}K \\ \rho_{12}K & \rho_{22}K & \cdots & \rho_{2p}K \\ \vdots & & \ddots & \vdots \\ \rho_{1p}K & \rho_{2p}K & \cdots & \rho_{pp}K \end{bmatrix}\end{aligned}$$

where

- ρ is a $p \times p$ matrix of scale parameters
- K is an $n \times n$ spatial covariance.

A Multivariate Spatial Model

- Extend the multivariate, multiple regression model:

$$\begin{array}{cccccc}\text{vec}(\mathbf{Y}) & = & (\mathbf{I}_p \otimes \mathbf{X}) \text{vec}(\boldsymbol{\beta}) & + & \text{vec}(\mathbf{h}) & + & \text{vec}(\boldsymbol{\epsilon}) \\ (np \times 1) & & (np \times qp)(qp \times 1) & & (np \times 1) & & (np \times 1)\end{array}$$

OR

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{h} + \boldsymbol{\epsilon}$$

- Now everything follows...

The multiKrig Class

- Create a multivariate spatial regression within the univariate Krig framework:

$$\mathbf{Y} = \mathbf{T}\boldsymbol{\beta} + \mathbf{h} + \boldsymbol{\epsilon}$$

$$\mathbf{Y} = \begin{bmatrix} \mathbf{Y}_1 \\ \vdots \\ \mathbf{Y}_p \end{bmatrix} \quad \mathbf{T} = \mathbf{I}_p \otimes \mathbf{X} \quad \mathbf{h} = \begin{bmatrix} \mathbf{h}_1 \\ \vdots \\ \mathbf{h}_p \end{bmatrix} \quad \boldsymbol{\epsilon} = \begin{bmatrix} \boldsymbol{\epsilon}_1 \\ \vdots \\ \boldsymbol{\epsilon}_p \end{bmatrix}$$

The multiKrig Class

- Create a multivariate spatial regression within the univariate Krig framework:

$$\mathbf{Y} = \mathbf{T}\boldsymbol{\beta} + \mathbf{h} + \boldsymbol{\epsilon}$$

$$\begin{aligned}\mathbb{E}[\mathbf{Y}] &= \mathbf{T}\boldsymbol{\beta} \\ \text{Var}[\mathbf{Y}] &= \Sigma_h + \Sigma_{\epsilon} \\ &= \begin{bmatrix} \rho_1 & & \\ & \ddots & \\ & & \rho_p \end{bmatrix} \otimes \mathbf{V}(\theta) + \begin{bmatrix} s_{11} & s_{12} & \cdots & s_{1p} \\ s_{21} & s_{22} & \cdots & s_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ s_{p1} & s_{p2} & \cdots & s_{pp} \end{bmatrix} \otimes \mathbf{I}_n \\ &= \rho_1 \mathbf{R} \otimes \mathbf{V}(\theta) + s_{11} \mathbf{S} \otimes \mathbf{I}_n \\ &= \rho_1 (\mathbf{R} \otimes \mathbf{V}(\theta) + \lambda \mathbf{S} \otimes \mathbf{I}_n)\end{aligned}$$

The multiKrig Class

- Create a multivariate spatial regression within the univariate Krig framework:

$$\mathbf{Y} = \mathbf{T}\boldsymbol{\beta} + \mathbf{h} + \boldsymbol{\epsilon}$$

$$\begin{aligned} E[\mathbf{Y}] &= \mathbf{T}\boldsymbol{\beta} \\ \text{Var}[\mathbf{Y}] &= \Sigma_h + \Sigma_{\epsilon} \\ &= \rho_1 (\mathbf{R} \otimes \mathbf{V}(\theta) + \lambda \mathbf{S} \otimes \mathbf{I}_n) \end{aligned}$$

- Given \mathbf{S} , \mathbf{R} , and θ , use Krig to estimate $\boldsymbol{\beta}$, ρ_1 and λ .

The multiKrig Class

- Issues:
 - Specifying x , Y , and Z
 - Mean function (`null.function`)
 - Covariance function (`cov.function`)
 - Error function (`wght.function`)
- Estimation (S , R , and θ)

Krig Function

```
Krig <- function (x, Y, Z,
  null.function = "Krig.null.function",
  cov.function = "stationary.cov",
  wght.function = NULL,
  null.args = NULL, cov.args = NULL, wght.args = NULL)
```

- x is an $n \times q$ matrix of spatial locations
- Y is a n -vector of observations
- Z is a $n \times q$ matrix of additional covariates

multiKrig Function

```
multiKrig <- function(s,Y,Z,  
                      cov.function="multi.cov",cov.args=NULL,  
                      wght.function="multi.wght",wght.args=NULL)
```

- s is an $n \times q$ matrix of spatial locations
- Y is an $n \times p$ matrix of observations
- Z is either:
 - a $n \times q$ matrix of additional covariates, or
 - a list of $n \times q_i$ matrices of additional covariates

multiKrig Function

```
multiKrig <- function(s,Y,Z,
                      cov.function="multi.cov",cov.args=NULL,
                      wght.function="multi.wght",wght.args=NULL) {
  :
  d <- ncol(Y)
  n <- nrow(Y)
  Y <- c(Y)
  :
  x <- expand.grid(1:n,1:d)
  nZ <- kronecker(diag(d),cbind(s,Z))
  :
  obj <- Krig(x=x,Y=c(Y),Z=nZ,method="REML",
               null.function="multi.null",
               cov.function=cov.function,cov.args=cov.args,
               wght.function=wght.function,wght.args=wght.args)
  :
}
```

- $\text{Y} \leftarrow \text{c}(\text{Y})$

$$\mathbf{Y} = \begin{bmatrix} \mathbf{Y}_1 \\ \vdots \\ \mathbf{Y}_p \end{bmatrix}$$

```

multiKrig <- function(s,Y,Z,
cov.function="multi.cov",cov.args=NULL,
wght.function="multi.wght",wght.args=NULL){
:
d <- ncol(Y)
n <- nrow(Y)
Y <- c(Y)
:
x <- expand.grid(1:n,1:d)
nZ <- kronecker(diag(d),cbind(s,Z))
:
obj <- Krig(x=x,Y=c(Y),Z=nZ,method="REML",
null.function="multi.null",
cov.function=cov.function,cov.args=cov.args,
wght.function=wght.function,wght.args=wght.args)
:
}

```

- `x <- expand.grid(1:n,1:d)`

$$x = \begin{bmatrix} 1 & 1 \\ 2 & 1 \\ \vdots & \\ n & 1 \\ 1 & 2 \\ \vdots & \\ n & p \end{bmatrix}$$

```

multiKrig <- function(s,Y,Z,
                      cov.function="multi.cov",cov.args=NULL,
                      wght.function="multi.wght",wght.args=NULL){
  :
  d <- ncol(Y)
  n <- nrow(Y)
  Y <- c(Y)
  :
  x <- expand.grid(1:n,1:d)
  nZ <- kronecker(diag(d),cbind(s,Z))
  :
  obj <- Krig(x=x,Y=c(Y),Z=nZ,method="REML",
               null.function="multi.null",
               cov.function=cov.function,cov.args=cov.args,
               wght.function=wght.function,wght.args=wght.args)
  :
}

```

- $nZ \leftarrow \text{kronecker}(\text{diag}(d), \text{cbind}(s, Z))$ $Z = \begin{bmatrix} s Z & & \\ & \ddots & \\ & & s Z \end{bmatrix}$

```

multiKrig  <-  function(s,Y,Z,
                        cov.function="multi.cov",cov.args=NULL,
                        wght.function="multi.wght",wght.args=NULL){
  :
  d <- ncol(Y)
  n <- nrow(Y)
  Y <- c(Y)
  :
  x <- expand.grid(1:n,1:d)
  nZ <- kronecker(diag(d),cbind(s,Z))
  :
  obj  <- Krig(x=x,Y=c(Y),Z=nZ,method="REML",
                null.function="multi.null",
                cov.function=cov.function,cov.args=cov.args,
                wght.function=wght.function,wght.args=wght.args)
  :
}

```

```

multi.null <- function(x,Z=NULL,drop.Z=FALSE){
  data <- data.frame(a=as.factor(x[,2]))
  X <- model.matrix(~a,data=data,contrasts=list(a="contr.treatment"))
  :
  return(cbind(X,Z))
}

```

$$T = \begin{bmatrix} 1 & 0 & 0 & sZ & 0 & 0 \\ 1 & 1 & 0 & 0 & sZ & 0 \\ 1 & 0 & 1 & 0 & 0 & sZ \end{bmatrix}$$

```

multiKrig <- function(s,Y,Z,
  cov.function="multi.cov",cov.args=NULL,
  wght.function="multi.wght",wght.args=NULL){
  :
  obj <- Krig(x=x,Y=c(Y),Z=nZ,method="REML",
    null.function="multi.null",
    cov.function=cov.function,cov.args=cov.args,
    wght.function=wght.function,wght.args=wght.args)
  :
}

```

Covariance Function

- Issue: x is now a matrix of indices.
- Solution: pass the spatial locations as an argument to the covariance function.

```

multiKrig  <-  function(s,Y,Z,
                        cov.function="multi.cov",cov.args=NULL,
                        wght.function="multi.wght",wght.args=NULL){
  :
  cov.args$s <- s
  obj   <-  Krig(x=x,Y=c(Y),Z=nZ,method="REML",
                  null.function="multi.null",
                  cov.function=cov.function,cov.args=cov.args,
                  wght.function=wght.function,wght.args=wght.args)
  :
}

multi.cov <-  function(x1,x2,marginal=FALSE,C=NA,s,theta,rho,smoothness){
  :
  ind <- unique(x1[,2])
  temp  <-  stationary.cov(s[x1[,1][x1[,2]==1],],
                            s[x2[,1][x2[,2]==1],],
                            Covariance="Matern",theta=theta,smoothness=smoothness)
  if  (length(ind)>1){
    for  (i in 2:length(ind)){
      temp2  <-  rho[i-1]*stationary.cov(s[x1[,1][x1[,2]==i],],
                                             s[x2[,1][x2[,2]==i],],
                                             Covariance="Matern",theta=theta,smoothness=smoothness)
      d1 <- dim(temp)
      d2 <- dim(temp2)
      temp  <-  rbind(cbind(temp,matrix(0,d1[1],d2[2])),
                      cbind(matrix(0,d1[1],d2[2]),temp2))
    }
  }
  :
  return(temp)
}

```

Weight Function

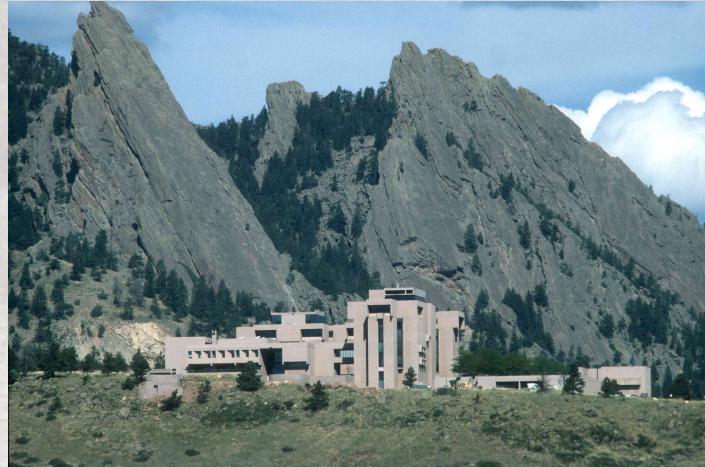
```
multiKrig  <-  function(s,Y,Z,
                        cov.function="multi.cov",cov.args=NULL,
                        wght.function="multi.wght",wght.args=NULL){
  :
  obj   <-  Krig(x=x,Y=c(Y),Z=nZ,method="REML",
                  null.function="multi.null",
                  cov.function=cov.function,cov.args=cov.args,
                  wght.function=wght.function,wght.args=wght.args)
  :
}

multi.wght  <-  function(x,sp){
  n <- length(unique(x[,1]))
  :
  return(kronecker(solve(S),diag(n)))
}
```

Parameter Estimation and Other Issues

- Krig will estimate β , ρ_1 and λ .
 - REML
 - GCV (not quite there...)
- How to estimate S , R , and θ ?
- Nonseparable covariance functions.
- Estimation/prediction for missing observations.
- Implementation in fields.

Thanks!



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- Sain, S.R., Mearns, L., Shrikant, J., and Nychka, D. (2006), "A multivariate spatial model for soil water profiles," *Journal of Agricultural, Biological, and Environmental Statistics*, **11**, 462-480.
- Sain, S.R. and Cressie, N. (2007), "A spatial model for multivariate lattice data," *Journal of Econometrics*, **140**, 226-259, doi:10.1016/j.jeconom.2006.09.010.