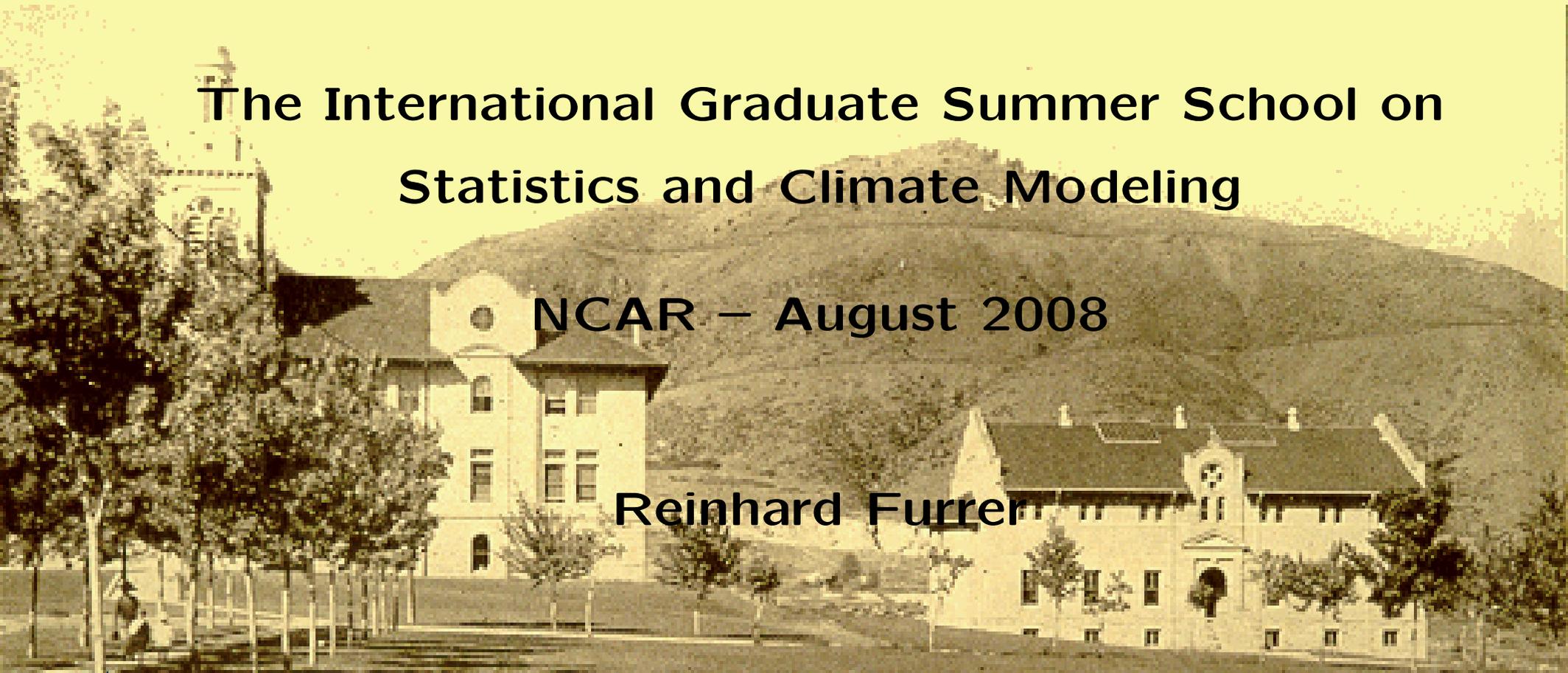


A Bayesian view of climate change: assessing uncertainties of general circulation model projections

**The International Graduate Summer School on
Statistics and Climate Modeling**

NCAR – August 2008

Reinhard Furrer



We present probabilistic projections for spatial patterns of future temperature change using a hierarchical Bayesian model.

Collaboration with: Reto Knutti - ETHZ

Stephan Sain, Doug Nychka, Claudia Tebaldi,
Jerry Meehl, Linda Mearns, . . . - NCAR

NSF DMS-0621118



Outline of the Talk

- Climate projection data
- A simple hierarchical Bayesian model
- Presenting uncertainty results
- Model extensions



Studying Climate with AOGCMs

AOGCM: Atmosphere-Ocean General Circulation Models

Numerical models that calculate the detailed large-scale motions of the atmosphere and the ocean explicitly from hydrodynamical equations.

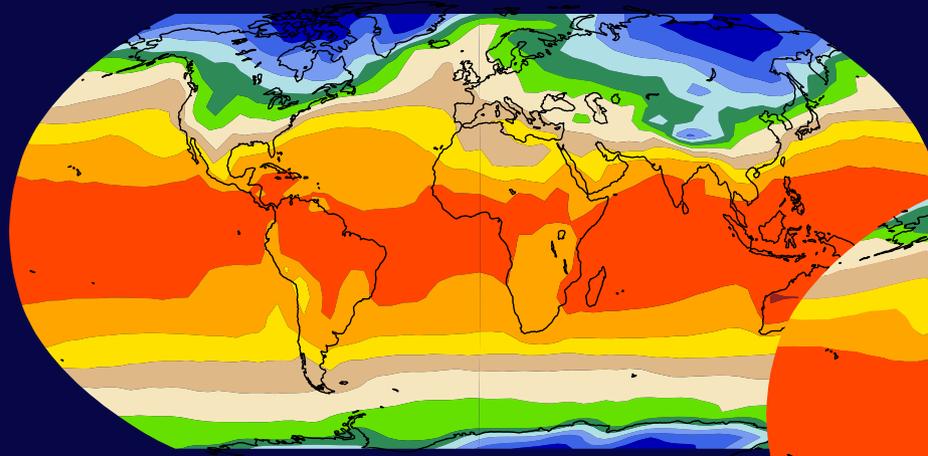


Studying Climate with AOGCMs

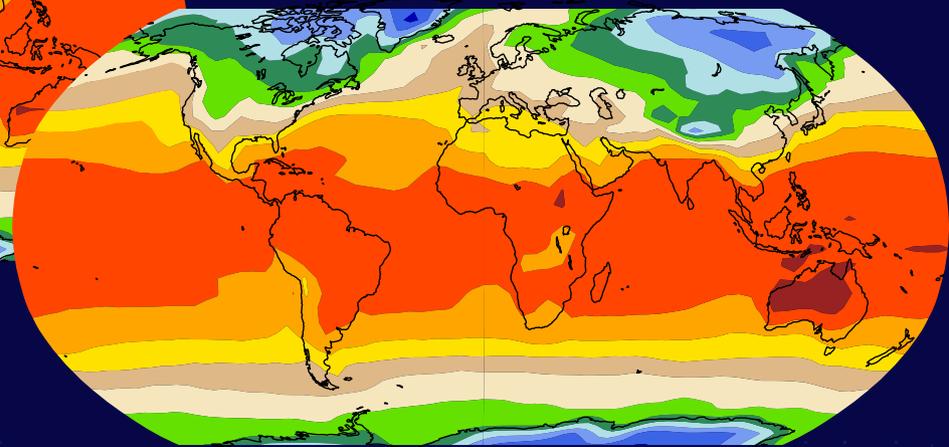
AOGCM: Atmosphere-Ocean General Circulation Models

CCSM3 DJF temperature

1980-2000



2080-2100

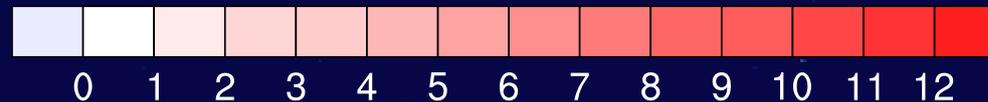
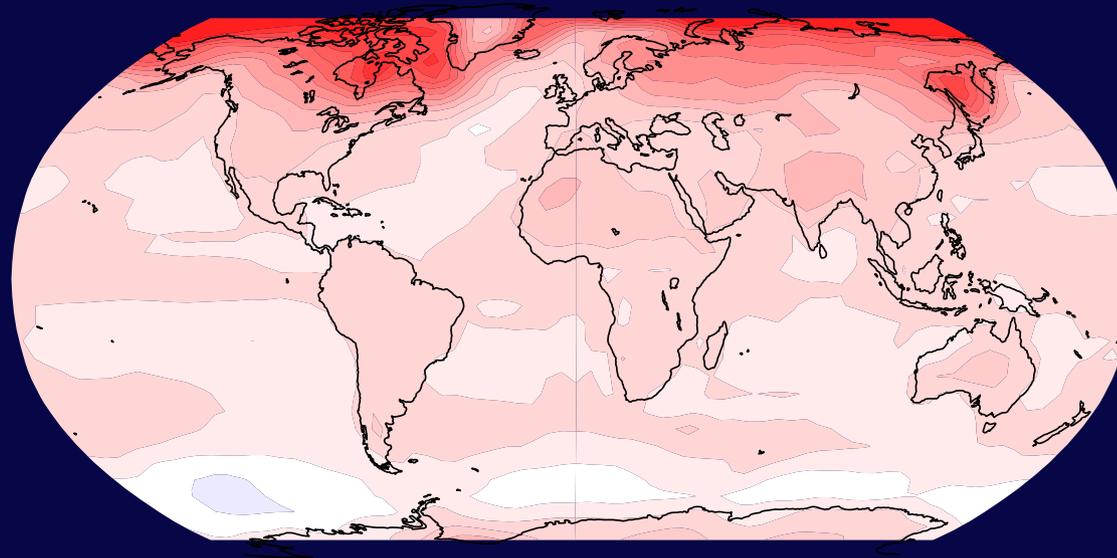


Studying Climate with AOGCMs

AOGCM: Atmosphere-Ocean General Circulation Models

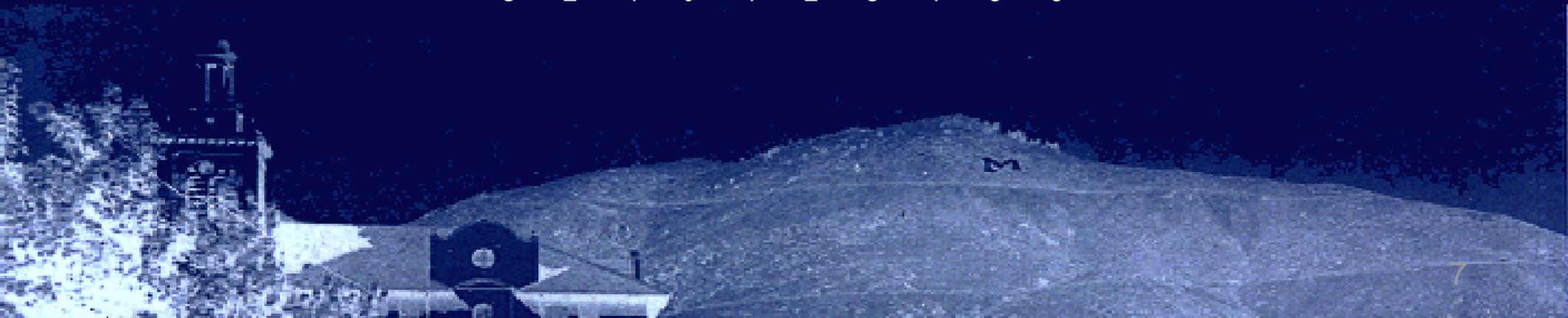
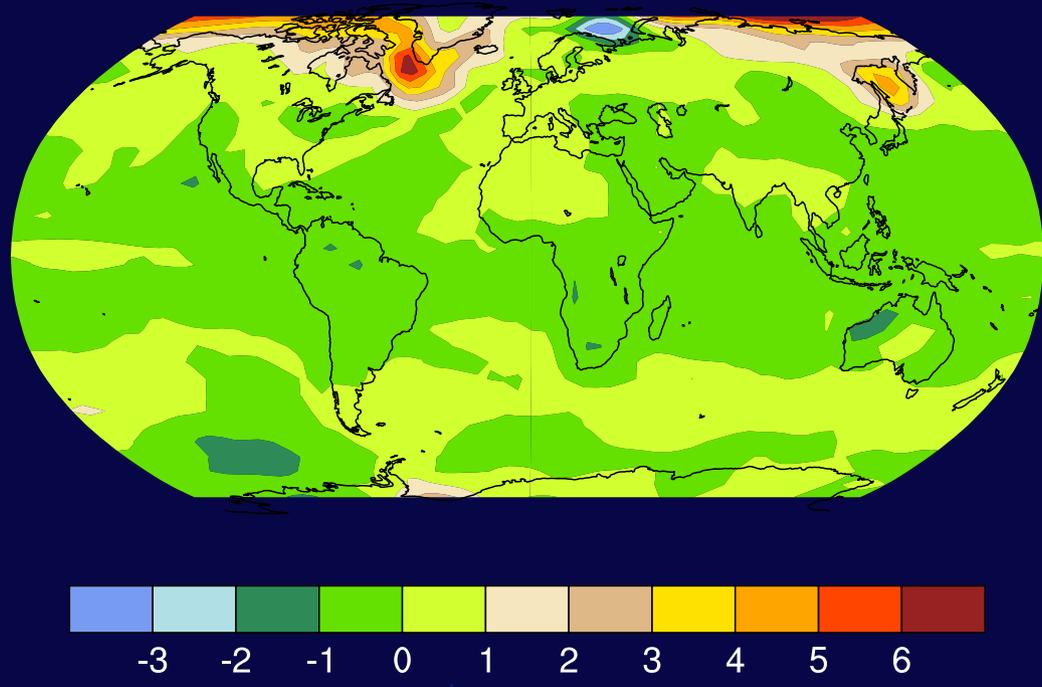
CCSM3 DJF temperature change

2080-2100 vs 1980-2000

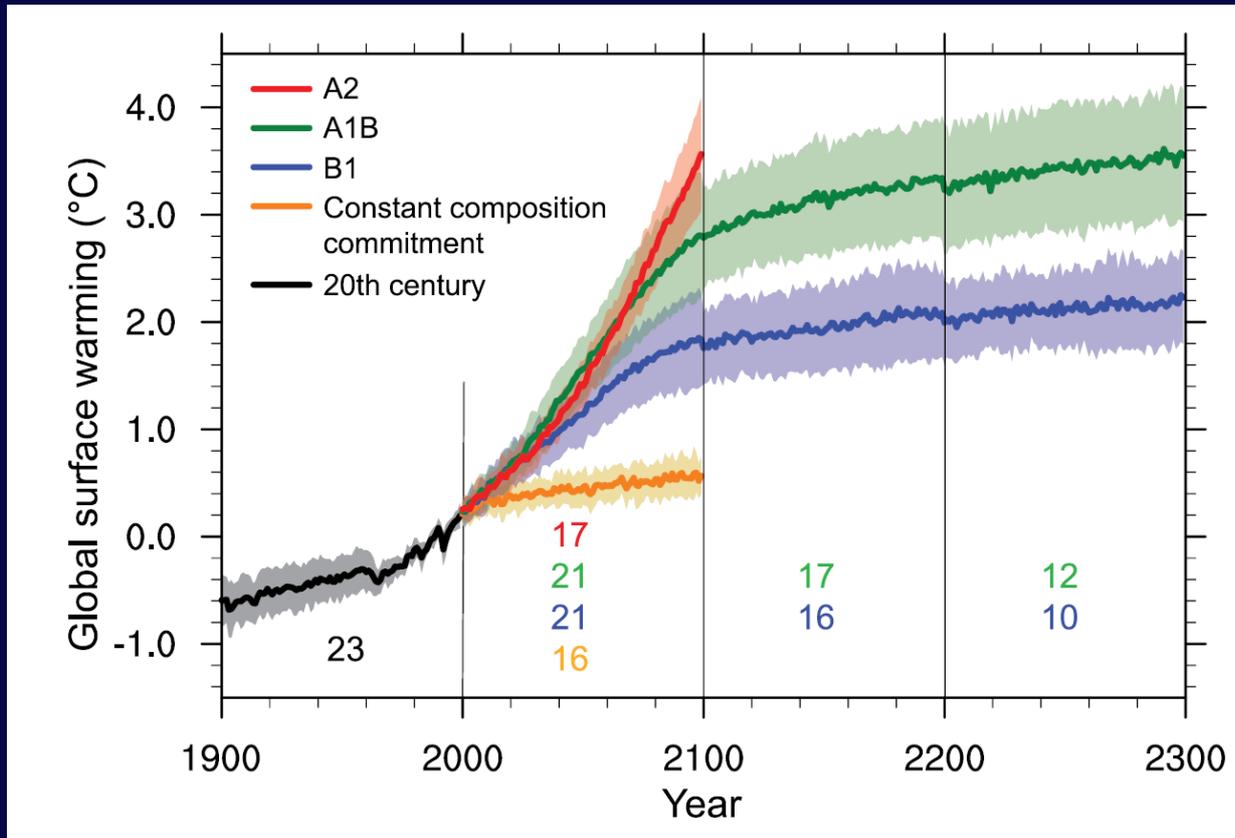


Models Do Not Agree

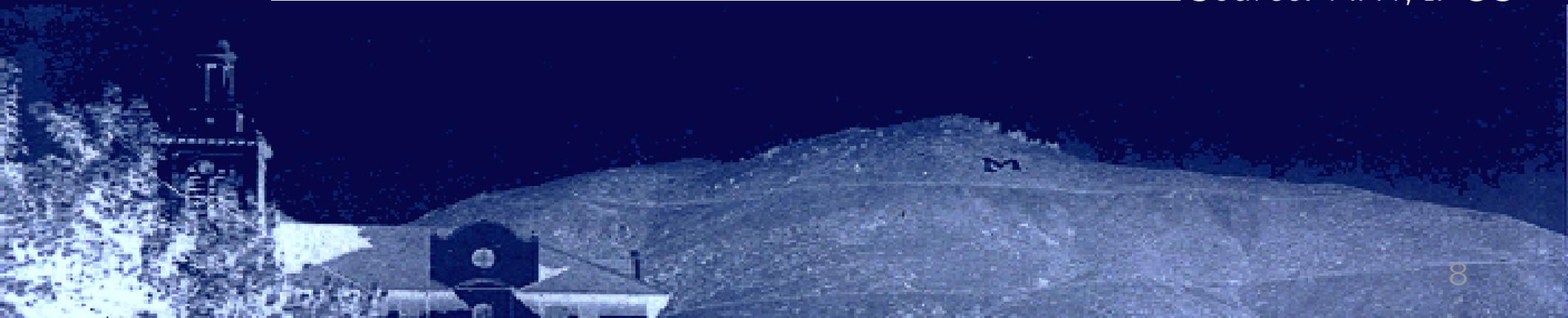
CCSM3 DJF temp change difference to sample mean (21 models)



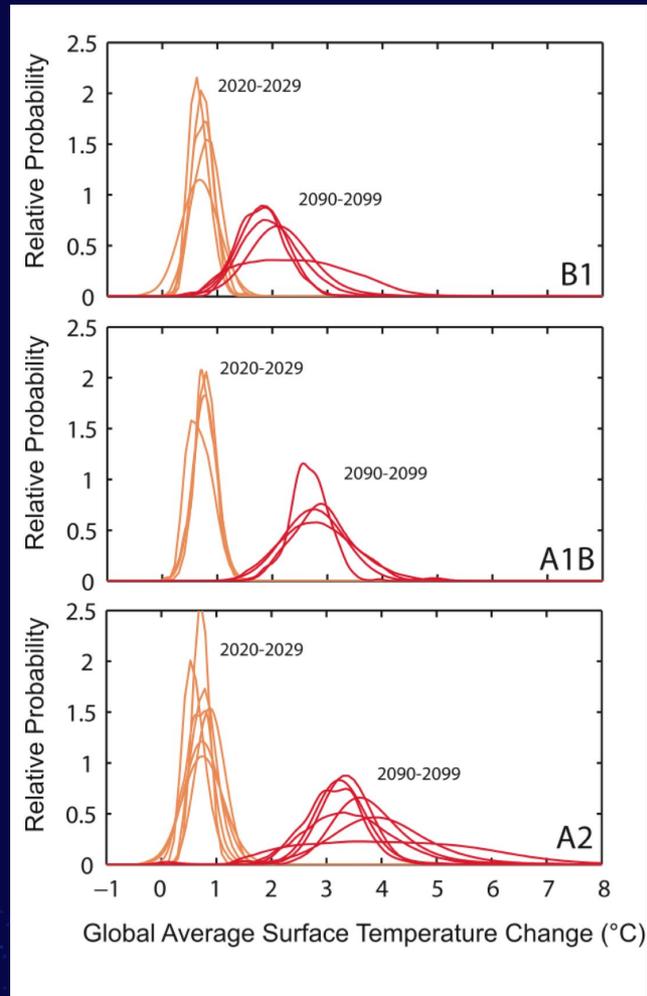
Models Do Not Agree



Source: AR4, IPCC

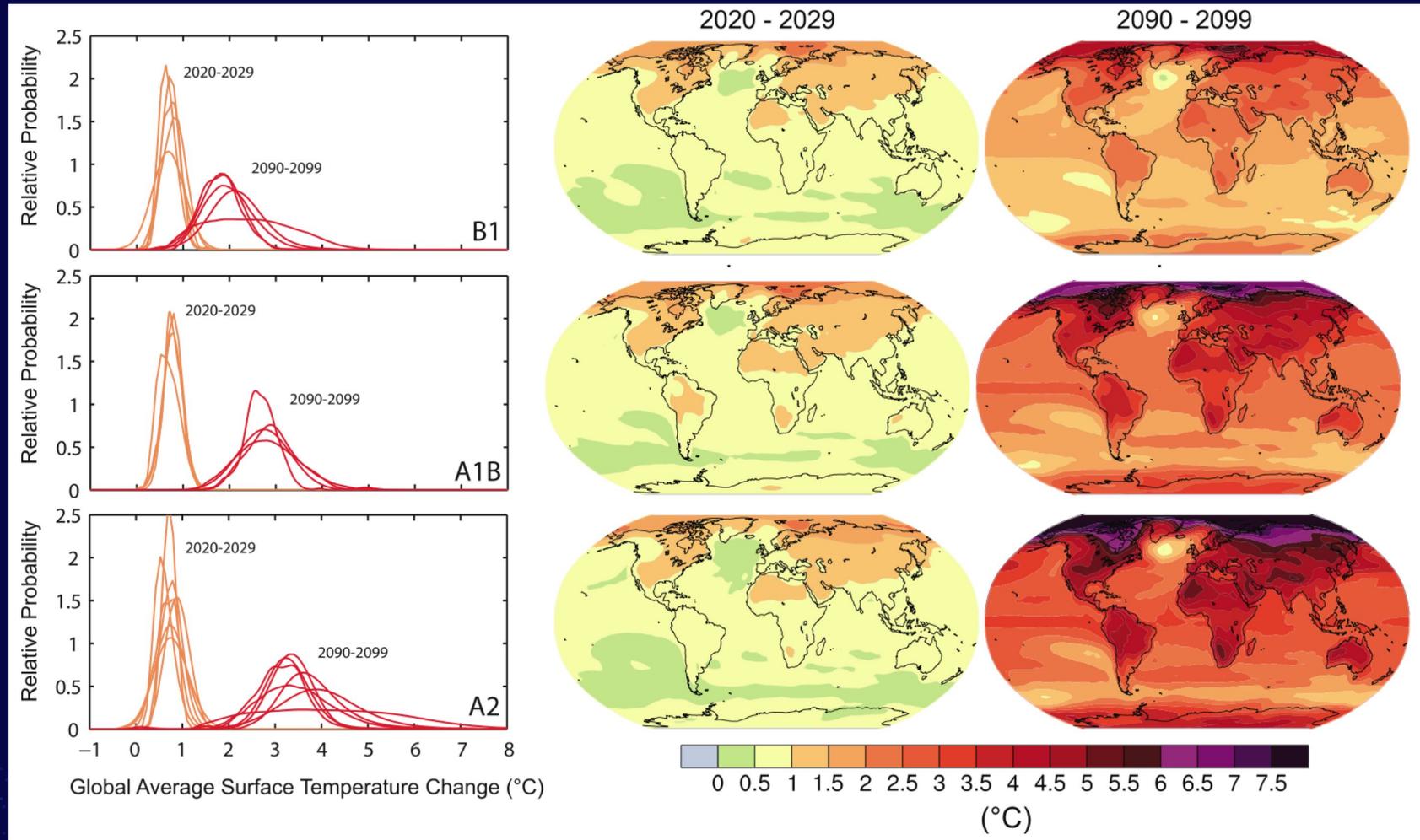


Quantifying Uncertainty



Source: AR4, IPCC

Quantifying Uncertainty



Source: AR4, IPCC

Data

Data provided for the Fourth Assessment Report of IPCC:

- 21 models (CCSM, GFDL, HADCM, PCM, ...)
- Around $2.8^\circ \times 2.8^\circ$ resolution (8192 data points, T42)
- Different scenarios (A2: “business as usual”, A1B, B1)
- Temperature, precipitation, pressure, winds...



Data

Data provided for the Fourth Assessment Report of IPCC:

- 21 models (CCSM, GFDL, HADCM, PCM, ...)
- Around $2.8^\circ \times 2.8^\circ$ resolution (8192 data points, T42)
aggregate to $5^\circ \times 5^\circ$ and omit the “poles” (3264 points).
- Different scenarios (A2: “business as usual”, A1B, B1)
- Temperature, precipitation, pressure, winds...
seasonal averages over years 1980–1999 and 2080–2099

Statistical Model

Given AOGCM output construct a statistical model to describe climate change probabilistically while accounting for all (most?) underlying uncertainties.



Statistical Model

Given AOGCM output construct a statistical model to describe climate change probabilistically while accounting for all (most?) underlying uncertainties.

For models $i = 1, \dots, N$, stack the gridded seasonal temperature into vectors:

\mathbf{X}_i = simulated present climate _{i}

\mathbf{Y}_i = simulated future climate _{i}

PDF and probabilistic description of climate change

$$\mathbf{D}_i = \mathbf{Y}_i - \mathbf{X}_i$$

Hierarchical Model

Separate the statistical modeling of a complex process into different levels consisting of:

Data level:	Classical geostatistics	(variogram, kriging)
Process level:	Multivariate analysis	(EOF, PCA)
Prior level:	Bayesian statistics	(priors, MCMC)

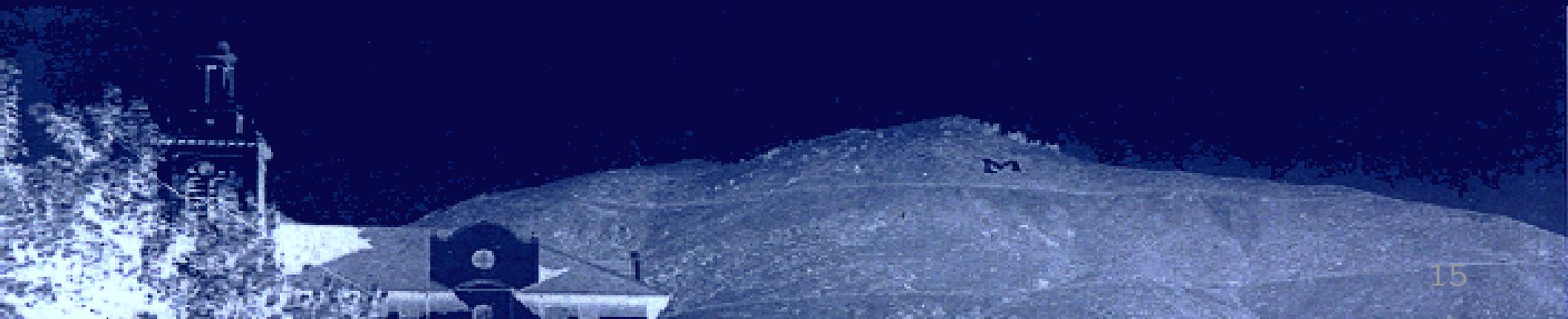
↪ hierarchical Bayesian modeling



Data Level

{ Data level | Process level | Prior level }

$$\mathbf{D}_i = \mathbf{Y}_i - \mathbf{X}_i = \text{simulated climate change}$$



Data Level

{ Data level | Process level | Prior level }

$\mathbf{D}_i = \mathbf{Y}_i - \mathbf{X}_i =$ simulated climate change
= large scale structure + small scale structure



Data Level

{ Data level | Process level | Prior level }

$\mathbf{D}_i = \mathbf{Y}_i - \mathbf{X}_i =$ simulated climate change
= large scale structure + small scale structure
= climate signal + model bias and internal variability



Data Level

{ Data level | Process level | Prior level }

$\mathbf{D}_i = \mathbf{Y}_i - \mathbf{X}_i =$ simulated climate change
= large scale structure + small scale structure
= climate signal + model bias and internal variability
= μ_i + ε_i

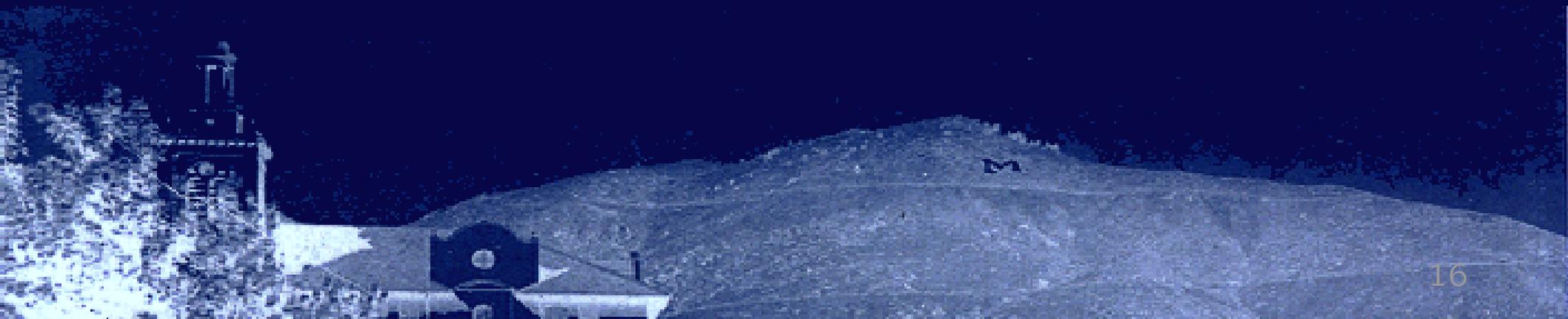
$\mathbf{D}_i \mid \mu_i, \phi_i \stackrel{\text{iid}}{\sim} \mathcal{N}_n(\mu_i, \phi_i \Sigma) \quad \phi_i > 0 \quad i = 1, \dots, N$
for given Σ

Process Level

{ Data level | Process level | Prior level }

$$\mu_i = \mathbf{M}\theta_i$$

for given \mathbf{M}



Process Level

{ Data level | Process level | Prior level }

$$\mu_i = \mathbf{M}\theta_i$$

for given \mathbf{M}

$$\theta_i \mid \nu, \psi_i \stackrel{\text{iid}}{\sim} \mathcal{N}_p(\nu, \psi_i \mathbf{I}) \quad \psi_i > 0 \quad i = 1, \dots, N$$

Prior Level

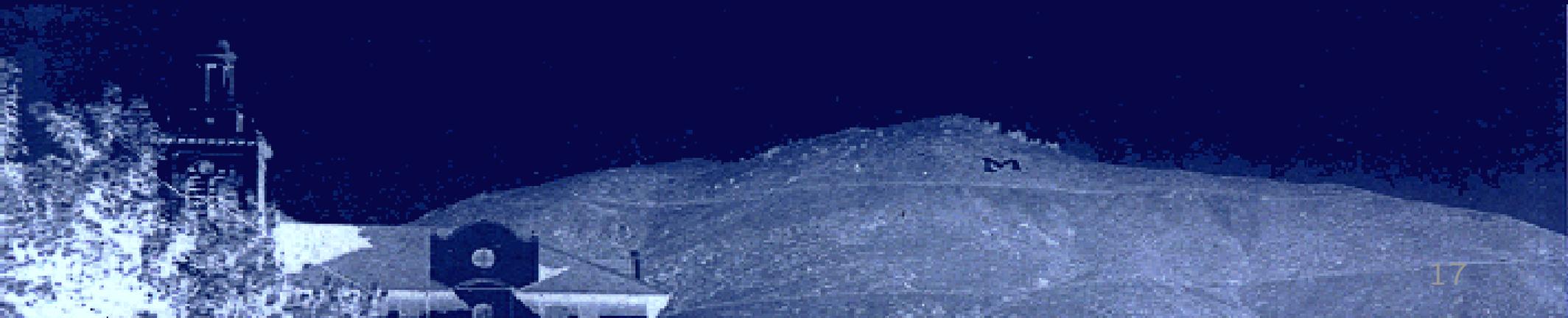
{ Data level | Process level | **Prior level** }

$$\phi_i \stackrel{\text{iid}}{\sim} \text{IG}(\xi_1, \xi_2) \quad \xi_1, \xi_2 > 0 \quad i = 1, \dots, N$$

$$\psi_i \stackrel{\text{iid}}{\sim} \text{IG}(\xi_3, \xi_4) \quad \xi_3, \xi_4 > 0 \quad i = 1, \dots, N$$

$$\boldsymbol{\nu} \sim \mathcal{N}_p(\mathbf{0}, \xi_5 \mathbf{I}) \quad \xi_5 > 0$$

for given ξ_1, \dots, ξ_5



Initial Parameters

For the different levels we need to specify:

Data level Covariance model for $\phi_i \Sigma$:
spatial coherence of internal variability and bias

Process level Basis functions used in \mathbf{M} :
practical decomposition of possible signals,
dimension reduction

Prior level Hyperparameters $\xi_1, \xi_2, \xi_3, \xi_4, \xi_5$:
tuning parameters

Covariance Model for $\phi_i \Sigma$

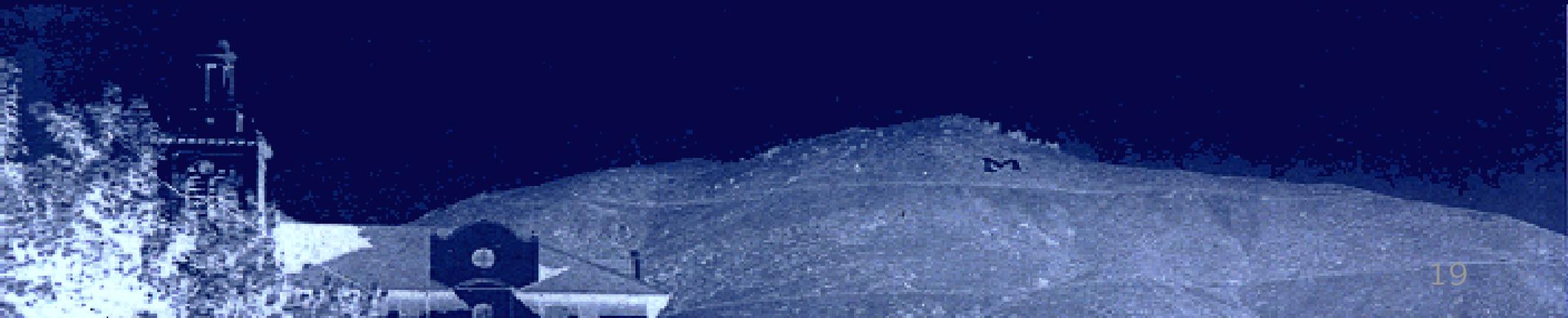
{ Data level | Process level | Prior level }

For the covariance matrices $\phi_i \Sigma$, we need positive definite functions on the sphere (by restricting one on \mathbb{R}^3 to \mathbb{S}^2):

$$c(h; \phi_i, \tau) = \phi_i \exp(-\tau \sin(h/2))$$

Individual variances ϕ_i are modelled.

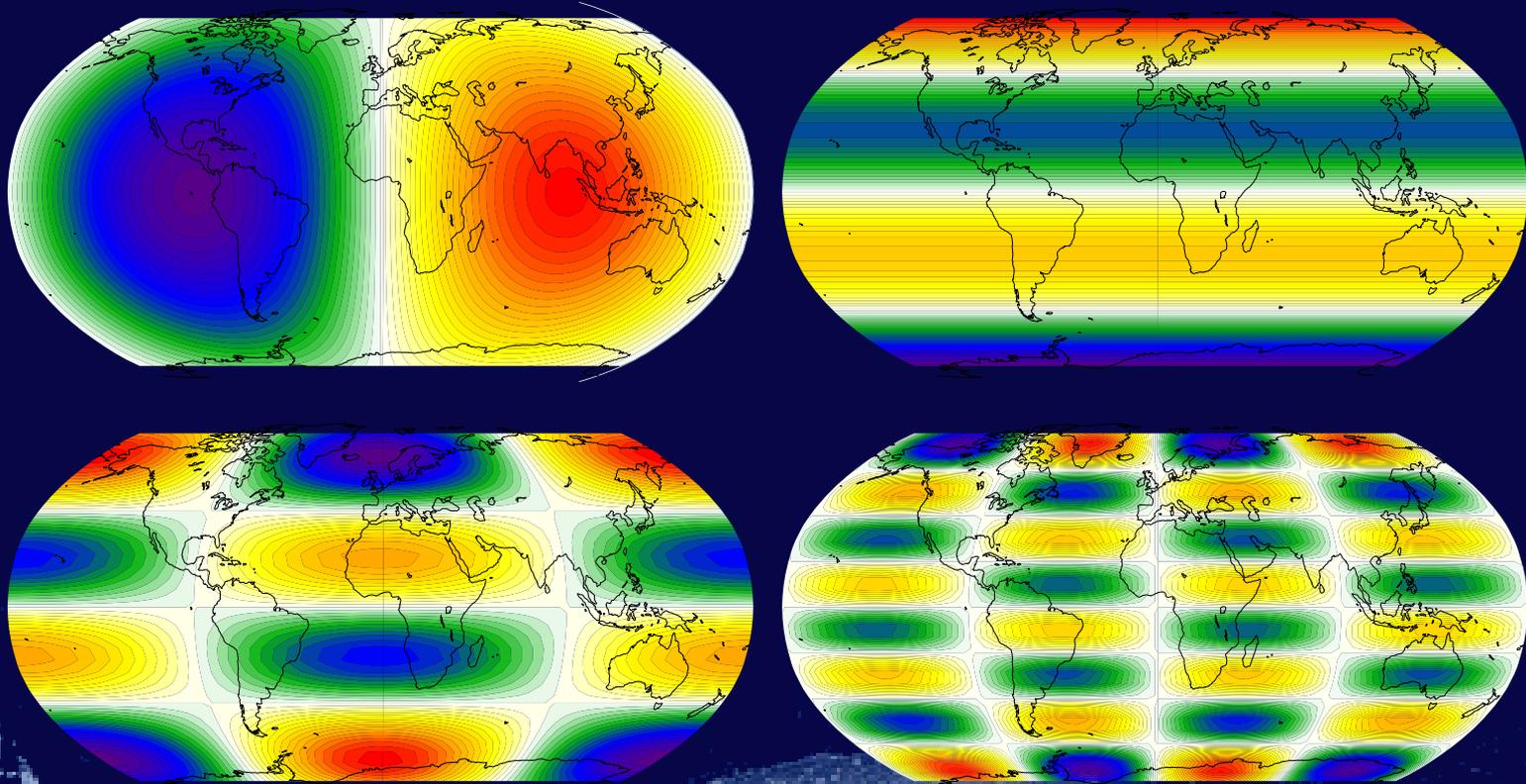
Common range τ is chosen according to an “empirical Bayes” approach.



Basis Functions Used in M

{ Data level | Process level | Prior level }

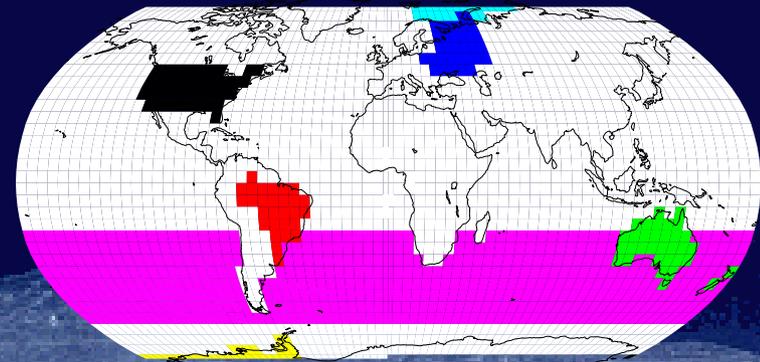
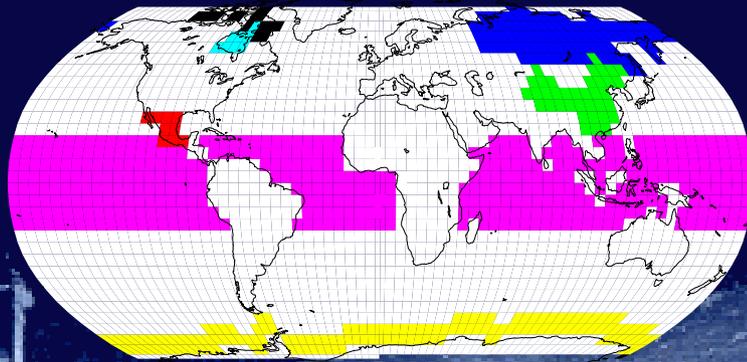
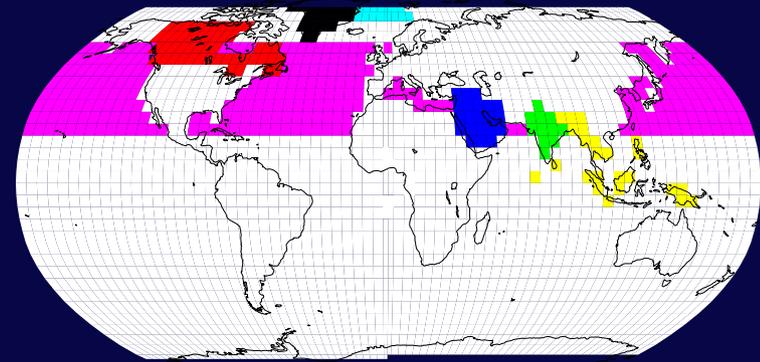
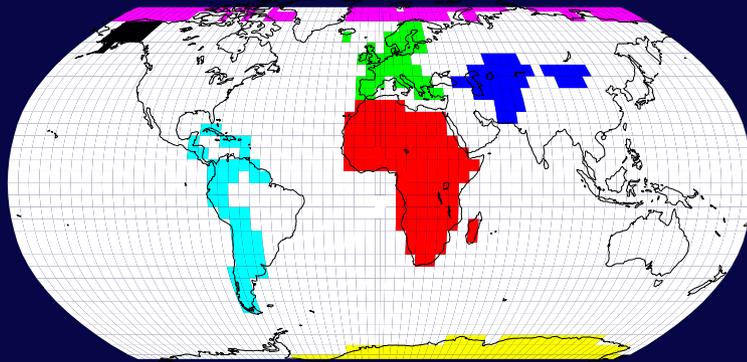
1. Spherical harmonics (here shown 4 out of 121)



Basis Functions Used in M

{ Data level | Process level | Prior level }

1. Spherical harmonics
2. Indicator functions (28)



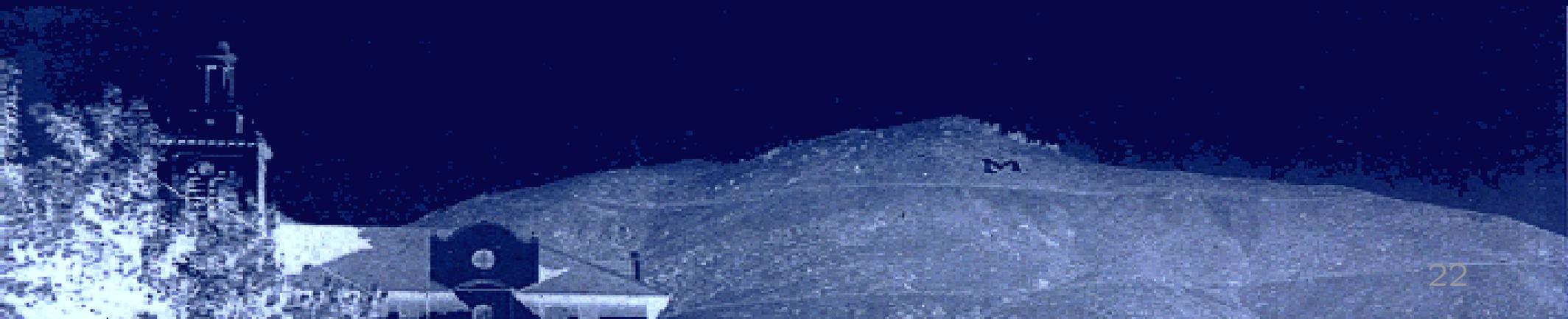
Hyperparameters ξ_1, \dots, ξ_5

{ Data level | Process level | **Prior level** }

To make sure that variability around the truth is smaller than bias and internal variability

$$\phi_i > \psi_i$$

Choose ξ_1, ξ_2, ξ_3 small, $\xi_4 \in [1, 2.5]$, ξ_5 large.



PDF of Climate Change

The goal is the (posterior) PDF of the climate change signal given the AOGCM data and model parameters:

[climate change | AOGCM data, model parameters ...]

[$\mathbf{M}\nu$ | $\mathbf{D}_1, \dots, \mathbf{D}_N$, ...]



PDF of Climate Change

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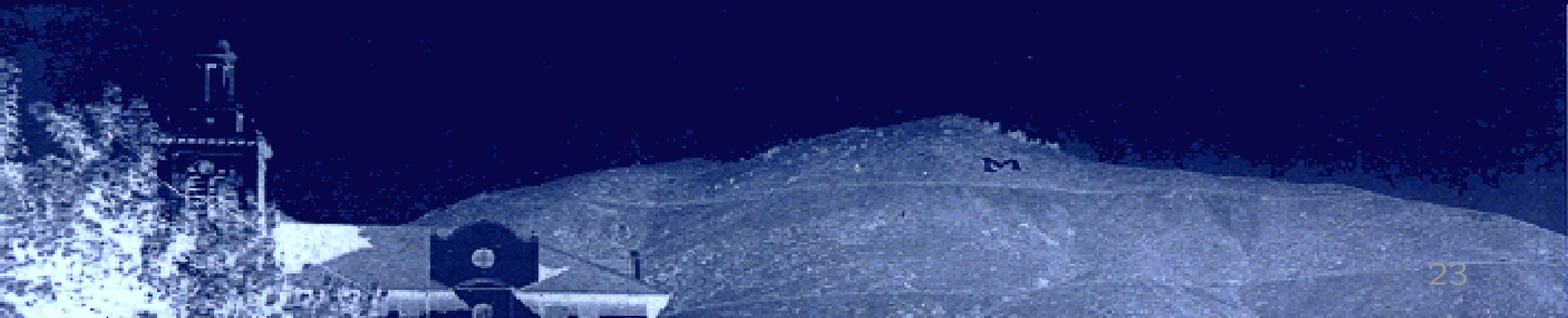
[$\mathbf{M}\nu$ | $\mathbf{D}_1, \dots, \mathbf{D}_N$, ...]

Via Bayes' theorem, the (posterior) PDF is

[process | data, parameters]

\propto [data | process, parameters]

\cdot [process | parameters] \cdot [parameters]



Computational Approach

No closed form of the posterior density.

Use a computational approach: Markov Chain Monte Carlo (MCMC), here a Gibbs sampler.

1. Express the distribution of each parameter conditional on everything else (full conditionals).
2. Cycle through the parameters: draw a new value based on the full conditional and the current values of the other parameters.
3. Repeat, ...

Full Conditionals

Full conditionals for all parameters have been derived:

$$\boldsymbol{\nu} \mid \dots \sim \mathcal{N}_p(\mathbf{A}^{-1}\mathbf{b}, \mathbf{A}^{-1})$$

$$\mathbf{A} = \frac{1}{\xi_5} \mathbf{I} + \sum_{i=1}^N \frac{1}{\psi_i} \mathbf{I} \quad \mathbf{b} = \sum_{i=1}^N \frac{1}{\psi_i} \boldsymbol{\theta}_i$$

$$i = 1, \dots, N : \boldsymbol{\theta}_i \mid \dots \sim \mathcal{N}_p(\mathbf{A}^{-1}\mathbf{b}, \mathbf{A}^{-1})$$

$$\mathbf{A} = \frac{1}{\psi_i} \mathbf{I} + \frac{1}{\phi_i} \mathbf{M}^\top \boldsymbol{\Sigma}^{-1} \mathbf{M} \quad \mathbf{b} = \frac{1}{\psi_i} \boldsymbol{\nu} + \frac{1}{\phi_i} \mathbf{M}^\top \boldsymbol{\Sigma}^{-1} \mathbf{D}_i$$

$$i = 1, \dots, N : \phi_i \mid \dots \sim \text{IG} \left(\xi_1 + \frac{n}{2}, \xi_2 + \frac{1}{2} (\mathbf{D}_i - \mathbf{M}\boldsymbol{\theta}_i)^\top \boldsymbol{\Sigma}^{-1} (\mathbf{D}_i - \mathbf{M}\boldsymbol{\theta}_i) \right)$$

$$i = 1, \dots, N : \psi_i \mid \dots \sim \text{IG} \left(\xi_3 + \frac{p}{2}, \xi_4 + \frac{1}{2} (\boldsymbol{\theta}_i - \boldsymbol{\nu})^\top (\boldsymbol{\theta}_i - \boldsymbol{\nu}) \right)$$

Full Conditionals

Full conditionals for all parameters have been derived:

$$\boldsymbol{\nu} \mid \dots \sim \mathcal{N}_p(\boldsymbol{\nu}, \Sigma)$$

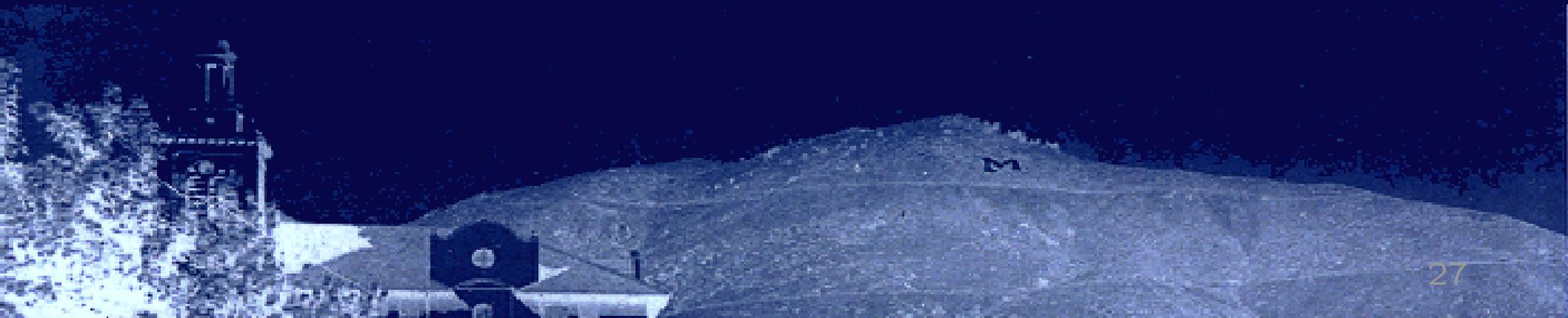
$$i = 1, \dots, N : \boldsymbol{\theta}_i \mid \dots \sim \mathcal{N}_p(\boldsymbol{\theta}_i, \Sigma)$$

$$i = 1, \dots, N : \phi_i \mid \dots \sim \text{IG}\left(\alpha, \beta\right)$$

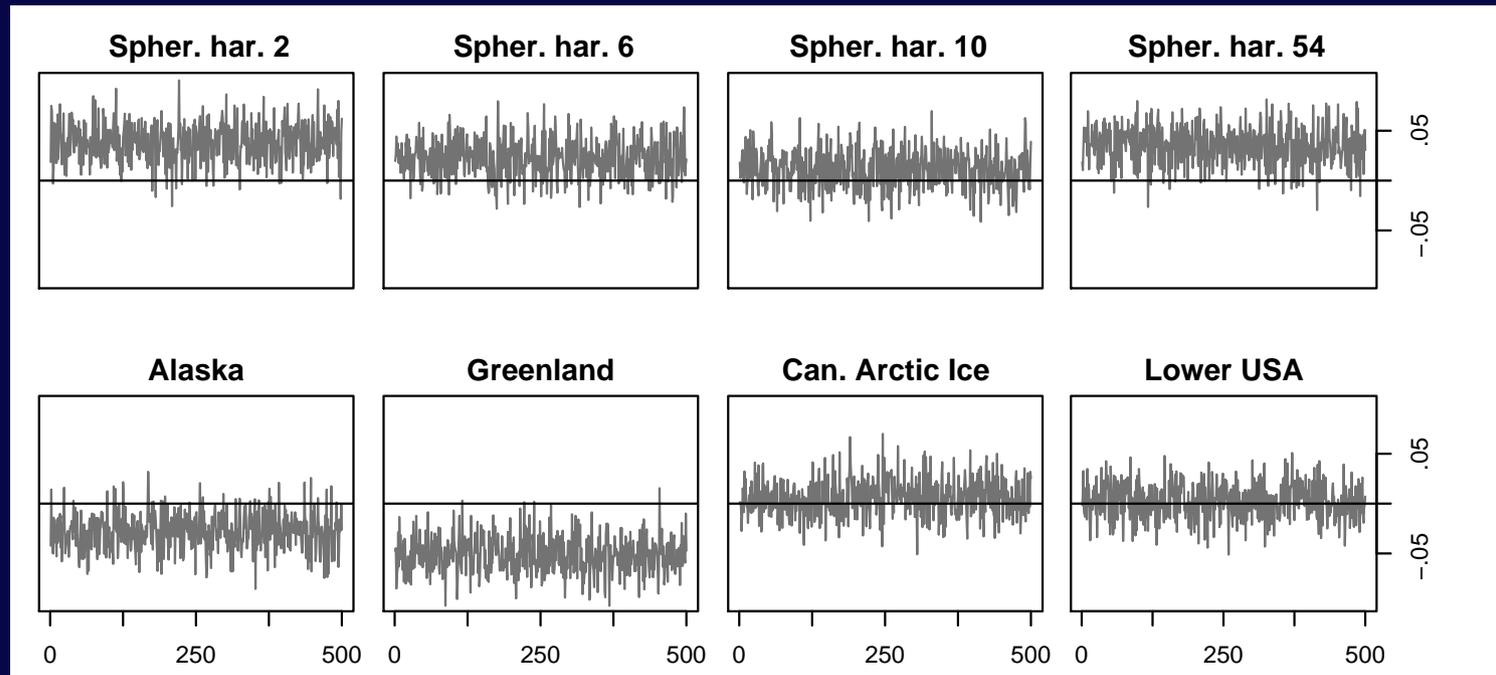
$$i = 1, \dots, N : \psi_i \mid \dots \sim \text{IG}\left(\alpha, \beta\right)$$

Computational Aspects

- Gibbs sampler programmed in R
free software environment for statistical computing and graphics
- Run 20000 iterations
10000 burn-in, keep every 20th, takes a few hours
- Visual/primitive inspection of convergence



Computational Aspects



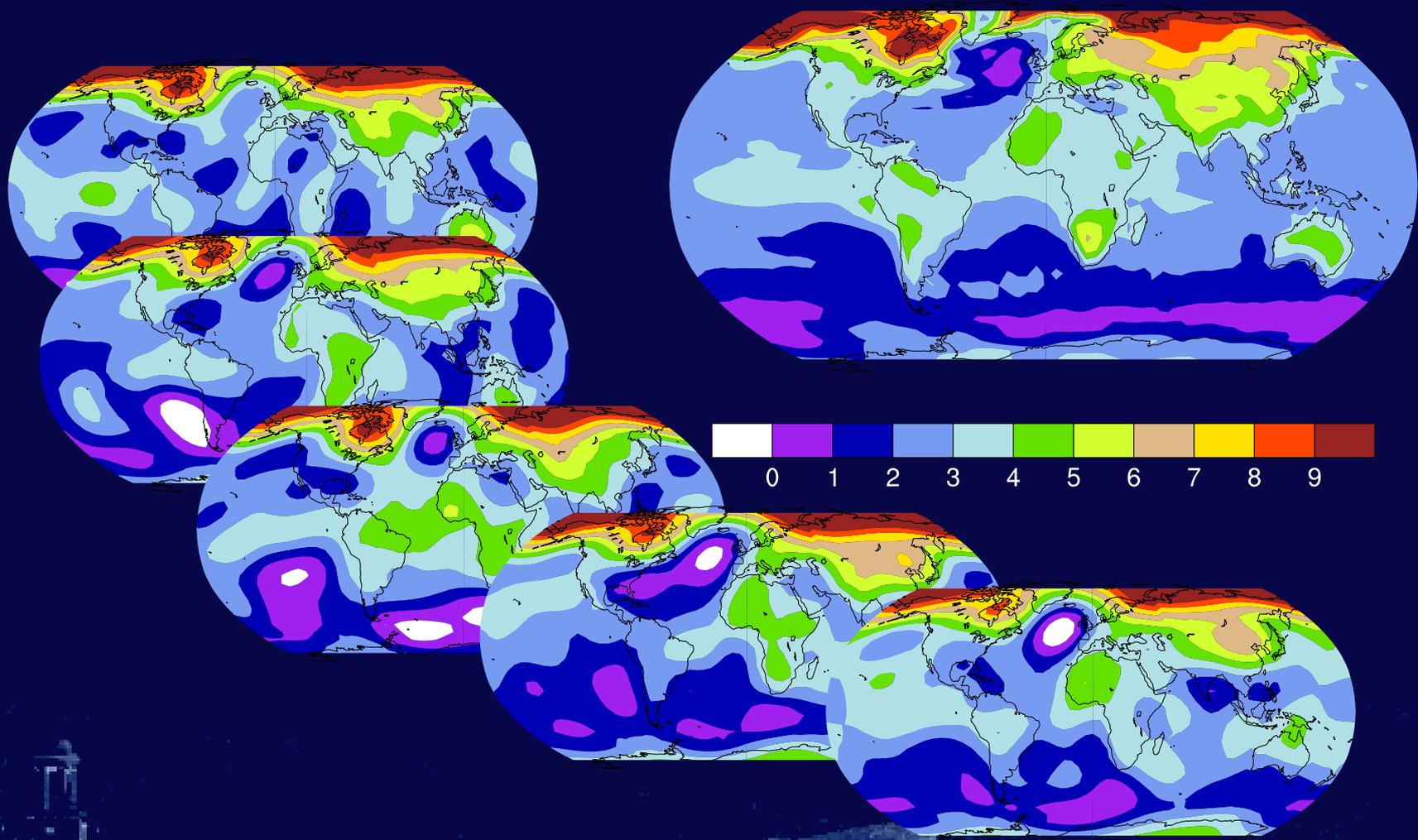
and graphics

- Visual/primitive inspection of convergence



Posterior Draws

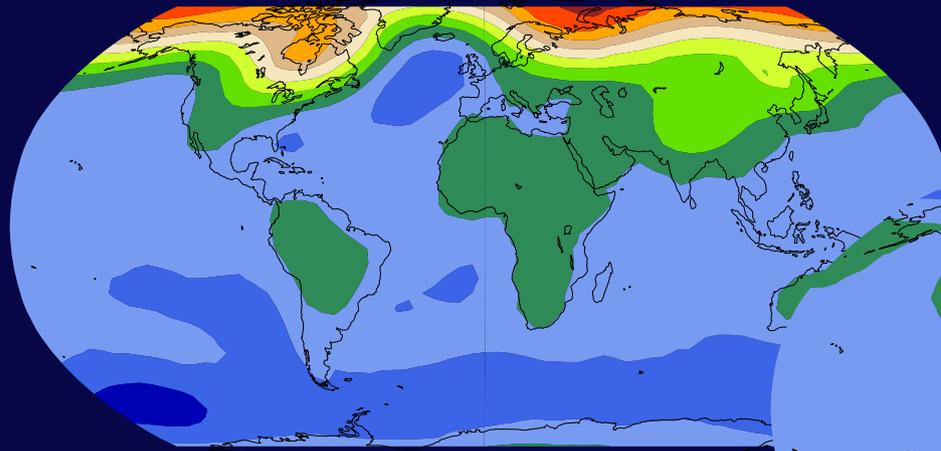
MPI ECHAM5



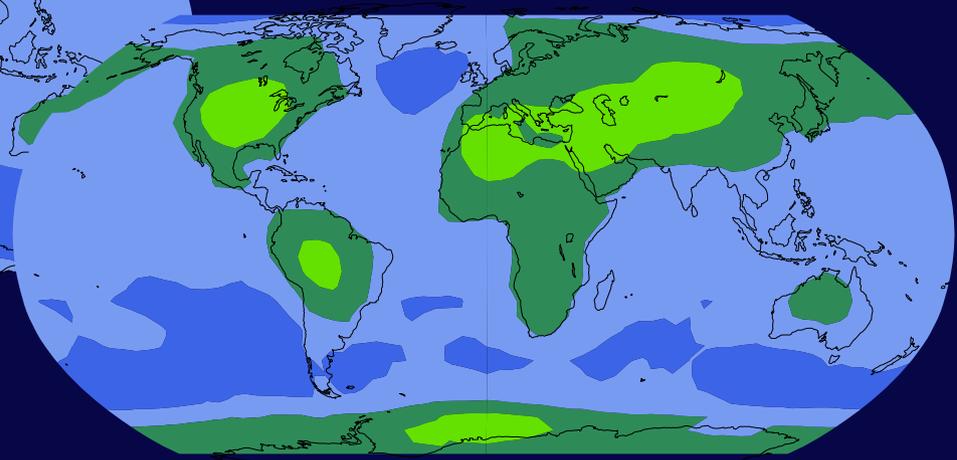
Temperature Change Quantiles

20% quantile of temperature change [°C]
(2080-2100 vs 1980-2000)

DJF



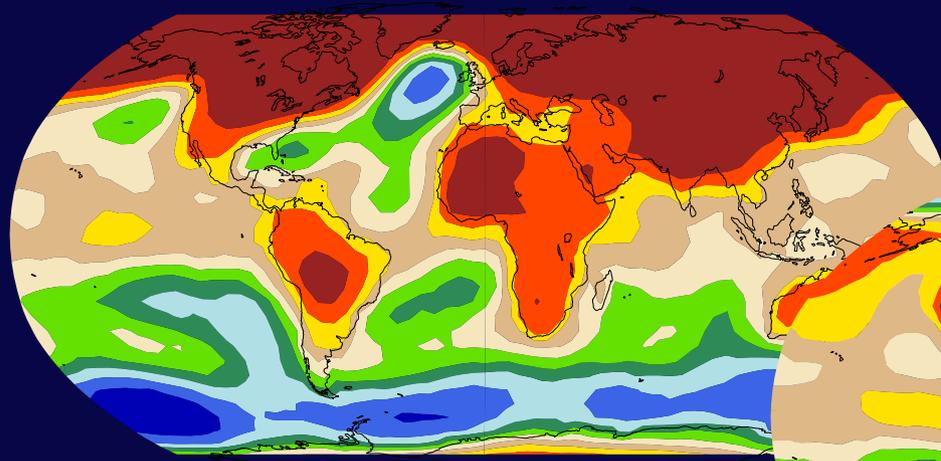
JJA



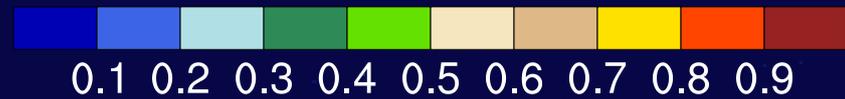
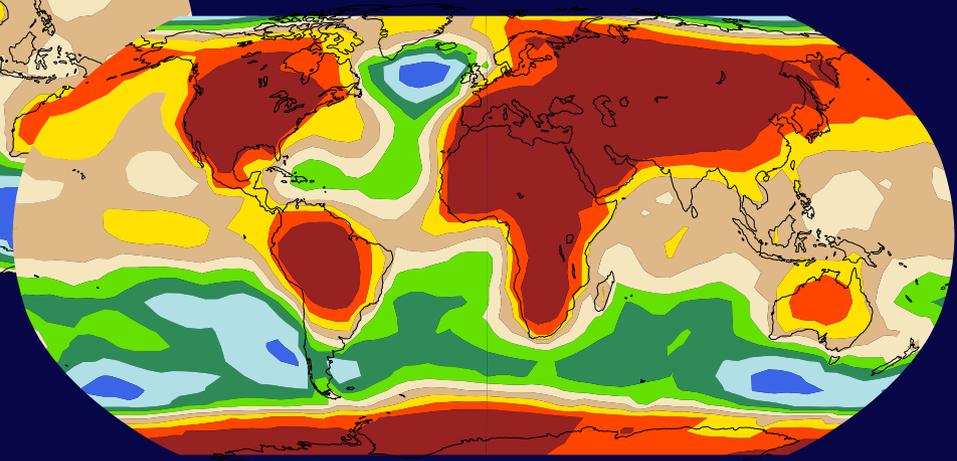
Exceedance Probabilities

Probability of exceeding 2°C temperature change
(2080-2100 vs 1980-2000)

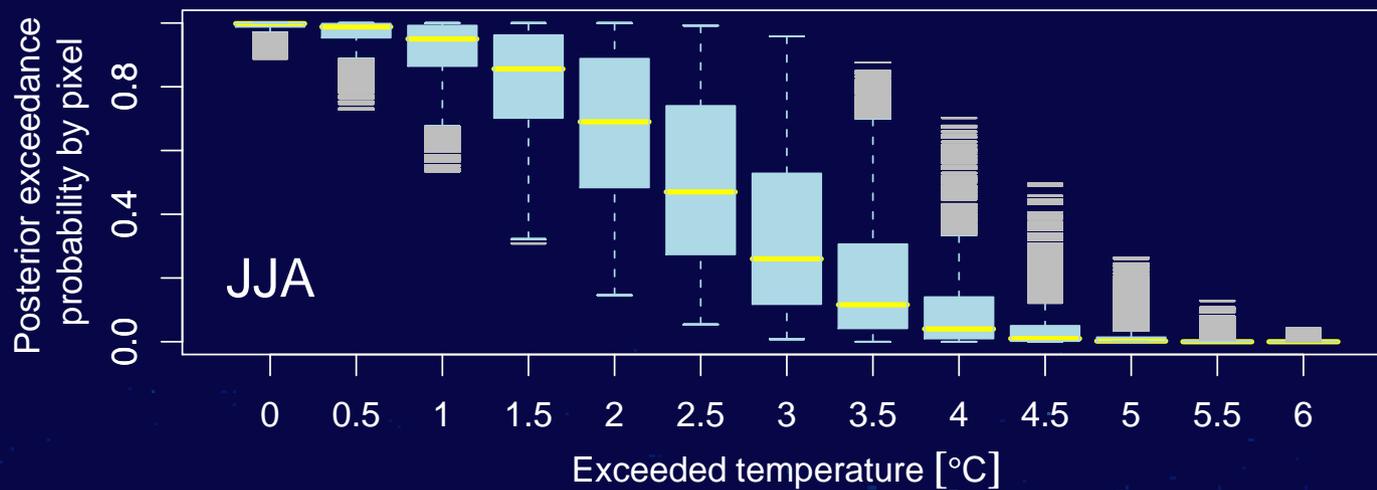
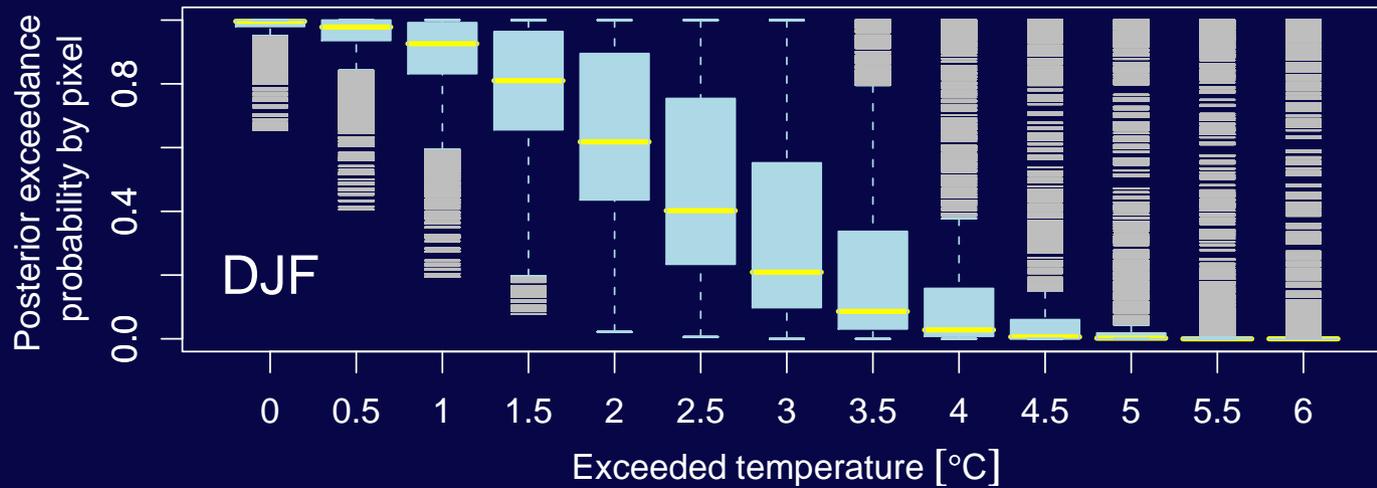
DJF



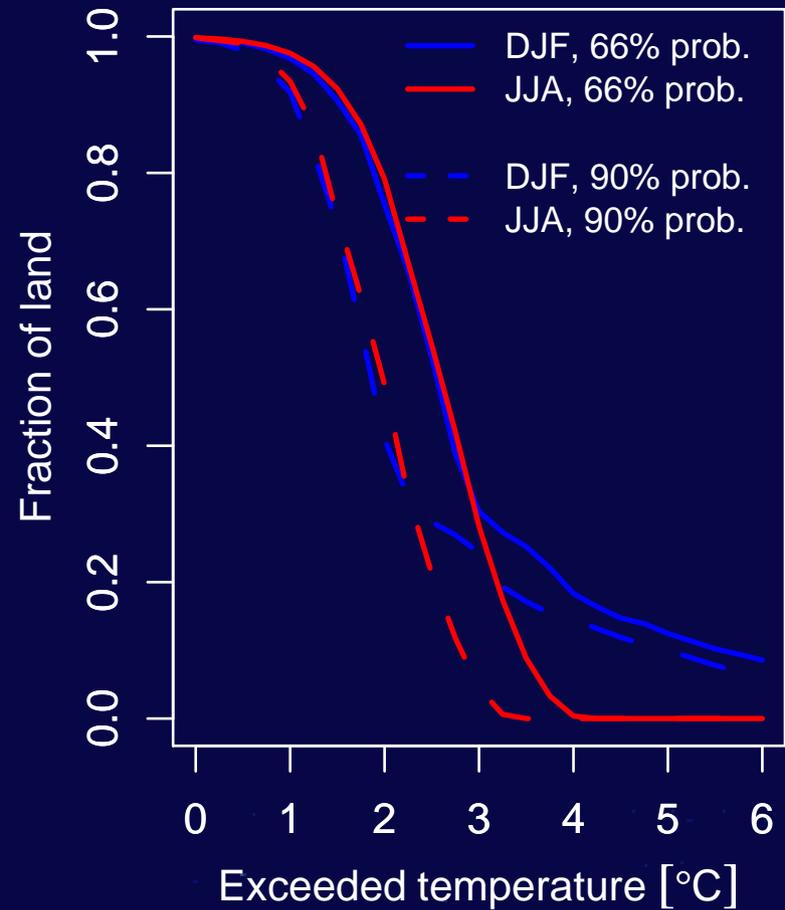
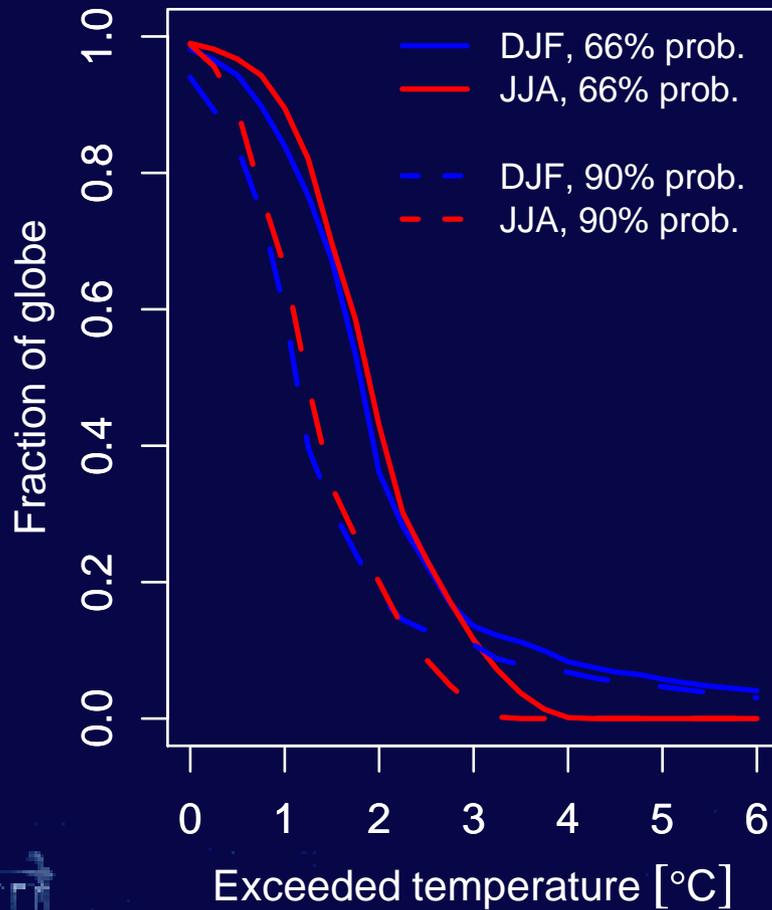
JJA



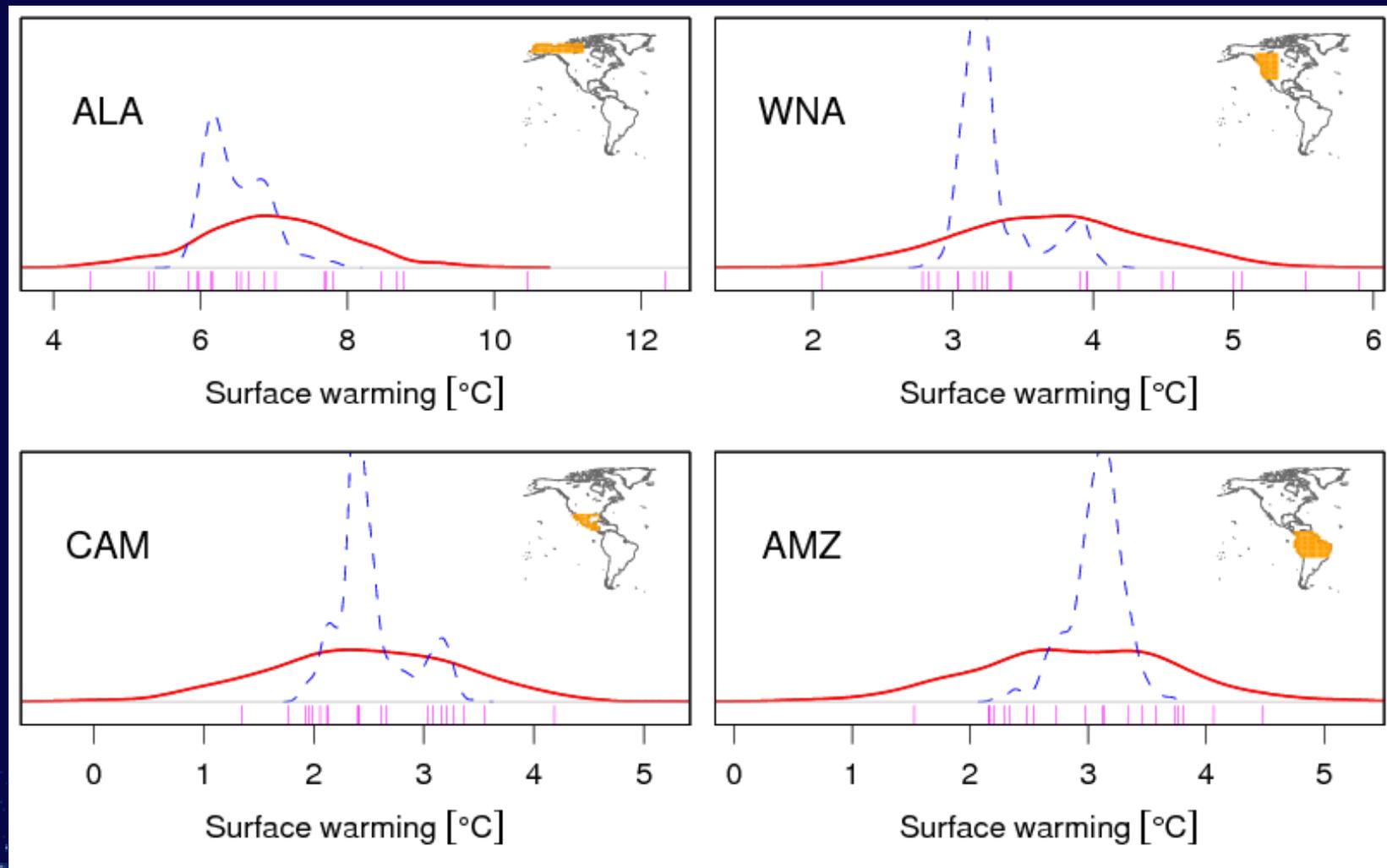
Exceedance Probabilities



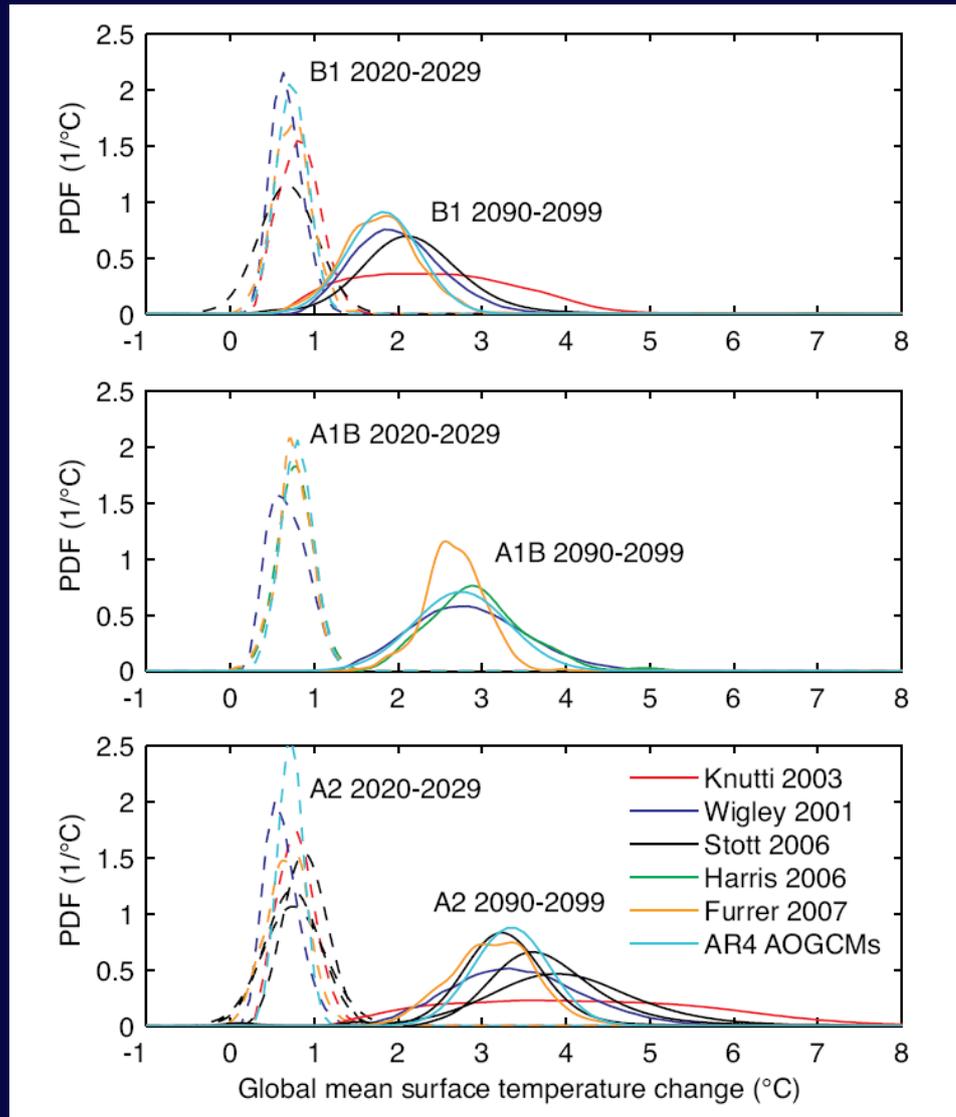
Exceedance Fractions



Regional Assessment



Global Assessment



Source: AR4, IPCC

Model Extensions

- Use “more” data
 - ↪ ensemble runs, model bias and internal variability, model present and future individually, . . .
- Use AOGCM specific weighting
 - ↪ performance, “core” similarities, . . .
- Parameterize covariance matrices
 - ↪ built in range, nonstationarity, . . .
- Building bi-/multivariate models
 - ↪ use temperature for precipitation prediction, . . .
- Address computational complexity
 - ↪ sparsity, GMRF, Metropolis-Hastings steps, . . .

References

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