

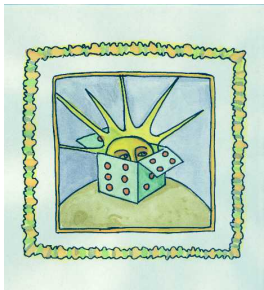
Combining climate model experiments

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- Climate change and climate models
- Inference for a single region
- Two-way effects for several regions.

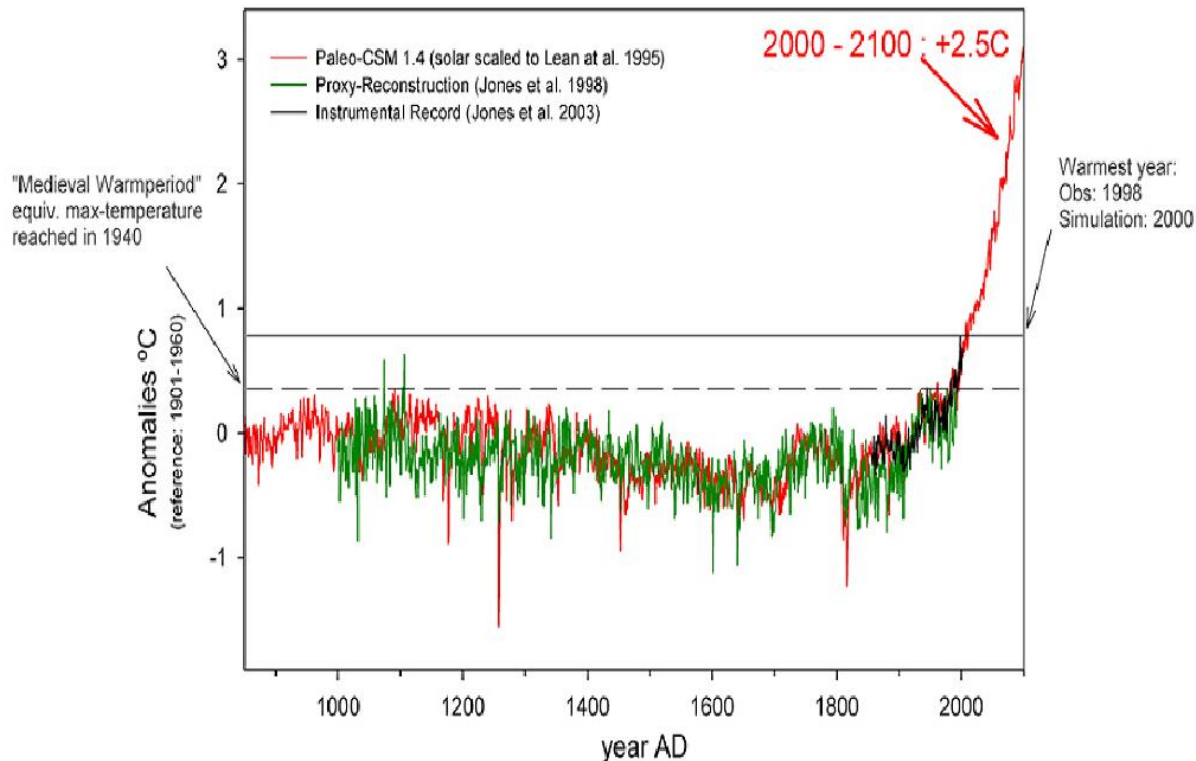
How does a changed (warmer) climate effect human health?



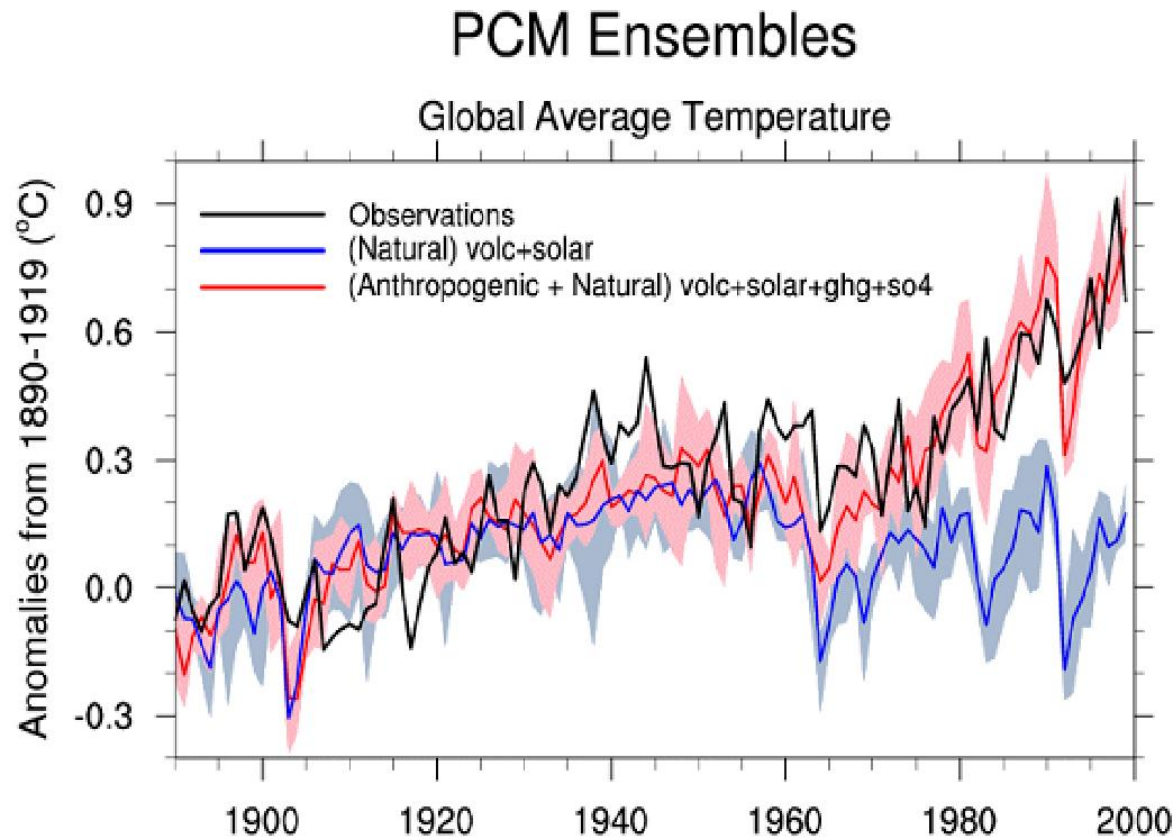
Climate: What you expect ... *Weather:* What you get.

Recent warming appears unusual from the proxy records of global temperatures

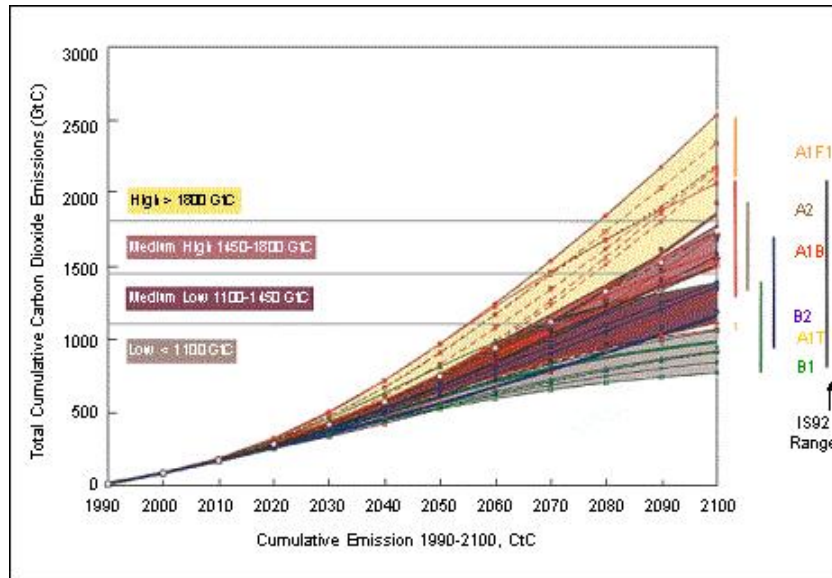
Last Millennium Simulation with Paleo-CSM 1.4



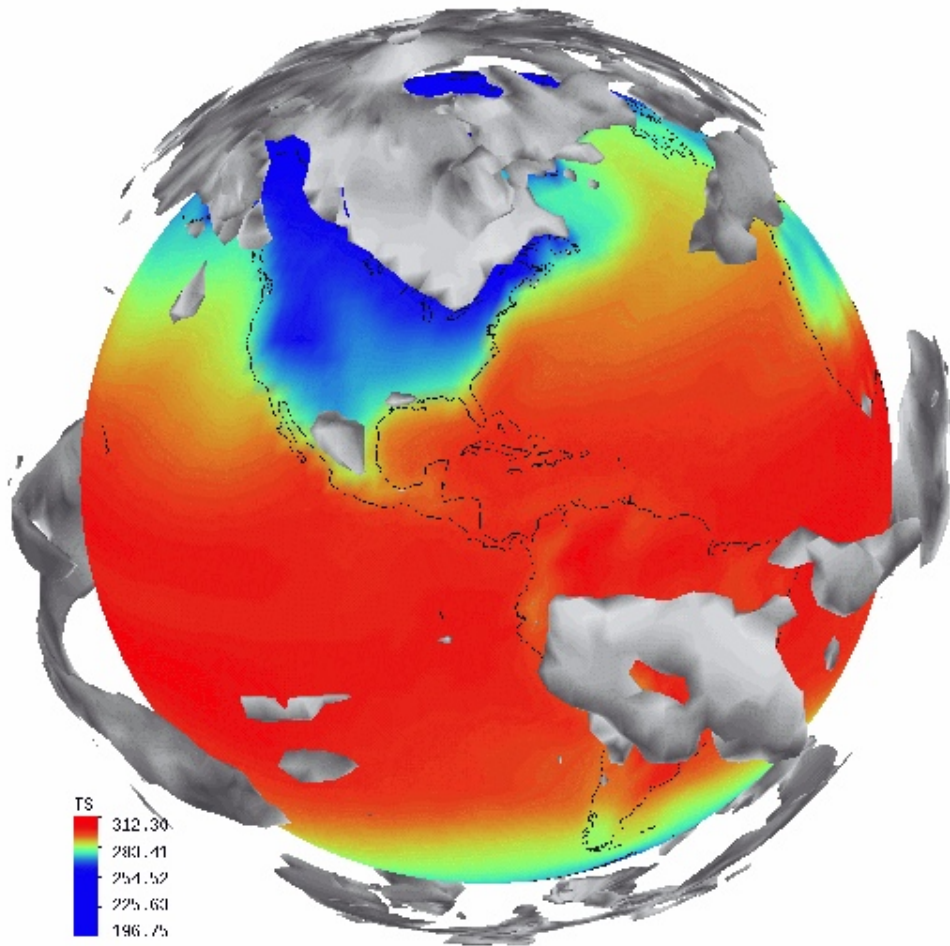
Evidence for attribution due to human activities



Scenarios for emissions in the future



A snapshot of a climate model



How do they do it?

Modeling the atmosphere

The physical equations to describe atmospheric motion are derived from fluid mechanics and thermodynamics.

The complete state depends on:

- 3-d wind field, v
- pressure p
- temperature T
- heating by radiation Q_{rad} , condensation Q_{con}
- evaporation E and condensation C from clouds
- D_H D_M and D_q are diffusion terms.

Climate System Model (CSM)

General Circulation Model (GCM): A deterministic numerical model that describes the circulation of the atmosphere by solving the primitive equations in a discretized form.

- Conceptually based on grid boxes (for the NCAR climate system model: there are $128 \times 64 \times 17 \approx 141K$) and the state of the atmosphere is the average quantities for each box ($\approx 1M$ real numbers).
- Each grid cell is large (for NCAR CSM/PCM $\approx 170 \times 170$ miles) and so important processes that affect large scale flow are not resolved by the grid.
- GCM must be stepped on the order of minutes, even for a 200+ year numerical experiment! To halve the horizontal resolution the amount of computing goes up by $2^4 = 16$.

Climate System Model

A GCM coupled to other models for the ocean, ice , land, chemistry, etc. to model the entire climate system. Coupling these components without overt flux adjustments is an important feature.

Called an AOGCM because air/ocean coupling is the most important.

- Several models years can be simulated per *day* on a large computer. Full numerical experiments are limited and expensive.
- The NCAR model takes 50+ people to maintain and develop
- Completely deterministic!

Motivation

Based on model results, what will the climate be like in 2100?

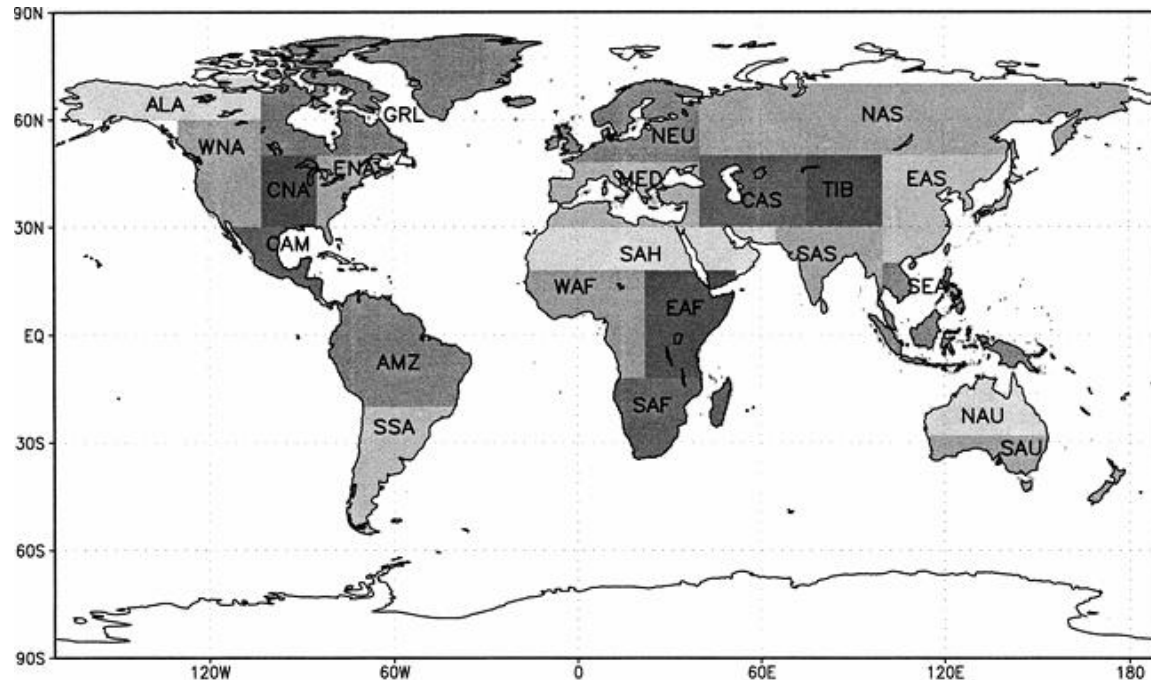
- **Reconciling different projections** - no model is the true model!
- Offering **stake-holders** and **policy-makers** a probabilistic forecast.
- Substituting formal **probabilistic assumptions** for **heuristic criteria**, and testing sensitivity of the results to them.

Impacts of climate change include: Extremes in summer temperatures, Possible degradation in air quality, Changes in the domain of vector-borne diseases. All of these have implications for human health.

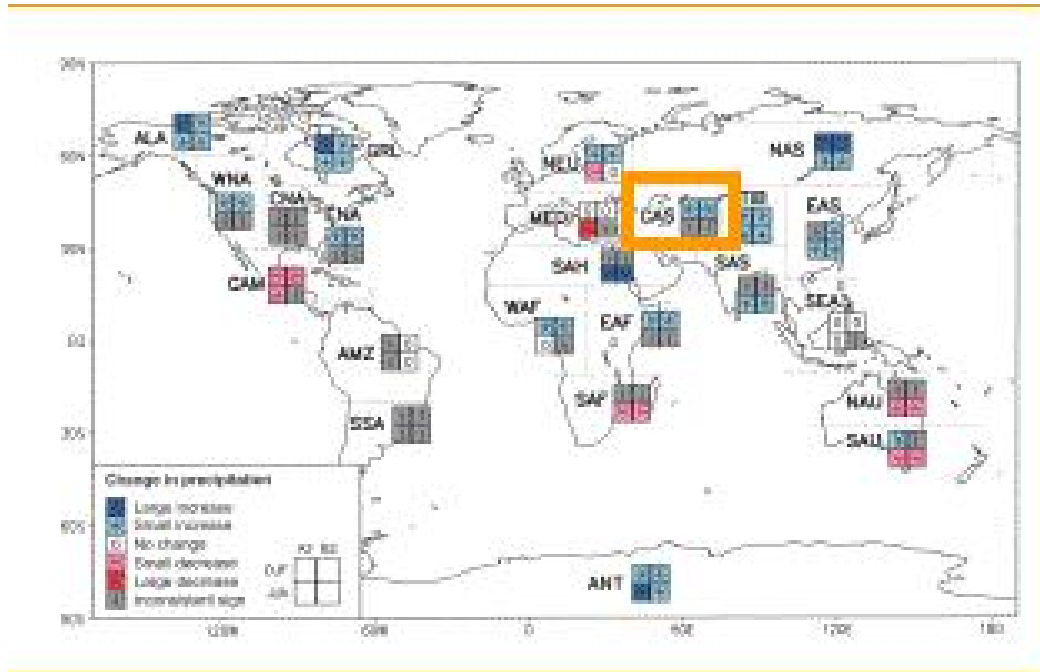
The Data

- 9 AOGCMs;
- 22 Regions;
- 2 Seasons;
- Simulated Temperature values in 30-years averages (X , 1961-1990; Y , 2071-2100 (A2));
- Observed Temperature average, X_0 , for 1961-1990. (Allows for an estimate of model bias for current climate.)

Regions



State-of-the art inference for the last IPCC report



Some background: Reliability Ensemble Average

- *Journal of Climate*, May 2002: Calculation of Average, Uncertainty Range and Reliability of Regional Climate Change from AOGCM Simulations....., by Giorgi and Mearns.
- Combine regional climate results , based on a **WEIGHTED AVERAGE**.
- Weights take into account:
model performance (**BIAS**)
and
model agreement (**CONVERGENCE**).

Reliability Ensemble Average (cont'd)

Given the single AOGCM responses:

$$\{\Delta T_i\}_{i=1,\dots,9}$$

The summary is given by a weighted average:

$$\widehat{\Delta T} = \sum_i \frac{R_i \Delta T_i}{\sum_i R_i}$$

where the weights are iteratively recomputed, since they include $\widehat{\Delta T}$ itself, the target of the estimation:

$$R_i = K_{nat. \text{ var.}} \cdot \left(\frac{1}{|T_0 - T_i|} \cdot \frac{1}{|\widehat{\Delta T} - \Delta T_i|} \right)^p$$

Incidentally: This is robust estimation!

The (implicit) loss function minimized is:

$$\sum_i w_i |\Delta T_i - \delta|^{2-p}$$

If $p = 1$, $\hat{\delta}$ is the (weighted) median of the 9 AOGCM responses.

A Bayesian model for future climate outcomes

For one region:

Model i produces a **current temperature reconstruction**

$$X_i \sim N[\mu, \lambda_i^{-1}]$$

and a **future temperature projection**

$$Y_i \sim N[\nu, (\theta \lambda_i)^{-1}]$$

The **observed current temperature** is

$$X_0 \sim N[\mu, \lambda_0^{-1}]$$

True current temperature μ , true future temperature ν ,
AOGCM's precision λ_i , “inflation/deflation” of precision future
 θ

A Bayesian model for future climate outcomes (cont'd)

The i th model has some **unknown precision** λ_i

Bias of the i th model wrt current climate and
Convergence of the i th model within the ensemble
give information on λ_i

Prior distribution is

$$\lambda_i \sim \Gamma(a, b)$$

with $a = b = .001$

Very weak prior assumption – nevertheless proper posteriors result.

A Bayesian model for future climate outcomes (cont'd)

Priors for μ , ν and θ are:

$$\mu \sim U(-\infty, +\infty)$$

$$\nu \sim U(-\infty, +\infty)$$

$$\theta \sim \Gamma(c, d)$$

with $c = d = .001$

As non-committed as we can be.

Perhaps expert knowledge could be included.

Gibbs sampler

- Simple Gibbs sampler – all full conditionals are either gammas or gaussians.
- Conclusions based on a total of 50,000 values for each parameter, representing a sample from its posterior distribution.
- Convergence verified by standard diagnostic tools.

Conditional distributions for present and future temperature

Assume $\lambda_1, \lambda_2, \dots, \lambda_9$ known:

Define

$$\tilde{\mu} = (\sum_{i=0}^9 \lambda_i X_i) / (\sum_{i=0}^9 \lambda_i)$$

and

$$\tilde{\nu} = (\sum_{i=1}^9 \lambda_i Y_i) / (\sum_{i=1}^9 \lambda_i)$$

Then, posteriors for present and future true temperatures:

$$\begin{aligned}\mu | \dots &\sim N[\tilde{\mu}, (\sum_{i=0}^9 \lambda_i)^{-1}] \\ \nu | \dots &\sim N[\tilde{\nu}, (\theta \sum_{i=1}^9 \lambda_i)^{-1}]\end{aligned}$$

But λ_i is unknown,
so...back to bias and convergence!

The posterior for λ_i is $\Gamma[a + 1, b + \frac{1}{2}((X_i - \tilde{\mu})^2 + \theta(Y_i - \tilde{\nu})^2)]$

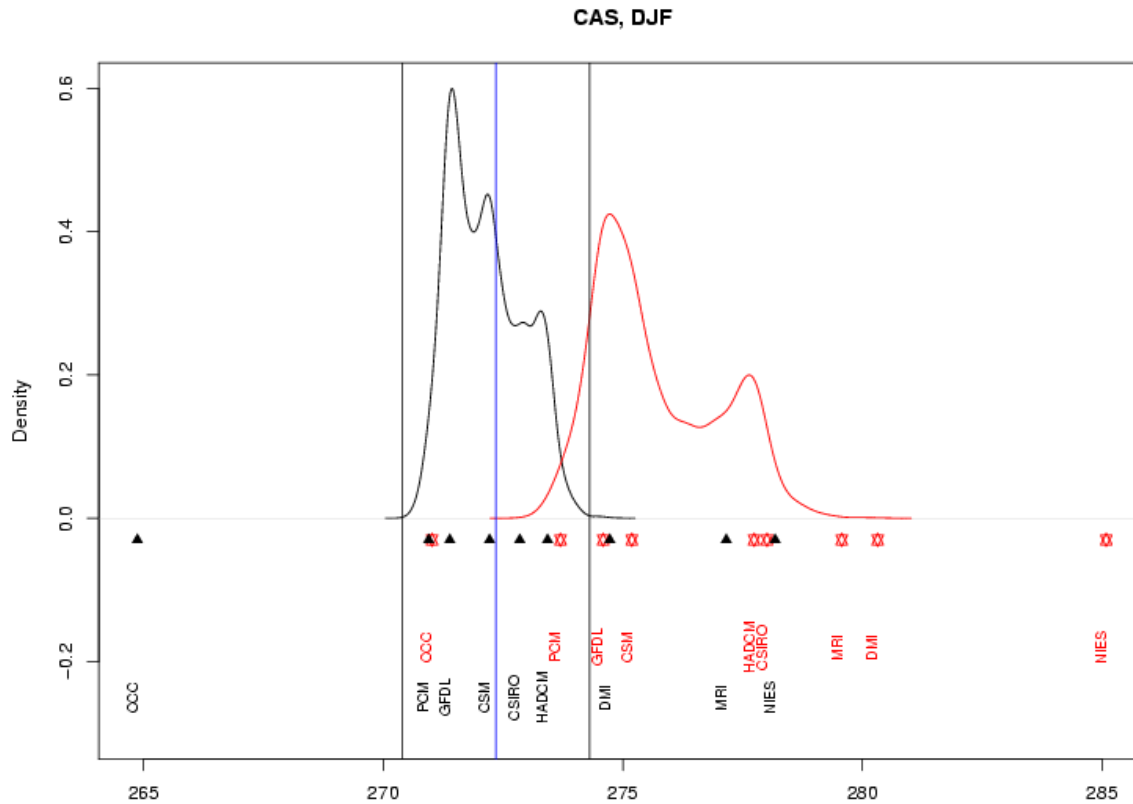
The posterior mean for λ_i is

$$\frac{a+1}{b+\frac{1}{2}((X_i-\tilde{\mu})^2+\theta(Y_i-\tilde{\nu})^2)}$$

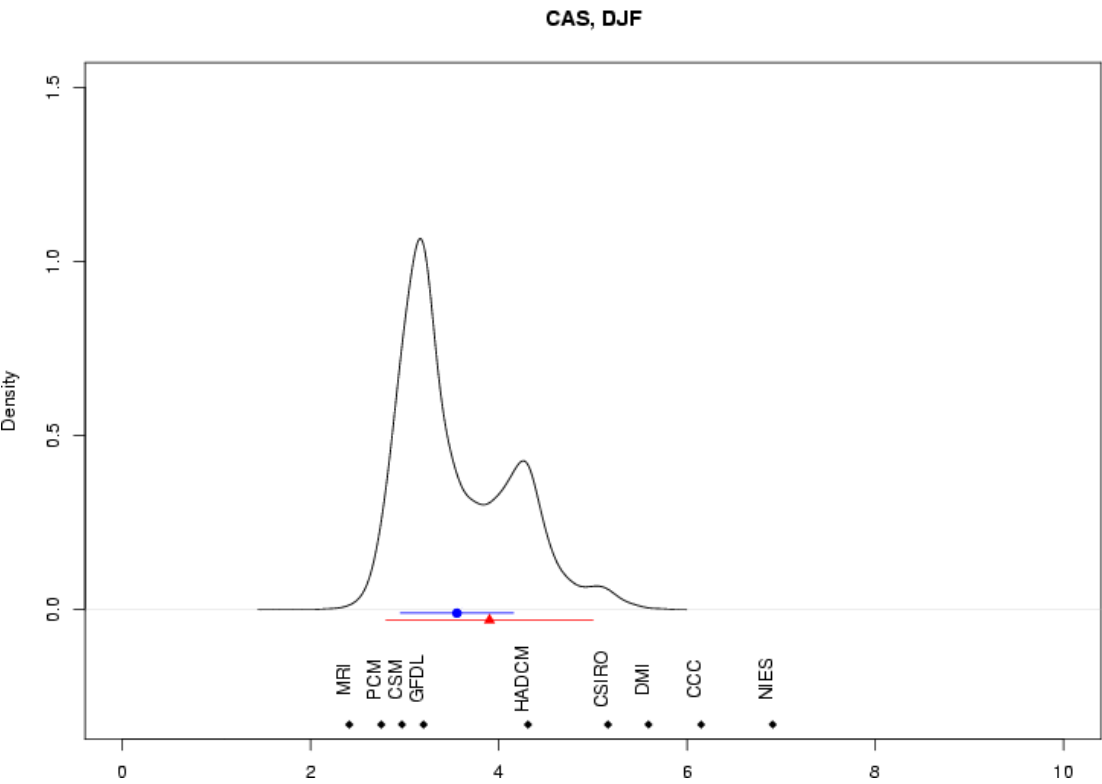
Large only if both $|X_i - \tilde{\mu}|$ ("bias")
and $|Y_i - \tilde{\nu}|$ ("convergence") are small

The "bias" becomes exactly $|X_i - X_0|$
if $\lambda_0 \rightarrow \infty$ in which case $\tilde{\mu} \rightarrow X_0$

A tour of Central Asia: posteriors for μ and ν



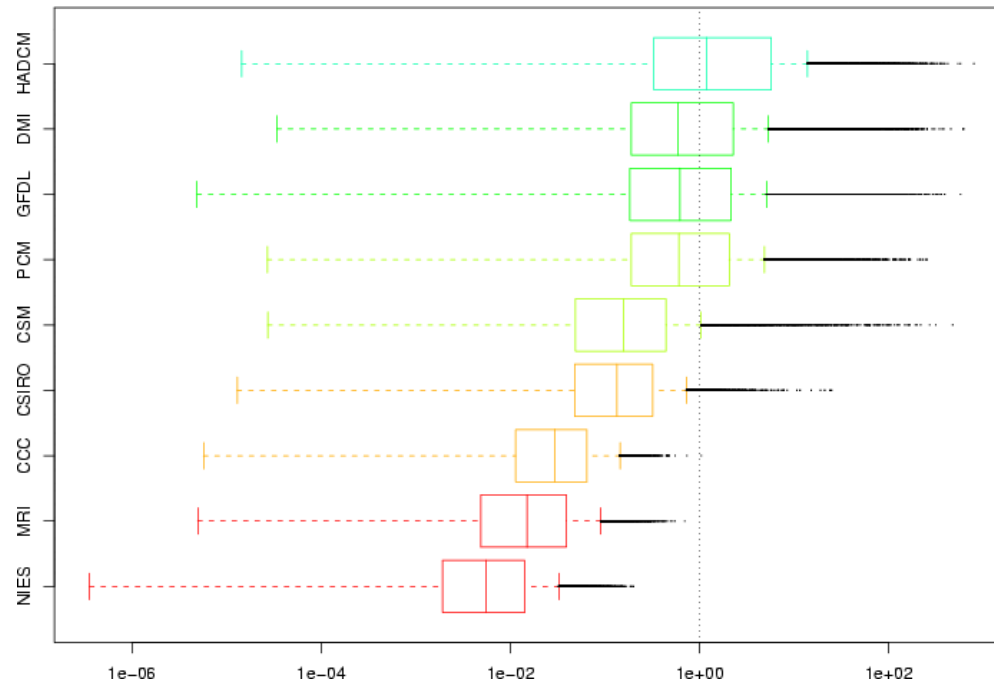
Posterior for climate change $\Delta T = \nu - \mu$



	NIES	MRI	CCC	CSIRO	CSM	PCM	GFDL	DMI	HADCM
BIAS	5.83	4.81	-7.48	0.50	-0.13	-1.40	-0.96	2.38	1.08

A tour of Central Asia

Model precision λ_i



	NIES	MRI	CCC	CSIRO	CSM	PCM	GFDL	DMI	HADCM
$\tilde{\lambda}_i / \sum_i \tilde{\lambda}_i \times 100$	0.04	0.12	0.18	1.09	5.00	12.73	19.95	23.08	37.81

Model precision as weight

Notice the amount of additional information when going from a table to a picture of distributions.

Clear ranking of models, but substantial spread and uncertainty (overlapping of the distributions).

Extensions

1. Is Y_i (cor)related with X_i ?
2. Do we have real outliers among X_i and Y_i ?

Easily modeled:

1. Assume

$$X_i \sim N[\mu, (\lambda_i)^{-1}]$$

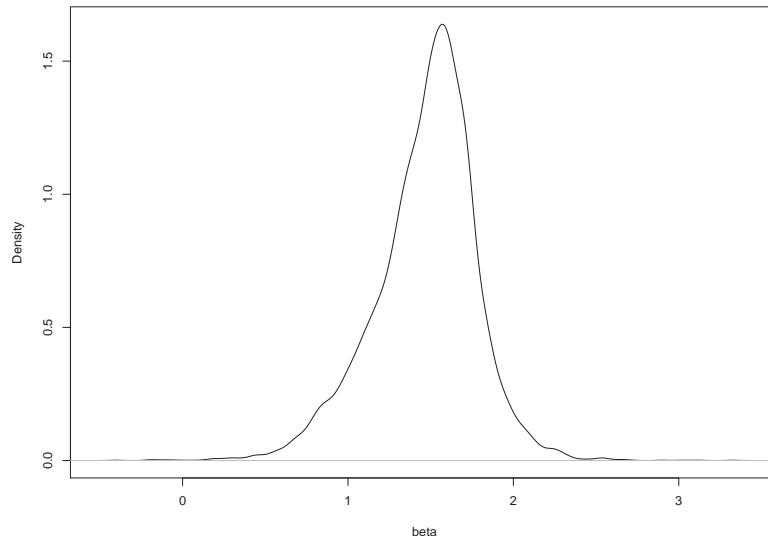
and

$$Y_i \sim N[\nu + \beta(X_i - \mu), (\theta\lambda_i)^{-1}]$$

2. Assume heavy-tailed distributions instead of gaussians for X_i and Y_i

A tour of Central Asia

Regression coefficient between future and present climate β

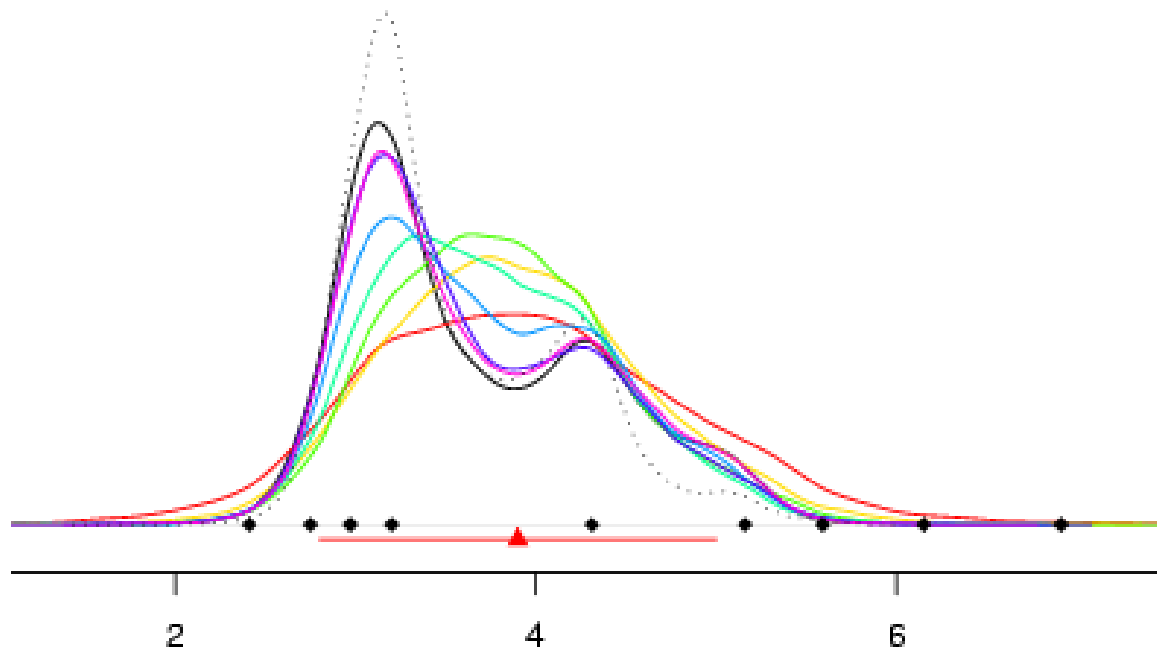


Different from 0!

A tour of Central Asia

Climate change under different statistical assumptions

Results varying across T -family.



$N = 10000$ Bandwidth = 0.1002

A multivariate version

Are the temperatures of an AOGCM in **different regions** correlated?

Double indexing...

i indexes **AOGCMs (9)**, j indexes **regions (22)**

Then:

$$X_{0j} \sim N[\mu_j, \lambda_{0j}^{-1}],$$

$$X_{ij} \sim N[\mu_j + \alpha_i, (\phi_j \lambda_i)^{-1}],$$

$$Y_{ij} \sim N[\nu_j + \alpha_i' + \beta_x(X_{ij} - \mu_j - \alpha_i), (\theta_j \lambda_i)^{-1}],$$

$$\alpha_i' \sim N[\beta_\alpha \alpha_i, (\psi_i)^{-1}].$$

Main features

- Still **region specific** μ_j and ν_j .
- The additive effects α_i and α'_i , common to all regions **for a given model**, introduce correlation.
- β_α and β_x introduce correlation between regions as well, in addition to allowing for correlation **between future and current responses**.

Main features (cont'd)

- Systematic variations of precision with regions, but retaining a "model precision" component: the precision is a product of two factors.

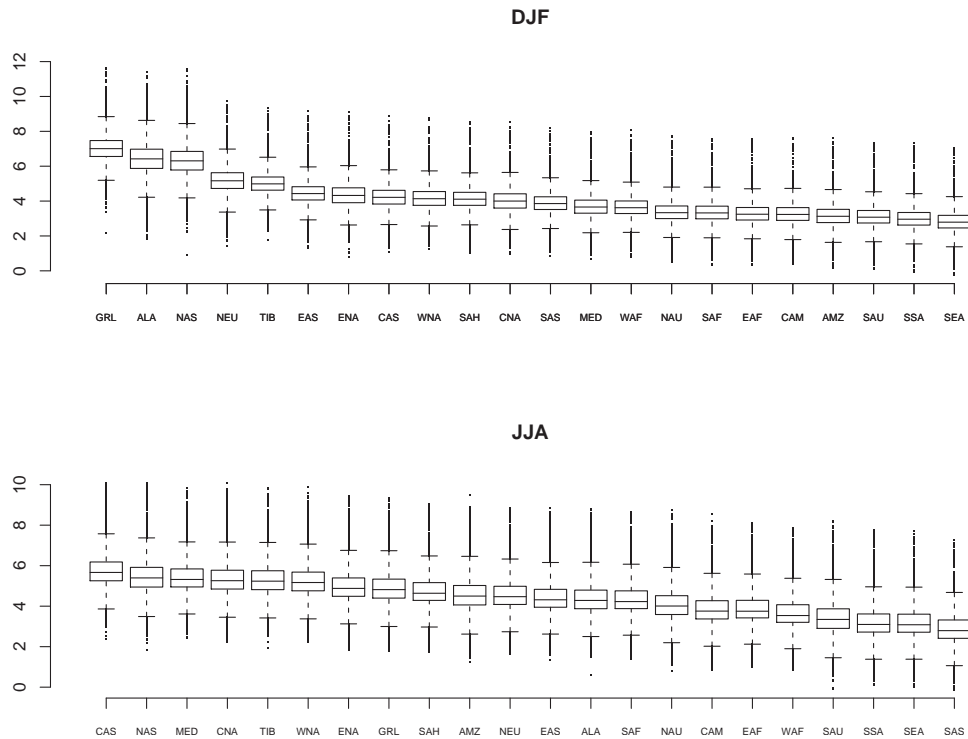
λ_i **model-specific**

θ_j, ϕ_j **region-specific**

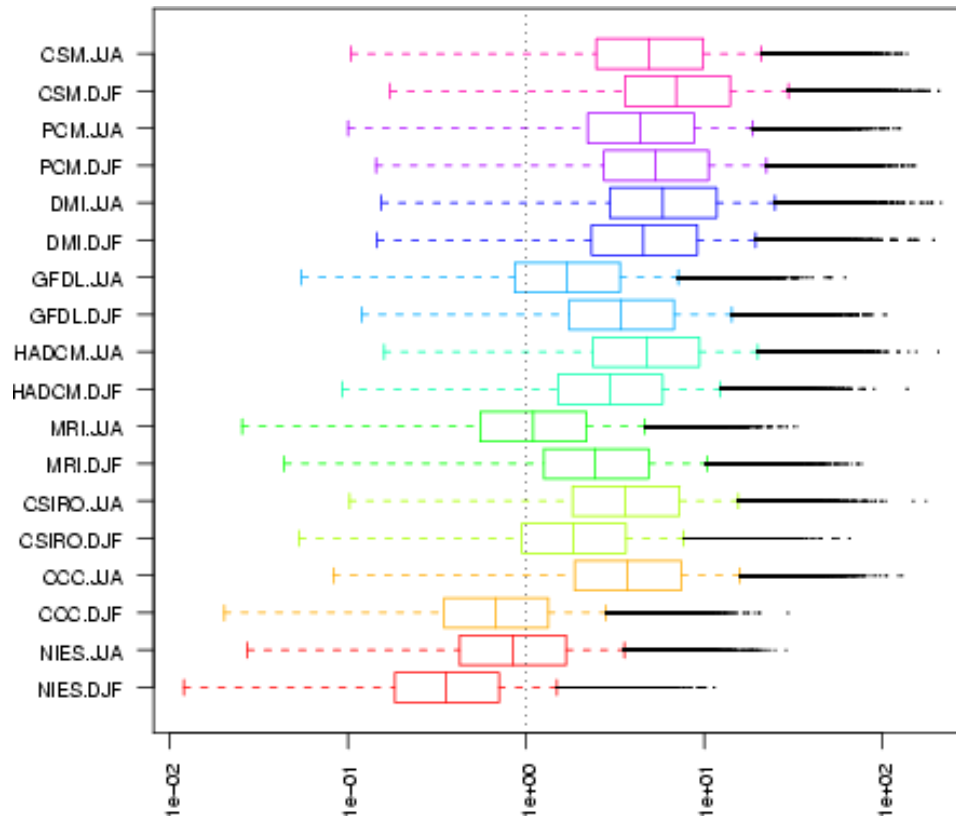
- We borrow strength from **all the regional responses** in estimating λ_i 's;
- We gather information from **all the models** in the posterior distribution of θ_j, ϕ_j 's.
- Two different region-specific factors, θ_j and ϕ_j in the precisions of present and future temperatures' distributions: **the "quality" of the regional climate simulation may vary between the two simulation periods.**

Climate change

The big picture



Model-specific precision factors λ_i



Conclusions

- We have formalized the criteria of *bias* and *convergence* as a way of analyzing Multi-model ensembles.
- There is a hierarchy of models available. The assumptions for each are clearly stated. In particular the prior assumptions are vague, not constraining any of the parameters a priori.
- The posterior distributions from combining models can be used to propagate uncertainty into other models to assess the impacts of a changed climate.
- We can perform sensitivity analysis to prior assumptions.